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2 Warranty and Safety

Limited After-Sales Warranty 2.1

Xi'an ACTIONPOWER Electric Co., Ltd. is responsible for free maintenance of the PRE20XXS series products manufactured and sold within 12 months from the date of delivery for any failure or damage under normal use.

ACTION

During the guarantee period, the Company shall not be liable for free repair for any of the following circumstances, and the Company shall charge according to the repair conditions after repair:

Products not directly sold by our company or agents not officially authorized by our company.

Failure or damage caused by irresistible catastrophes, or failure to use in accordance with the User's Manual or fault of the user, such as improper operation or other disposal.

Disassemble, repair, refit or install accessories without the consent of our company, resulting in failure or damage.

During the warranty period, the user is responsible for transporting the faulty or damaged products to the Company at their own expense, and the Company is responsible for transporting the repaired products to the user (mainland China only) or its designated location (mainland China only).

This "Warranty" excludes all other express or implied warranties.

2.2 Safety



ACTION

Do not make any unauthorized modifications, or install or replace any parts. Please return the product to the Company's maintenance department if maintenance is necessary, to maintain its safety features.

Please refer to the specific warnings or precautions in the user manual to avoid personal injury or product damage.

Safety Rules 2.3

In order to prevent electric shock, it is strictly prohibited to disassemble this product unless it is authorized by the Company.

This product must not be used on any equipment that has safety requirements, including life support systems. SILIS IS

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We disclaim all liability for any direct or indirect financial losses resulting from the use of this product.

Meaning of Safety Signs 2.4

Warning:

Cautionary statement, which indicates conditions and precautions that may endanger the life of the operator.

Caution:

Precautionary statement, which indicates that damage may be caused to the product or to other equipment connected to the product.

2.5 Safety Information

This section contains important information that should be read before attempting to install and start the PRE20XXS family of products and is intended for use by experienced operators. Experienced operators should understand and be familiar with the importance of life safety and other safety issues. This section mainly includes: ACTIONPOW

Safety precautions:

Warning;

Caution:

Installation preparation;

Installation instructions;



Be sure to familiarize yourself with the safety symbols shown on this page. These symbols are used throughout this manual and include important information and related issues affecting the safety of the end user or operator.









| | 一下一直 | SY 是TIPE |
|------------|---|-----------------|
| Ţ | Protective earth identification (equivalent | to "PE" symbol) |
| 0 | Disconnect the power supply | 一個 |
| $_{3\sim}$ | Three-phase AC | V TELEBOWER |
| \sim | AC | ACTION |
| | On (power on) | 三三個 |
| | DC | SK JETIONPOWER |
| \geq | AC and DC | |



CAUTION: When you see this warning symbol, be sure to refer to this manual to familiarize yourself with the nature of potential hazards and measures to avoid them.

2.6 Safety Precautions



4

The following general safety precautions must be observed during all phases of operation, maintenance and repair of this product. Violation with safety standards for design, manufacture, and intended use of the product caused by failure to observe these precautions or specific warnings elsewhere in this manual. Xi'an ACTIONPOWER Electric Co., Ltd. shall not be liable for any failure of the customer to comply with these requirements. ACTIONPOWER

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With a protective grounding terminal, this product is Class I safety equipment. The protective function of this product could be harmed if it is used contrary to the instructions.

ACTION

Warning: Ambient conditions.

This product is only suitable for installation in an indoor environment with pollution level 2, altitude not exceeding 2000m, overvoltage level OVCII and without direct sunlight, dust, flammable and explosive gases and strong magnetic fields. The operating temperature range is $0 \sim 50^{\circ}$ C and the relative humidity is less than 80%.

Note: Before power-on

Confirm that the AC input specifications of the product indicated on the nameplate match the parameters such as voltage and frequency of the available common circuit.

Safety precautions: grounding,

With a protective grounding terminal, this product is Class I safety equipment. In order to reduce the risk of electric shock, the enclosure grounding terminal of this product must be connected to the electrical safety ground. This product must be connected to the AC power supply through a suitably rated three-phase cable (L1-L2-L3-PE) with protective earthing.

Disconnecting the protective (grounding) conductor or protective earthing terminal could result in an electric shock hazard that could be harmful to people.

This product is equipped with line filters to reduce electromagnetic interference and must be properly grounded to minimize the risk of electric shock. Leakage currents greater than 5.0 mApeak may occur during operation at line TIONPOWER







ACTION





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voltages or frequencies that are higher than those listed on the model plate.

Warning: Avoid operating in an explosive environment.

Do not operate this product in flammable or explosive atmospheres.

WARNING: Disconnect the device.

IDNPOWER

A disconnecting device (external switch or circuit breaker) must be a part of the installation for the AC input connection. The disconnecting device must be located in an easily accessible position and must be marked as the disconnecting device for this product. All conductors must be simultaneously disconnected by the disconnecting device.

ACTION

It is necessary to provide external overcurrent protection devices (fuses, circuit breakers, and so on).

The overcurrent protection device's breaking capacity must be appropriate for the rated current of the device.

On the supply side of the overcurrent protective device, there must be at least minimal insulation between supply connection components with opposing polarities.

Protective conductors cannot have overcurrent protective devices installed in them. The neutral conductor of multi-phase equipment must be installed in accordance with GB19517-2009, without fuses or single-pole circuit breakers.

Before touching the equipment or any terminal block or pin, after cutting off the mains power, make sure to check any residual DC voltage from each line terminal to the grounding stud as shown in Figure 1 using the DC position of the digital multimeter (DMM) to detect the safety voltages (< 5Vdc).

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IONPOWER

Figure 1 Schematic Diagram of Residual Voltage Check of AC Input Filter After Disconnecting AC Power

ACTION

WARNING: Do not replace parts or modify.

Due to the risk of introducing additional hazards, do not install replacement parts or make any unauthorized modifications to this product. This product should be mailed back to the Sales Service Department of Xi'an ACTIONPOWER Electric Co., Ltd. for service and repair to ensure that this product is properly maintained.

Damaged or defective products shall be taken out of service and affixed with a similar "Faulty/To be repaired" sign to prevent accidental operation until they are repaired by professional service personnel. ACTIONPOWER

NOTE: Instrument position.

Do not place the instrument in any position that prevents easy access to the power disconnecting means or in any manner that makes it difficult to operate the power disconnecting means.



Note: Please keep the product surface clean and dry.





Note: Do not place heavy objects on the product shell.

Caution: Avoid damage to the machine due to severe impact or improper handling.

Note: Rear, front and side plates' vents should not be blocked.

WARNING: To prevent fire, only fuses of the specification specified for this product are permitted.

Caution: Maintain cleanliness.

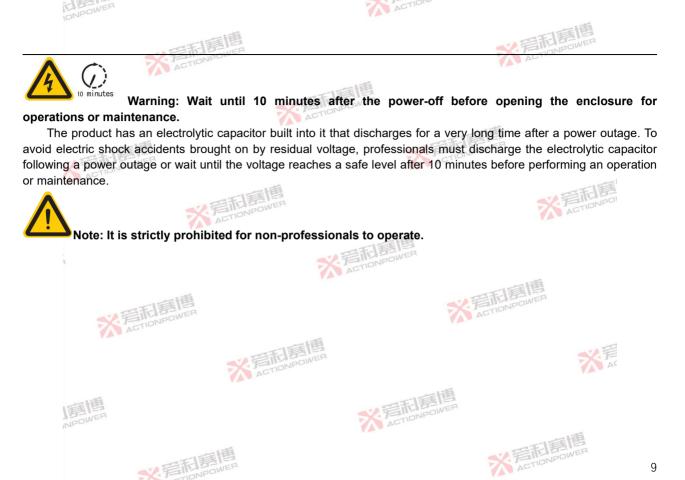
Electric shock could occur if this product were to be maintained and cleaned while it live. Do not directly spray the detergent on the soft cloth; rather, dampen it with water and mild detergent. Avoid using chemicals or detergents that contain abrasive substances such as benzene, toluene, xylene and acetone.

Non-professionals should not repair and maintain this product, otherwise it will cause personal injury or product damage.

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ACTION

This chapter mainly describes the general operating characteristics of the PRE20XXS series bidirectional AC programmable power supplies. ACTION

General Description 3.1

IONPOWER

PRE20XXS series bidirectional AC programmable power supply leads the development direction of a new generation of AC power supply. It has extremely high power density and can achieve rated output power of 20kVA in 3U volume. The whole system is equipped with matrix parallel function, and the parallel expansion can be up to 200kVA to provide greater output power to meet the test requirements. The independent high-precision measurement system has good industry load adaptability and raises the output index to a new height, making the application test more accurate and convenient.

The PRE20XXS series products have four-quadrant working capability, which can meet the general grid simulation regulation test. The unique RLC mode can meet the grid adaptability, island and off-grid operation test of all green energy-related industries, such as PV grid-connected inverter, energy storage system ESS/PCS, microgrid, on-board charger OBC/BOBC, uninterruptible power supply UPS and other products.

Small signal bandwidth up to 10kHz, analog output capability, very low latency and optimization specifically for hardware-in-the-loop simulation (PHIL) capabilities.

The PRE20XXS series products provide accurate, stable, clean AC or DC power, either by operating the front panel display or by remote operation using LAN, USB, analog interfaces for standard testing, automatic testing and more functions.

PRE20XXS series products have built-in five programming functions of List, Wave, Step, Pulse and Advanced, and two harmonic parameter setting functions of harmonic and interharmonic, and support steady-state output functions such as sine wave, pulse wave, triangular wave, leading edge half wave, trailing edge half wave, 30 built-in harmonics and custom wave. It also has waveform point editing function and supports import/export of external USB storage ACTIONPOWER

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devices.

3.2 **Product Features**

The following features apply to all PRE20XXS series products.

Source/load integration, full power feedback, full power four-quadrant load;

Small signal bandwidth up to 10*kHz*, large signal bandwidth 2000*Hz*, optimized for hardware-in-the-loop simulation (PHIL) functions;

High power density 3U up to 20kVA, standard 19-inch cabinet capacity configurable200kVA;

3 phases can be linked, independent and parallel, with $0 - 450V_{@L-N}$ output capacity;

High precision output and measurement, $0.01\% \pm 0.05\% F.S$ voltage precision and $0.1\% \pm 0.1\% F.S$ current precision;

Frequency range of output fundamental wave0.01 - 200Hz;

Harmonic expansion to 100 times@40Hz - 70Hz;

Constant power curve output, no need to set high and low voltage gears;

Up to 12 RLC network topology simulation functions;

USB and Ethernet interfaces compatible with SCPI and Modbus communication protocols;

Based on the advanced power conversion technology of PRE20XXS series products, when the product output is connected to energy feedback loads, such as motors, inverters, etc., it can work in four-quadrant state without adding a discharge circuit.

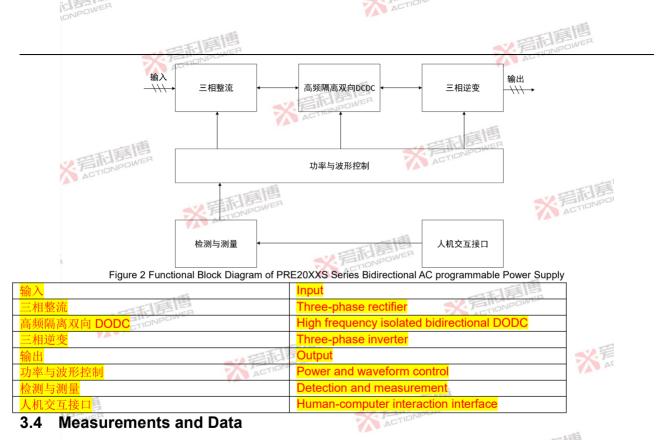
3.3 Function Block Diagram

The PRE20XXS series products use full high frequency devices to raise performance indicators to a whole new height. Figure 2 shows the internal function diagram of the PRE20XXS series products.

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The operation and setting parameters such as voltage, current and frequency of PRE20XXS series products can be K ACTIONPOWER ACTIONP



read and set through the display screen or communication port.

PRE20XXS series products are internally designed with a high precision synchronous measuring system, which has been calibrated at the factory and complies with the specifications. They can be used in general applications without the need for additional instruments. Detailed data content and precision can be found in 4.2.

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3.5 Accessories

Each qualified PRE20XXS series product includes the accessories listed in Table 1. If one or more accessories are found to be incorrect or missing, please contact the manufacturer for after-sales service.





4 TECHNICAL SPECIFICATIONS

The relevant performance indicators in the technical specifications of this chapter are applicable to the ambient temperature of 0~50°C and the altitude shall not exceed 2000m.

4.1 Product model

There are 6 models available for PRE20XXS series products, with a power range of 6*kVA*~20*kVA*. See or detailed product models.

Table 2 Model List of PRE20XS Series Products

| | | | and here | | | | | |
|------------------|-------------------------------|-------------------------|-------------------------------|---|--|------------------------------|------------------------------|----------------|
| Product model | Number of output phases | Rated power (kVA) | Maximum voltage (V_rms) | Maximum three-phase current (A_rms) | Maximum single-phase current (A_rms) | Maximum voltage (V_DC) | Maximum current (A_DC) | Appear ance |
| PRE2006S | Three-pha se | 6 | 450 | 30 | 90 | 636 | 90 | 3U |
| PRE2007S | Three-pha se | 7.5 | 450 | 30 J | NPOWER 90 | 636 | 90 | 3U |
| PRE2009S | Three-pha se | 9 | 450 | 35 | 105 | 636 | 105 | 3U |
| PRE2012S | Three-pha | -12 -12 | 450 | 35 | 105 | ACT 636 | 105 | 3U |
| PRE2015S | Three-pha se | 15 | 450 | 35 | 105 | 636 | 105 | 3U |
| PRE2020S | Three-pha se | 20 | 450 | IBIE 35 | 105 | 636 | 105 | 3U |

4.2 TECHNICAL SPECIFICATIONS

Table 3 briefly lists the data under rated input and resistive load conditions with ambient temperature of 25°C±5°C, which can meet the general selection reference. For other influencing conditions, refer to 4.4-4.13.

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| TABLE 3 | Summary of Technical Specifications |

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|--------------------------------|-------------------------------|--------------------|------------------|--------------------|--------------------|--|--|
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| TABLE 3 Summary of Technical S | Specifications | | | ALTI | 010. | | |
| Product model | PRE2006S PRE2007S | PRE2009S | PRE2012S | PRE2015S | PRE2020S | | |
| Output mode | AC, DC, AC+DC, DC+AC | | | • | | | |
| Operating mode | Bidirectional feedback source | ; | | | | | |
| Number of output phases | Three-phase, single-phase, s | plit-phase | | | | | |
| Maximum power (kVA) | 6 7.5 | 9 | 12 | 15 | 20 | | |
| AC output | | | | | | | |
| Voltage | | | | | | | |
| Range (V_rms) | L-N/0-450, L-L/0-779@0.00 | 1Hz-200Hz | | | | | |
| Setting resolution (V) | 0.01 | | | | | | |
| Precision ① | 0.01%±0.05% F.S | | | | | | |
| Type of waveform | Sine wave, triangular wave, p | oulse wave, clippi | ng, multipulse w | /ave, built-in hai | monic, custom wave | | |
| DC component (mV) (2) | <20 | | <u> </u> | · · | · · · · | | |
| | <0.3%@50Hz/60Hz | | | | | | |
| Voltage distortion ③ | <1%@0.001Hz-200Hz | | | | | | |
| Load adjustment rate | ±0.05% F.S | | | | | | |
| Source Adjustment Rate | ±0.01% F.S@10% Variation | | | | | | |
| Remote compensation | Adaptive | | | | | | |
| Voltage slew rate | AC>3.0V/µs | | | | | | |
| Frequency | | | | | | | |
| Range (Hz) | DC,0.001-200.0 | | | | | | |
| Resolution (Hz) | 0.001 | | | | | | |
| Precision | ±0.01% | | | | | | |
| Phase | | | | | | | |
| Scope | A = 0°, B = 240°, C = 120° (d | efault); programn | nable range 0°~ | 359.9° | | | |
| Precision (5) | ±0.1°@0.001-200Hz | | | | | | |
| Set resolution | ±0.1° | | | | | | |
| Harmonics | | | | | | | |
| Number of times | 100 times@40-70Hz; 25 time | s@70-200Hz; | NPOWEN | | | | |
| Content 6 | 40% | | | | | | |
| Amplitude error | ±5% @ 0.1% of set value or | fundamental valu | e | | | | |
| Phase angle range | 0°-359.9° | | | | | | |
| <u> </u> | | | | A PILO | VPU | | |











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|---------------------------------------|-----------|--|-------------------|------------------|-------------------|-----------------------|
| Current | | | | | | |
| Single-phase effective value (A rms) | 90 | 90 | 105 | 105 | 105 | 105 |
| Single-phase peak value (A peak) | 270 | 270 | 315 | 315 | 315 | 315 |
| Three-phase effective value (A_rms) | 30 | 30 | 35 | 35 | 35 | 35 |
| Three-phase peak value (A_peak) | 90 | 90 | 105 105 | 105 | 105 | 105 |
| Setting resolution (A) | 0.01 | AL | | | | |
| Peak Factor ⑦ | 1-6 | | | | | |
| Precision (8) | 0.1%+0.1 | I%F.S@15-200Hz | Z | | POWER | |
| Transient | | | | | | |
| Programming | | | | | | |
| Mode | List, Wav | e, Step, Pulse, A | dvanced, Harmo | nic, Interharmor | nic, 30 groups of | DST |
| Minimum programming time step | 100µs | , , , , | , | , | | |
| Number of programmed waveforms | 50 | | | | | |
| Synchronization source/trigger source | Internal, | external | | | | |
| Data Source | Edit, Imp | ort, Export | | | | |
| Analog Programming | Effective | Effective value, amplitude, instantaneous value (power amplifier mode) | | | | |
| Standard | | | | | | |
| AC IEC 61000 | 4-11, 4-1 | 3, 4-14, 4-27, 4-2 | 8, 3-2, 3-3, 3-11 | , 3-12 | | |
| DC IEC 61000 | 4-17, 4-2 | 4-17, 4-29 | | | | |
| Internal resistance mode | | | | | | |
| R range (Ω)9 | 0-10 | | | | ACTIONPUT | |
| L range (mH) | 0-2 | | | | - Alle | |
| Set resolution | 0.001 | | | | | |
| Precision | 0.1%+0.2 | 2% F.S. | | | | |
| RLC Load | | | | | | |
| Resistance | | | | | | |
| Range (Ω) | 0.001-10 | 00 | | | | |
| Setting resolution (Ω) | 0.001 | | | 一一一一一一 | | |
| Precision | ±0.1% F. | S. | | ETCLOSWER | | |
| Inductance | | | | | | |
| Range (mH) | 1-5000 | | | | | 1.55 |
| Setting resolution (mH) | 0.001 | | | | | |
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|--------------------------|---------------------------|---------------|
| | 日夏唐 | 义 晋市唐傳 |
| Precision | ±0.1% F.S. | AUTION |
| Capacitance | | |
| Range (µF) | 1-5000 | |
| Setting resolution (µF) | 0.001 | |
| Precision | ±0.1% F.S. | |
| DC output | | |
| Voltage | | |
| Scope (V) | ±636 | TUBOWER |
| Setting resolution (V) | 0.01 | TION |
| Output precision 10 | 0.01%+0.05%F.S. | |
| Output ripple (V_rms)(1) | <0.35@(DC-300kHz) | -15 |
| Load adjustment rate | ±0.05%F.S. | |
| Source Adjustment Rate | ±0.01 F.S.%@10% Variation | ACTIONIC |
| Output swing rate | DC>3.0V/µs | |
| Current | | |
| Scope (A) | 90 90 95 95 | 95 95 |
| Setting resolution (A) | 0.01 | · · |
| Precision | 0.1%+0.1% F.S. | |
| Measurement parameters | | |
| AC voltage | | |
| Range (V_rms) | L-N/0-600 | |
| Resolution (V_rms) | 0.01 | AU |
| Precision ACT | 0.01%+0.05% F.S. | |
| Frequency | | |
| Range (Hz) | 0.001-500 | SA TE |
| Resolution (Hz) | 0.001 CTIONPORT | AL |
| Precision | ±0.01% | |
| AC current | | |
| Scope (A) | 140 | ER |
| Resolution (A) | 0.01 | |
| Precision | 0.1%+0.2% F.S. | - |
| Peak current | | |

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| Scope (A) | 4x rated | |
| Resolution (A) | 0.01 | |
| Precision | ±2% F.S. | |
| Peak factor | | |
| Scope | 1.00-6.00 | |
| Resolution | 0.01 | |
| Precision | ±2.0% F.S. | |
| Active power | | |
| Range (kW) | 20 | |
| Resolution (W) | 1 | |
| Precision (12) | ±0.2% F.S. | |
| Apparent power | | |
| Range (kVA) | 20 | |
| Resolution (VA) | 1 | |
| Precision (12) | ±0.2% F.S. | |
| Power factor | | |
| Scope | -1.00-1.00 | ß |
| Resolution | 0.01 ACTIONED | |
| DC voltage | | |
| Scope (V) | ±1000 | 日本語言 |
| Resolution (V) | 0.01 | SK FIDNPOWER |
| Precision | ±0.1% F.S. | ACTO |
| DC current | | |
| Scope (A) | ±200 | |
| Resolution (A) | 0.01 | |
| Precision | 0.1%+0.2% F.S. | AC |
| Input | | |
| Wiring mode | Three-phase four-wire ABC+PE | 一個 |
| Frequency (Hz) | 47 - 63 | |
| Voltage range (V) 🚯 | 304 - 480 | ONPOWER |
| Current per phase (A_max) | 12 15 18 | 22 30 35 |
| Input peak current (A) | < 1.5x rated | |
| Power factor (14) | > 0.99 | THE DOWER |
| | POWER | ACTIONPOWE |

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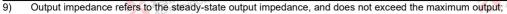
| | 一篇團 | るこの語言 |
|---------------------------|---|----------------------------|
| Efficiency (14) | > 0.91 | ACTIONPOL |
| Interface | | |
| Generic Interface | Type-B, USB, LAN | |
| Multifunctional interface | "Anyport", as defined in the user manual | |
| Environment | | |
| Operating range (°C) | 0-50 | - |
| Storage range (°C) | -20-70 | 国語に |
| Humidity | ≤80% | ELEDWER |
| Dimensions Weight | | |
| Dimensions (W×H×D) | 435×132×680mm(780mm With Breaker) | |
| Weight / | 35kg | |
| Protection | | |
| | Effective value overcurrent-disconnected | ACTIONI |
| | Peak overcurrent disconnected | |
| | Overpower disconnected | |
| Protection | Overcapacity disconnected | |
| | Overvoltage (set 1%-105%) disconnected | |
| | Over-temperature disconnected | |
| | Overvoltage or undervoltage when being connected to the | ne power grid-Disconnected |

Notes:

- 1) F.S. in the parameter table related to AC output voltage refers to the maximum AC voltage of 450V;
- 2) The DC component is set as output voltage 220VAC and frequency 50Hz, tested under no load;
- When the output frequency is ≤200Hz, the maximum distortion is tested under 250VAC and the pure resistive load to the rated output power;
- 4) When the resolution is 0.001 or 0.01% of the current setting value, whichever is greater;
- 5) The phase precision is set to 220V for the three-phase output voltage, and the three-phase phase is set to the default phase. The test is conducted under no load;
- 6) 40% of the amplitude of 300V_rms refers to the total content of superimposed harmonics;
- 7) Peak factor refers to the ratio of peak current to effective value. The typical value of standard sine wave is 1.414, and the maximum allowable value is 6, but the peak value does not exceed the maximum current value of a single machine, and does not refer to the peak factor under rated values;

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8) F.S. in the parameter table related to AC current refers to the maximum current of the corresponding model;



- 10) In the parameters table, the FS related to DC output voltage refers to the maximum DC voltage of 636V;
- 11) The output ripple voltage is 500V for the output DC voltage, and the output is under no load. The oscilloscope is AC coupled with 20MHz bandwidth limit;

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- 12) The FS of active power and apparent power precision refers to the maximum measured power value of the machine of the corresponding model;
- 13) The input voltage 304-323V needs to be derated by 60%, and the input voltage 323-342V needs to be derated by 80%. See Figure 5 for detailed derating requirements;
- 14) Power factor and efficiency index are tested under the three-phase input voltage of 380V, the set output of 220V, pure resistive load to the rated output power.

4.3 Overall dimensions

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The PRE20XXS series products are standard 19-inch chassis construction. See Figure 3 for overall dimensions. It can be applied to standard cabinet systems or desktops.



Figure 3 Overall Dimensions of PRE20XXS Series Bidirectional AC programmable Power Supply

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4.4 Output voltage vs. current curve

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Conventional AC supply voltage output ranges have two gears to provide either high voltage or high current. The PRE20XXS series is designed with a unique single voltage range operating along a constant power curve. The constant output power curve is shown in Figure 4. Taking PRE2020S as an example, the rated power can be output at L-N/190 *Vac*@35 *A*, and this operating state range can be extended to L-N/450 *Vac*@15 *A* output without interruption. When other power supplies switch in the high and low voltage range, it will cause output disconnection and EUT power failure, which is difficult to test AC products with wide voltage input.

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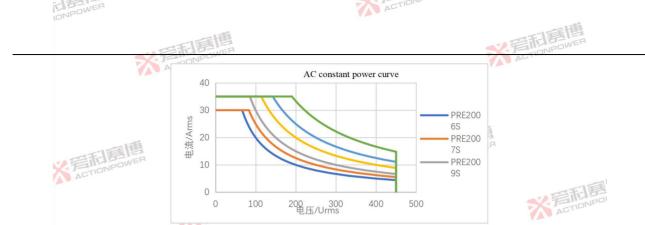


Figure 4 Output Voltage and Output Current Curve of PRE20XXS Series Products in AC Constant Power Mode

| 交流恒功率曲线 | AC constant power curve |
|----------------------|-------------------------|
| 电流/Arms | Current/Armson POWE |
| <mark>电压/Urms</mark> | Voltage/Urms |

Notes:

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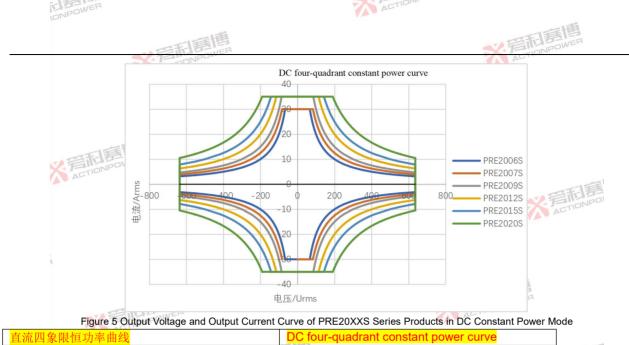
The output voltage range is determined by a number of constraints, for example, the output voltage and output power are affected to varying degrees at different output frequencies, as detailed in Section 4.4-4.8.

This feature also applies to the DC output mode. General AC programmable power supply, its output current will be 1/2 of the AC effective value when outputting DC mode. The PRE20XXS series products benefit from advanced power conversion technology. When DC mode output is selected, the average value of the maximum output current is equal to the AC effective value, and it can operate in a four-guadrant state. Figure 5 shows the four-guadrant voltage-current CENTIONPOWER relationship in DC mode.

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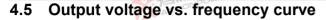
| 直流四象限恒功率曲线 | | DC four-quadrant constant power curve | |
|----------------------|--------|---------------------------------------|----|
| <mark>电流/Arms</mark> | T | Current/Arms | 公元 |
| <mark>电压/Urms</mark> | ACTION | Voltage/Urms | AC |

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The PRE20XXS series products can provide up to 3 independent outputs in DC output mode. Positive, ground and negative three-wire DC output can be achieved by simple connection, e.g. producing ±270V output for aviation test systems. Fully adaptable to 100% unbalanced loads. One output can also be realized in parallel to provide 3 times the current.







The maximum output range of PRE20XXS series products can reach L-N/450 Vac and L-L/0-779 Vac at 40Hz-70Hz, which can meet the test requirements of 660 and 690 systems.

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The maximum output frequency of the PRE20XXS series products is 200Hz, and full power output is available in the full frequency range. The voltage, frequency and output power curves of the PRE20XXS series products are shown in Figure 6 to Figure 11.











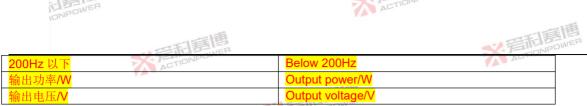


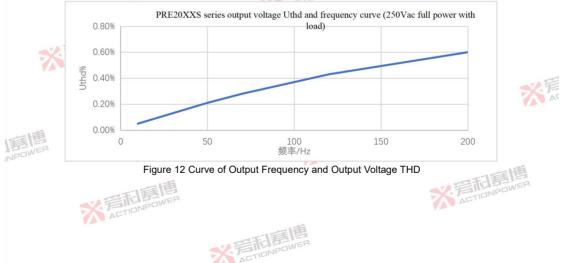
Figure 11 Curve of Single-phase Output Voltage and Output Power in PRE2020S Three-phase Mode

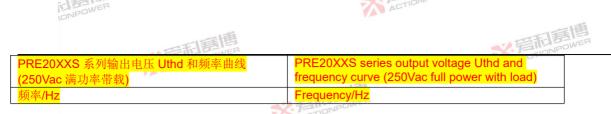
4.6 Output voltage THD and power

At steady-state output, the change of resistive load power will affect the THD index of output voltage. It is shown that PRE20XXS series products have good THD at light load. With the increase of load power, the THD value will increase, but it will not exceed the nominal value in the specification table.

4.7 Output voltage THD versus frequency curve

PRE20XXS series products have good THD characteristics in the full frequency range, which can meet most test requirements. Affected by limiting parameters, the output THD value will increase with the increase of output frequency. The output curve is shown in Figure 12.





4.8 Output voltage precision and frequency

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PRE20XXS series products adopt high-speed and high-precision asynchronous sampling technology, which can maintain high voltage precision in a large output range. When the output voltage is greater than 10V, the output voltage precision is less than the values indicated in the specification table.

4.9 Relationship curve between single harmonic content and superposition

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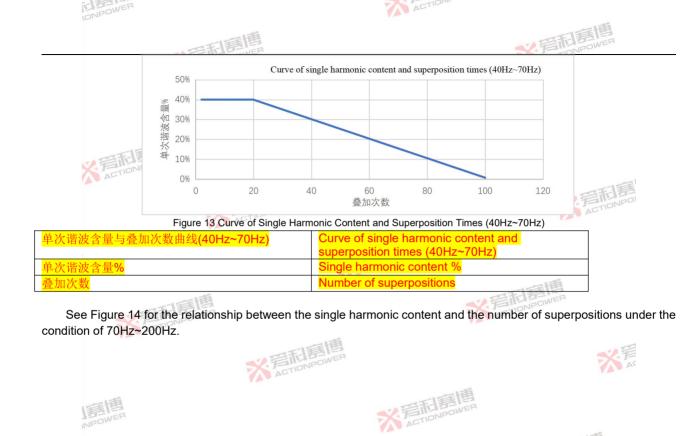
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number

The PRE20XXS series products have a wide harmonic generation capability. The harmonic frequency can reach 100 times at the fundamental frequency of 40Hz~70Hz, and the harmonic frequency can reach 25 times at 200Hz. See Figure 13 for the relationship between the single harmonic content and the number of superpositions under the conditions of 40Hz-70Hz.

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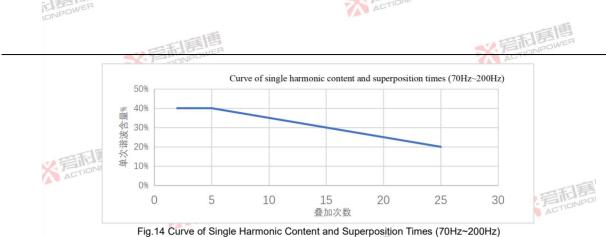


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| 单次谐波含量与叠加次数曲线(70Hz~200Hz) | Curve of single harmonic content and superposition times (70Hz~200Hz) | | | |
|---|---|--|--|--|
| 单次谐波含量% | Single harmonic content % | | | |
| 叠加次数 | Number of superpositions | | | |
| 4.10 Input voltage versus output power derating curve | | | | |

4.10 Input voltage versus output power derating curve

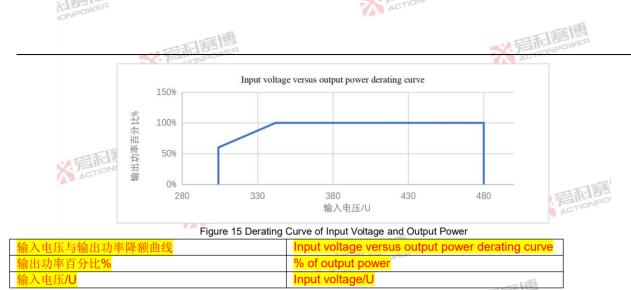
The PRE20XXS series adopts an advanced power conversion topology, which broadens the input voltage range to L-L/(304-480) to meet more demanding environmental requirements. Vac Vac However, when the input voltage is low, A the output power is derated, and the derating curve is shown in Figure 15.





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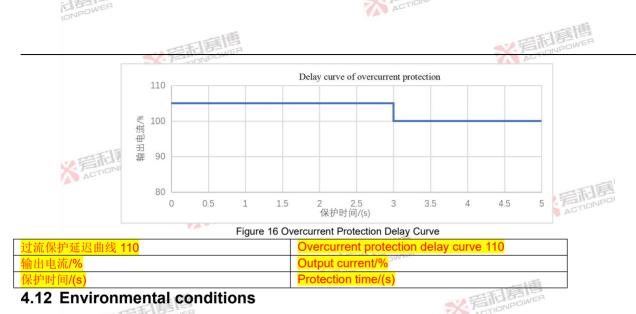


4.11 Output overcurrent protection delay curve

PRE20XXS series products are equipped with a relatively complete protection system, especially for various protections of loads, which can be adjusted by users as required, but the maximum limit is reserved for each item. In order to effectively prevent the misoperation of the protection device when the PRE20XXS series products are connected with impact load, the overcurrent protection delay time can be adjusted in a wide range, and the maximum setting area is shown in Figure 16. See Section 8.8 for setting operations.



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4.12 Environmental conditions

In order to ensure the good performance of PRE20XXS series products and guarantee its working life, the use environment shall not exceed the following limiting conditions. The environmental conditions are shown in Table 4. Table 4 Environmental Conditions of PRE20XS Series Products

| Working environment | TIONPU | | A | <i>,</i> C |
|-----------------------|---|------------|-------------|------------|
| Cooling mode | Intelligent speed regulating fan co | oling | | |
| Audio noise | Standard: 55dB | 一道 | | |
| Audio hoise | Full power: 70dB | 三王是言 | | |
| Operating temperature | 0℃-50℃ | STIONPOWER | | |
| Storage temperature | -20℃-70℃ | | | |
| Humidity | ≤80%, no condensation | | 三百萬四 | |
| | 2.言形意图 A.言形 B. | | ACTIONPOWER | 35 |

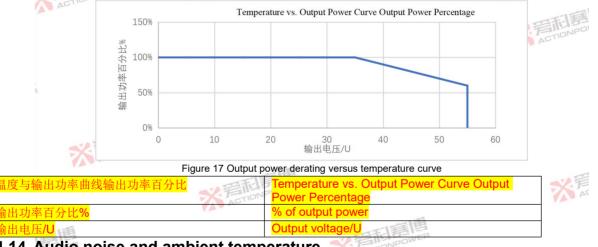
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|---------------------|--------------------------|---------------|---|
| | 一時度傳 | 秋 晋和唐博 | |
| Working environment | AGTIONPOWE | ADTIDU | _ |
| Altitude | ⁷ Up to 2000m | | |

4.13 Output derating and ambient temperature curve

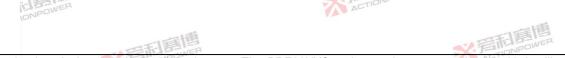
General electronic product development laboratories or production lines can ensure a good temperature environment, and PRE20XXS series products can ensure good performance under these environmental conditions. When the ambient temperature rises, the output power of the PRE20XXS series products will decrease until the overtemperature protection. The output power derating and temperature curves are shown in Figure 17.



4.14 Audio noise and ambient temperature

The PRE20XXS series products will generate audio noise of fan noise and fundamental noise when they work. Only ACTIONPOWE K ACTIONPOWER

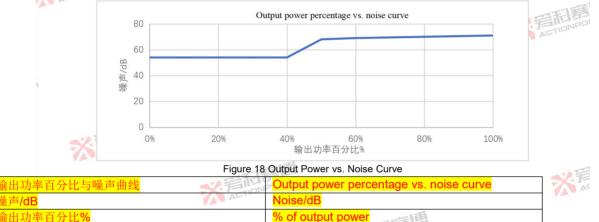




fan noise is calculated during audio noise test. The PRE20XXS series products are equipped with intelligent speed regulating fans, which can effectively reduce the audio noise at low ambient temperatures.

4.15 Audio noise versus output power curve

The PRE20XXS series products will generate audio noise of fan noise and fundamental noise when they work. Only fan noise is calculated during audio noise test. The PRE20XXS series products are equipped with intelligent speed regulating fan, which can effectively reduce the audio noise at low output power. As the output power increases, the fan noise also increases, and the relationship curve between the two is shown in Figure 18.



4.16 Audio noise and output frequency

PRE20XXS series products can output fundamental waves of 200Hz and harmonics of 100 times @40Hz-70Hz ACTIONPOWER

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and 25 times @200Hz. When working under these conditions, the power supply will produce audio noise that can be felt by human ears. Due to individual differences, different sensations will be felt under the same conditions. It is recommended that sensitive people take protective measures to protect their hearing.

4.17 Safety regulations and standards

| Standards to be follow | ed | |
|----------------------------------|--|------------|
| Safety regulations and standards | IEC 61010-1;2010 (Edition 3) | ACTIONPOWE |
| EMC Limits | EN 55011:2009+A1:2010 | |
| EMC withstand | IEC 61000-4-2, -3, -4, -5, -6, -8, -11 | 三王王 |
| Product Category | IEC61326-1:2010 | NPDI |
| | 5 Unnacking and Installa | tion |

5 Unpacking and Installation

Inspection 5.1

Please carefully check the completeness of the packaging before unpacking. If there is any abnormality or you think it may cause damage to the product, please contact Xi'an ACTIONPOWER Electric Co., Ltd. for the after-sales service immediately.

After unpacking, please carefully check the appearance of the product and the quantity of accessories according to the packing list. If there is any abnormality, please contact Xi'an ACTIONPOWER Electric Co., Ltd. for the after-sales service immediately.

All PRE20XXS Series models require a three-phase AC input and are equipped with a pluggable terminal block.

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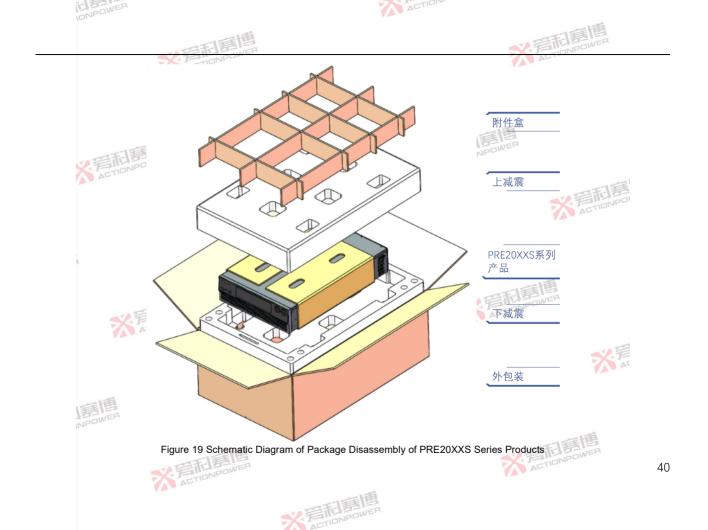






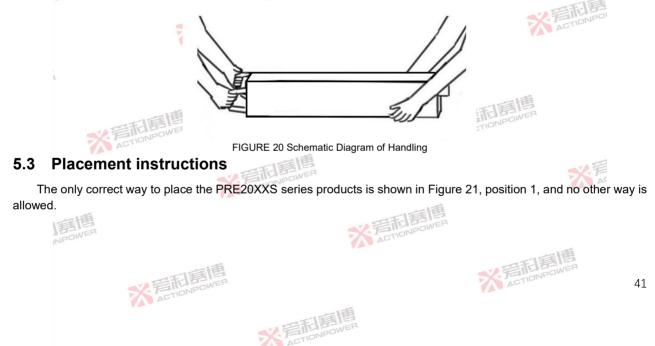
The packaging of PRE20XXS series products is shown in Figure 19. According to the safety regulations, the weight of this series of products is more than 18kg (about 35kg). Before unpacking, the package needs to be placed on a suitable flat surface. After unpacking, two people are required to take the product out of the package. One person is required to lift the long side of the package and place it in a suitable position. The position should support the weight of the product.

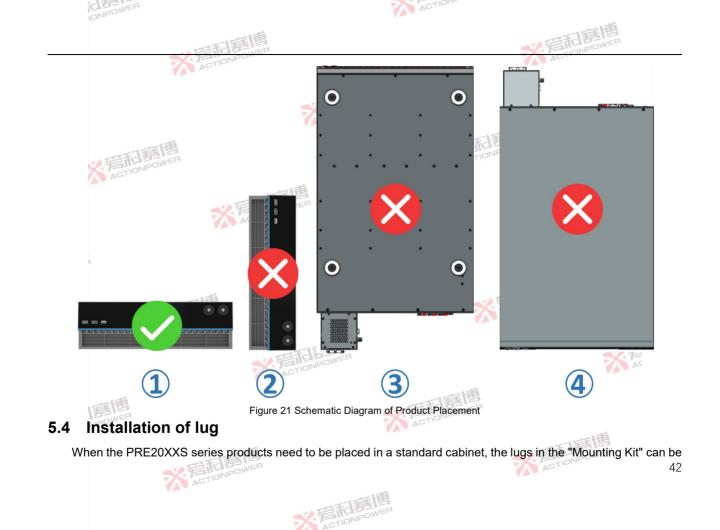




| INPOWER | ACTION | |
|---------------|--------------------------|---|
| 一一一一 | * 言和書傳 | 2 |
| 附件盒 | Accessory box | |
| 上减震 | Upper shock absorber | |
| PRE20XXS 系列产品 | PRE20XXS series products | |
| 下减震 | Lower shock absorber | |
| 外包装 | Outer packaging | |

During laboratory use, two people are required to lift or handle the product if it is necessary to move it. Do not attempt to lift alone or use the two handles on the front panel to lift the product alone. See Figure 20 for the schematic diagram of standardized handling.



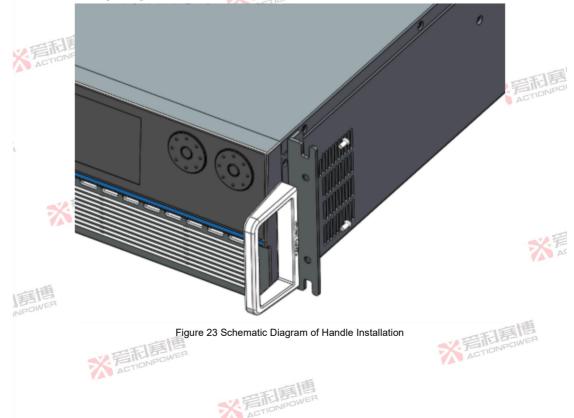






5.5 Installation of handle

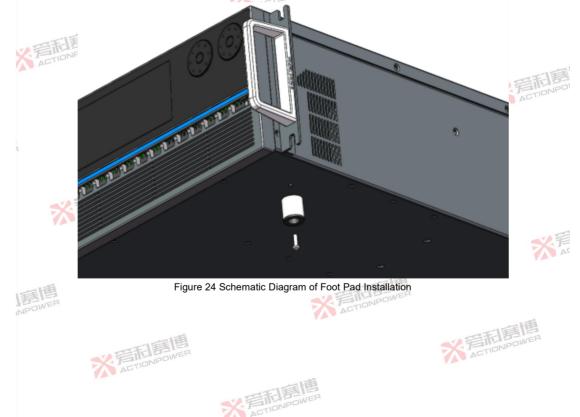
If the PRE20XXS series products need to be pushed and pulled in the cabinet, the handle in the "Installation Kit" MER can be installed according to Figure 23. -1





5.6 Mat Installation

The PRE20XXS series products have been installed with foot mats by default. If you need to raise the product for use, you can replace the high foot mat in the "Mounting Kit" as shown in Figure 24.



5.7 Check AC input

The PRE20XXS series products support a wide voltage and frequency range. Before connecting an AC power supply to the PRE20XXS product, you must check the type label on the device to verify that its AC input configuration matches the local grid. If the AC input voltage, phase and frequency do not match, do not connect a power supply to this product.

ACTION

5.8 AC input connection



The product AC input connection must include a disconnecting device (external switch or circuit breaker). As part of the installation, the disconnecting means must be in the proper position to be reached and must be marked as the disconnecting means of the product. All conductors must be simultaneously disconnected by the disconnecting device.

It is necessary to provide external overcurrent protection devices (fuses, circuit breakers, and so on).

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The overcurrent protection device's breaking capacity must be appropriate for the rated current of the device.

On the supply side of the overcurrent protective device, there must be at least minimal insulation between supply connection components with opposing polarities.

Protective conductors cannot have overcurrent protective devices installed in them. The neutral line of multiphase products shall not be equipped with fuses or single-pole circuit breakers, and shall be installed in accordance with the requirements of GB19517-2009. For each model of PRE20XXS series product, please select the corresponding cable according to Table 5.

Table 5 AC Input Wire Diameter/Wire Gauge



| IONPO | WER AL. | | | | |
|---------------|----------------------|--------------------------------|-----------------------------|--|--|
| | | 和夏博 | | * 言詞 | 美国 POWER |
| Product model | Rated power (kVA) | Rated input voltage (V_rms) | Rated input current (A_rms) | Recommended current distribution current (A_rms) | Recommended wire diameter (mm^2) |
| PRE2006S | 6 | 380 | 12 B | 30 | 4 |
| PRE2007S | 7.5 | 380 | C15ONPO | 30 | 4 |
| PRE2009S | 9 | 380 | 18 | 30 | 4 |
| PRE2012S | 12 | 380 | 22 | 30 | 4 |
| PRE2015S | 15 | 380 | 30 | 50 ONPOWER | 6 |
| PRE2020S | 20 DOWER | 380 | 35 | 50 | 6 |

The AC input connection must be on the AC input connector. The phase of the AC input is marked on the rear panel and requires a four-wire power connection (L1, L2, L3 and ground). The PRE20XXS series products adapt to the phase of AC input voltage. Unless there is a special need, it is not necessary to distinguish the three-phase phase correspondence. See Figure 25 for the wiring diagram.

Note: When installing the input connector, tighten the screws.





This product must be earthed through the AC input.

A well-grounded cable must always be used.

Grounding of electrical systems in accordance with applicable national standards must be observed.

The grounding terminal is the screw-fastened port in the lower right corner of the AC input connector, see Figure 25.

Load connection 5.9



Hazardous output: The product output is at a hazardous voltage level. The output is electrically isolated from the AC input power supply, so the output must always be considered hazardous. In all cases, when the AC input is connected to the product, the operator must disconnect the input of the PRE20XXS series before connecting or disconnecting the output connector.

All products can be configured for single-phase or three-phase output. The external voltage detection connector maintains the three-phase connection regardless of single-phase or three-phase operation. With the system





priguration the PPE20VVS series products automatically detect the channel and set it to the appropria

configuration, the PRE20XXS series products automatically detect the channel and set it to the appropriate configuration.

5.9.1 Output wiring and recommended wire diameter

The connection of the output terminals of the PRE20XXS series products to the load shall be made using the mating output connector provided. The connector is safe, the contact capacity is matched with the power output and must be used when connecting the load line.

Note: When installing the output connector, tighten the screws.

The load output cable has a certain derating relationship with the current size. For 40Hz-70Hz, it is recommended to select the corresponding wire diameter/wire gauge by referring to Table 6. The insulation withstand voltage rating of the load cable shall also be considered. Due to the skin effect, the same wire loss will increase with the increase of the output frequency. If the frequency exceeds 120Hz, it is recommended to use the output wire with reference to the standard derating.

| | | J O i | | | |
|---------------|-------------|----------------------|----------------------|----------------------|------------------|
| Product model | Rated power | Rated output voltage | Rated output current | Recommended | Recommended wire |
| | (kVA) | (V_rms) | (A_rms) | distribution current | diameter (mm^2) |
| | | | | (A_rms) | |
| PRE2006S | 6 | 300 | 12 | 30 V BOWER | 4 |
| PRE2007S | 7.5 | 300 | 15 | 30 ACTIDIC | 4 |
| PRE2009S | 9 ACTIONIC | 300 | 18 | 30 | 4 |
| PRE2012S | 12 | 300 | 22 | 50 | 4 |
| PRE2015S | 15 | 300 | 30 | 50 | 6 |
| PRE2020S | 30 | 300 300 | 35 | 50 | 6 |

Table 6 Output Wire Diameter/Wire Gauge@40Hz-70Hz

5.9.2 Three-phase Y-load connection

The three-phase and six-wire output of PRE20XXS series products are independent of each other. When butting Y-shaped load, the connection method is shown in Figure 26. NA, NB, NC are shorted to a neutral point which is the reference point for all phases. The PRE20XXS series products have been designed with an independent detection system, which does not need to be adjusted.

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FIG.26 Schematic Diagram of Y-Load Connection

With the increase of AC output frequency, the load terminal voltage will decrease greatly. To obtain a more accurate voltage at the load port, adjust the remote compensation cable as described in 7.10. 5.9.3 Three-phase Δ -load connection

Three-phase Δ -load connection 5.9.3

The three phase and six-wire output of PRE20XXS series products are independent of each other. When butting Δ-shaped load, the connection method is shown in Figure 27. The PRE20XXS series products have been designed with AC an independent detection system, which does not need to be adjusted.



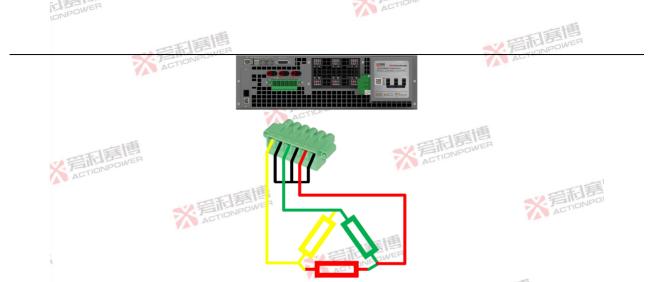


FIG.27 Schematic Diagram of Δ -Shaped Load Connection

5.9.4 Output neutral grounding

Ungrounded power output neutral terminal is equivalent to output midpoint suspension. The power supply allows its output to float relative to earth. The midpoint of the power supply can be earthed through the load. The output midpoint can also be connected to the grounding terminal on the rear panel of the power supply through a wire to obtain a stable grounding potential. The wiring method is shown in Figure 28.



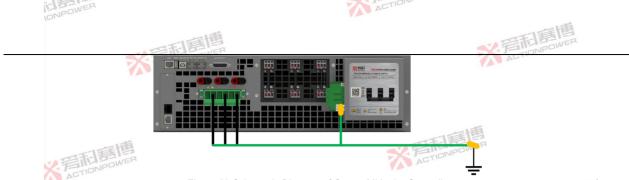


Figure 28 Schematic Diagram of Output Midpoint Grounding

5.9.5 Single phase / DC load connection

Although the internal space of PRE20 is very compact, two sets of devices, parallel switch and load switch, are still designed. The parallel switch is associated with single-phase mode, which can automatically parallel three-phase to A-phase outputs, reducing the operation complexity and solving the problem of protection when forgetting to remove external short-circuit wires. The load switch is associated with the OUT function, realizing the output and load isolation. making the R&D test and production line ATE conversion of the test object safer.



The three-phase and six-wire output of the PRE20XXS series products are independent of each other. Either one of the phases can be used, or the three phases can be connected in parallel to form a single phase/DC to extend the output capacity to the rated value. The PRE20XXS series products have been designed with an independent detection system, which does not need to adjust the detection system or set the current detection multiplier. ACTIONPOWER

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Figure 29 Wiring Diagram of Single-phase/DC Load with Current J Figure 30 Wiring Diagram of Single-phase/DC Load with Current <50A rms

Note: 1. The N line of all wiring modes must be short-circuited.

2. It is necessary to switch from three-phase mode to single-phase/DC mode after correct wiring as shown in the diagram. See Section 8.2 for details.

5.10 Installation of Energy Matrix Interface

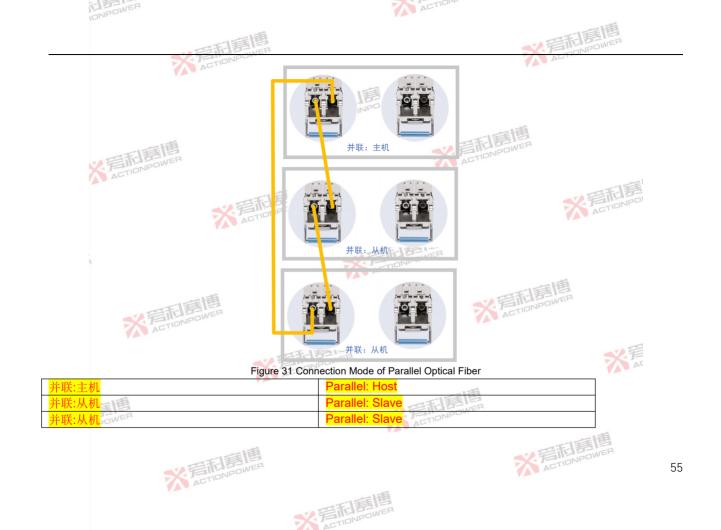
When the PRE20XXS series products are parallel, the outputs shall be short-circuited and the optical fiber cable shall be used for communication. This product only opens the Energy Matrix interface on the left side. Take 3 PRE20XXS series products in parallel as an example. The optical fiber connection method is shown in Figure 31. Insert the optical fiber cable into the optical module, fasten the optical fiber module, and then insert the optical fiber module into the Energy Matrix interface of the product. ACTION

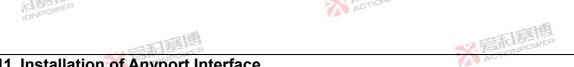
* 岩利县





≥50A rms

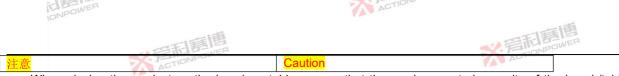




5.11 Installation of Anyport Interface

Anyport is a flexible user interface. An analog programming converter can be connected to this interface to use it. It is necessary to disconnect the power input before connecting or unplugging the Anyport interface. The installation method of Anyport is shown in Figure 32.





When placing the product on the bench or table, ensure that the maximum rated capacity of the bench/table is greater than the actual weight of the product.

The PRE20XXS series products are equipped with instrument pads at the bottom to prevent sliding damage to the desktop when used on the desktop. However, do not push the product forcibly when moving, to prevent the rubber parts ACTIONPOWER of the instrument pad from falling off and damaging the desktop.

5.13 Rack mounting

The PRE20XXS series products can be installed in standard 19-inch racks. Customers/system integrators who want to install one or more PRE20XS series products in their systems can order the PRE20XXS dedicated rack directly. The rack is equipped with input and output terminals and has reserved L-shaped support mounting space for zero stacking with other devices or test equipment. Xi'an ACTIONPOWER Electric Co., Ltd. can provide corresponding CTIONPOWER technical support.

5.14 Ventilation

The PRE20XXS series products adopt the design of front panel air inlet and rear panel air outlet. In order to ensure the normal operation of the product, there shall be no obstacle 30cm away from the rear panel to block the outlet air flow during installation of the PRE20XXS series products to prevent overheating.

5.15 Noise level



When the product is running at or near rated full power in high temperature environment, the fan speed will reach its maximum. The noise level of the power supply may exceed 70 dB at a distance of 1 m from the front panel of the power supply. The installer shall provide measures to reduce the noise level at the point of use by the operator to a safe level. These measures may include the installation of noise reduction baffles or the provision of protective earplugs. Operators 后前時 ACTIONPOWER should wear ear protection when exposed to these levels of noise.

Caution

ACTION

5.16 Liquid Prevention

PRE20XXS series products have no liquid spillage protection. Do not install it in areas where chemicals or liquids ACTIONPOWER ACTIONPO may spill.

5.17 Cleaning

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PRE20XXS series products have no user cleaning design or cleaning accessories, and can be used for a long time in the recommended environment. If necessary, please contact the manufacturer for after-sales service.

5.18 Handling of abnormal conditions

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In the unlikely event of product failure, or if the power supply cannot be turned on even if the correct AC power supply is connected, please attach a warning label to the power supply to indicate that maintenance or repair is required. Contact Xi'an ACTIONPOWER Electric Co., Ltd. or its authorized representative to arrange services. ACTIONPOWER

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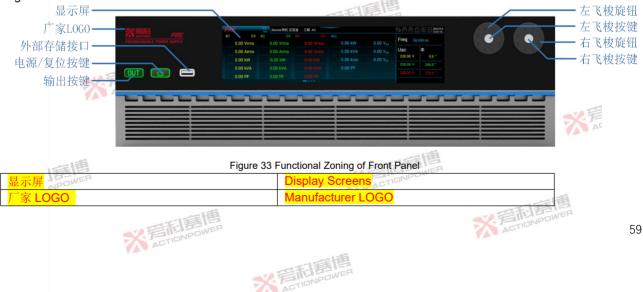


6 Front Panel

6.1 Front panel layout

The PRE20XXS series products are designed with an integrated panel. At the same time, the operation functions are distributed according to the principle of frequency of use and operation habits. The key function is placed at the lower left and the rotation function is placed at the upper right, which greatly speeds up the operation efficiency and improves the precision. The division of the operation functions takes into account the left-handed and right-handed users at the same time, so that each operator can be comfortable.

The functional partition of the front panel is shown in Figure 33, including display screen, manufacturer LOGO, external storage interface, power/reset button, output button, left shuttle knob, left shuttle button, right shuttle knob and right shuttle button.



| INPOWER | ACTION |
|-------------|----------------------------|
| | |
| 外部存储接口 | External storage interface |
| 电源/复位按键- | Power/reset button - |
| 输出按键 | Output button |
| 左飞梭旋钮 | Left shuttle knob |
| 左飞梭按键 | Left shuttle button |
| 右飞梭旋钮 | Right shuttle knob |
| 右飞梭按键音和音wer | Right shuttle button |

6.1.1 Display Screens

PRE20XXS series products use 8.8 inches, 1920*480 resolution, 16-bit RGB ultra-large aspect ratio LCD touch screen, which can display more information. The user can operate the controls by touching the display and physical keys.

6.1.2 Manufacturer LOGO

The manufacturer's LOGO has the function of indicating the product status. When the PRE20XXS series products are powered on, the LOGO will be lit up in red. The upper left corner is the company logo, the right side is the product series name PRE, and the bottom is the full name of the product PROGRAMMABLE POWER SUPPLY, that is, bidirectional AC programmable power supply.

6.1.3 External storage interface

This interface is used for external USB storage device, which can access and exchange the information of internal and external USB storage devices of PRE20XS series products. AC

6.1.4 Power/reset button

The power/reset button is the ON, OFF and reset button for PRE20XXS series products, with tri-color indicator lamp function. Yellow for standby, green for normal operation and red for protection.

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6.1.5 Output button

The output button is a button to turn on or off the output terminal. When the button indicator is not on, it indicates ACTIONPON ACTIONPOWER



| の三形意情 | NPOWER | | |
|--|---|--|--|
| that the output terminal is inoperable; when the button indicator is | green, it indicates that the output terminal is | | |
| disconnected; when the indicator is red, it indicates that the output term | ninal is connected. | | |

ACTION

6.1.6 Left/right shuttle button and knob

The backlight of the left/right shuttle button is off by default. The backlight is on when the shuttle button is pressed, and the shuttle knob at the corresponding position is enabled. After no operation for 5s, the shuttle button backlight will be automatically extinguished, and the shuttle knob function at the corresponding position will be invalid.

The left/right shuttle knobs are used to set the values on the right side of the main screen of the display. The left shuttle knob sets the output voltage and the right shuttle knob sets the frequency. The user can set the desired value by using the shuttle knob instead of the on-screen numeric keypad. Rotating the left/right shuttle knob clockwise increases the value and rotating it counterclockwise decreases the value in steps of 1.

6.2 Operation related to power/reset button

The power/reset button can realize three functions: power on, off and reset.

6.2.1 Power On/Off

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The power-on operation of the PRE20XXS series products is as follows:

Step1: Turn the rear panel AC circuit breaker upwards to ON, as shown in Figure 34, State 1;

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Step2: Wait for the front panel manufacturer's LOGO to light up, and the power/reset button indicator light turns yellow. At this time, it is the standby state, as shown in Figure 34, state 2;

Step3: Press and hold the power/reset button until the indicator light turns green, see Figure 34, status 3, that is, the product is turned on.

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X ACTIONPOWER

| INPOWER | ACTION | |
|---------|---------------------------|------------------|
| | | ※ 言 和 言 傳 |
| | | |
| AL. | Figure 34 Startup Process | |
| 状态 1 | State 1 | ETIONPOL |
| 状态 2 | IONPOWER State 2 | ACTIDI |
| 状态 3 | State 3 | |

The shutdown operation of the PRE20XXS series products is as follows:

Step1: Disconnect the output terminal, see Figure 35, State 1;

Step2: Press and hold the power/reset button until the indicator light changes from green to yellow, see Figure 35, State 2;

Step3: Turn the rear panel AC circuit breaker down to OFF, see Figure 35, status 3, that is, the product shutdown is completed.

Although the PRE20XXS series is a feedback device, it has anti-islanding function. In an emergency, when energy is fed back to the grid through the product, it can still be shut down by directly disconnecting the AC terminal circuit breaker. However, it is usually recommended to follow the above shutdown steps.

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| INPOWER | ACTION | |
|--------------------------|------------------------------------|-----------|
| ION I | PROGRAMMARLE POVER SUPPLY | |
| | | |
| | 状态2 | 状态3 |
| | Figure 35 Shutdown Process Diagram | |
| 状态1 | State 1 | ACTIONPOL |
| 状态 2 | State 2 | |
| <mark>状态 3</mark> | State 3 | |
| 6.2.2 Automatic start-up | * FILLSWER | |

6.2.2 Automatic start-up

PRE20XXS series products have automatic startup function, which simplifies the startup steps and is convenient for users.

The automatic start-up shall set the starting mode of the product to be automatic, as detailed in Section 8.13.

6.2.3 Reset

The reset operation of the PRE20XXS series products is as follows:

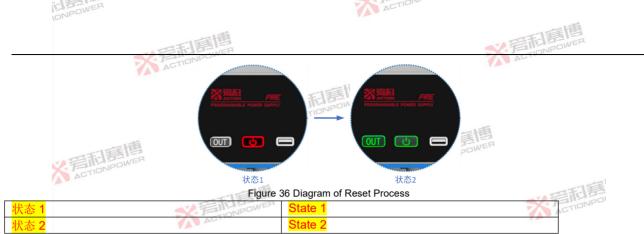
Step1: The power/reset button indicator turns red and the status display area shows the protection status, see Figure 36. State 1:

Step2: Press the power/reset button briefly and the output button indicator starts to flash. The reset action is completed until the power/reset button indicator and output key indicator turn green, and the status display area changes from the protection state to the standby state, as shown in Figure 36, State 2.

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6.3 Output button-related operation

The output button is a button to turn on or off the output terminal. When the button indicator is not on, it indicates that the output terminal is inoperable; when the button indicator is green, it indicates that the output terminal is ACTIONPOWER disconnected; when the indicator is red, it indicates that the output terminal is connected.

6.3.1 Manual output

The output operation of the PRE20XXS series products is as follows:

Step 1: The power supply is in standby state, see Figure 37, state 1:

Step2: Press the output button, the output relay is engaged, and the indicator lamp of the output button changes from green to red, as shown in Figure 37, State 2. At this time, the output terminal of the product is connected;

Step3: Press the output button again, the output relay is disconnected, and the output button indicator lamp changes from red to green, as shown in Figure 37, State 3, and the output terminal of the product is disconnected at this time.

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| IONPOWER | ACTIC | 2101 |
|------------------------|---------------------------|-----------------------|
| |] EDWER | 来 言和 ETIDNPOWER |
| | | |
| ACTION 状态1 | 状态2 | 状态3 |
| | Figure 37 Output On State | |
| 状态 1 | State 1 | A TETIONPOL |
| 状态 2 | ACTIONICE State 2 | |
| 大态 3 | State 3 | |
| 6.3.2 Automatic output | * TUNPOWER | |

6.3.2 Automatic output

The PRE20XXS series products have the function of automatic output. When the product operation mode is set to automatic, as shown in Section 8.13, the product will automatically output according to the parameter settings saved last ACTIONPOL time after startup.

Output on/off delay 6.3.3

PRE20XXS series products have the functions of output on-time delay and off-time delay.

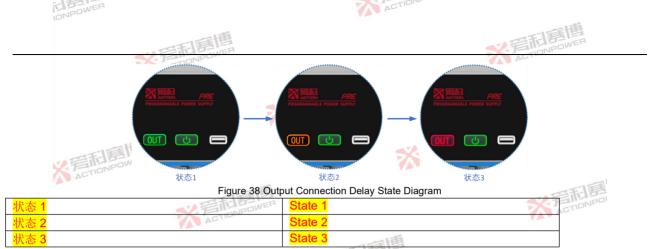
When setting the on-delay time of the product, see Section 8.13 for details. In the standby state, after pressing the output button, the indicator light of the output button turns from green to yellow, as shown in State 2 of Figure 38. After the set on-delay time, the output relay is closed, and the indicator light of the output button turns from yellow to red, as shown in State 3 of Figure 38. At this time, the output end of the product is connected. NPOWER

* STIDNPOWE

ACTION

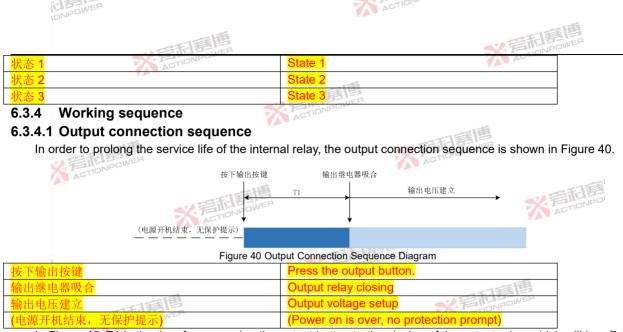






When the product disconnection delay time is set, see Section 8.13 for details. In the output state, after the output button is pressed, the output button indicator turns from red to yellow, as shown in State 2 of Figure 39. After the set disconnection delay time, the output relay is disconnected, and the output button indicator turns from yellow to green, as shown in State 3 of Figure 39. At this time, the output end of the product is disconnected.





In Figure 40, T1 is the time from pressing the output button to the closing of the output relay, which will be affected by many factors such as on-time delay parameters and response delay, and the minimum time is 100ms. AC

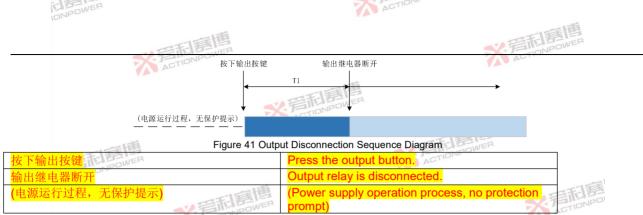
6.3.4.2 Output disconnection sequence

See Figure 41 for the output disconnection sequence.









In Figure 41, T1 is the time from pressing the output button to disconnecting the output relay, which is affected by various factors such as shutdown slew rate, shutdown angle and disconnection delay parameter. The output voltage has dropped to zero before the output relay is disconnected.

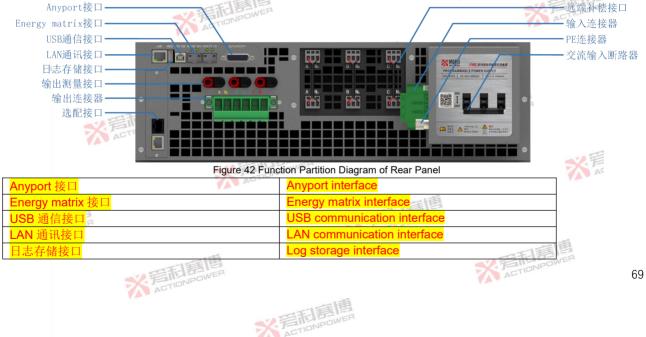




The rear panel of PRE20XXS series products provides a simple and standard interface. This chapter introduces the layout of the rear panel and matters needing attention in use.

7.1 Rear panel layout

The rear panel includes Anyport interface, Energy matrix interface, USB communication interface, LAN interface, log storage interface, output measurement interface, output connector, optional interface, remote compensation interface, input connector, PE connector and AC input circuit breaker, as shown in Figure 42.

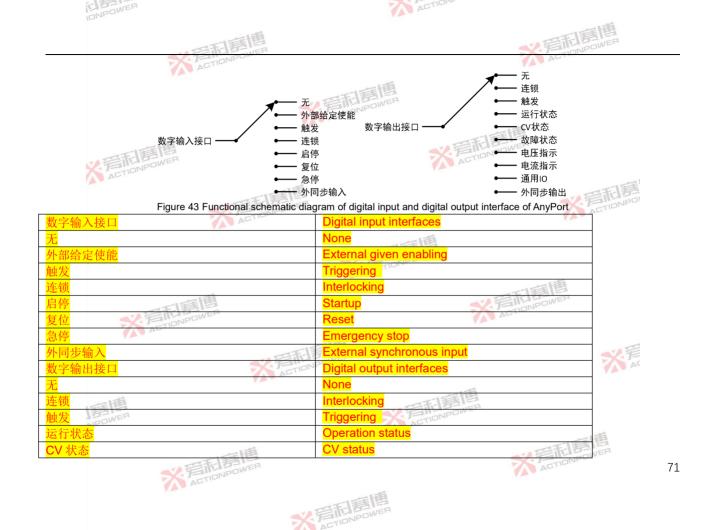


| IDNPOWER | ACTION |
|-------------------|--|
| 三市憲博 | ※ 言和 E I I I I I I I I I I I I I I I I I I |
| 输出测量接口 | Output measurement interface |
| 输出连接器 | Output connector |
| <mark>选配接口</mark> | Optional interface |
| 远端补偿接口 | Remote compensation interface |
| 输入连接器 | Input connector |
| PE 连接器 | PE connector |
| 交流输入断路器 | AC input circuit breaker |

Anyport interface 7.2

洞窟 Anyport is a multi-functional interface, which has four types: digital input, digital output, analog input and analog output. By configuring the corresponding functions of this interface, users can operate and monitor the product's status. 6-channel digital input interfaces and 6-channel digital output interfaces can be independently configured to realize different demand control. See Figure 43 for the functions of digital input and digital output interfaces.





| DOWER |
|-------|
| INPU |
| IL. |



| | 三和唐唐 | | 《 》章而唐 | 美唐 |
|--------------------|-------------|---|-----------------------------|-----------|
| 敏障状态 | ACTIONPO | | Sensitive barrier state | |
| <mark>电压指示</mark> | | | Voltage indication | |
| 电流指示 | | - | Current indication | |
| 通用 IO | | 7 | Universal IO | |
| <mark>外同步输出</mark> | | | External synchronous output | |

Analog interface function has been fixed, which can be configured to realize voltage, current, power, internal resistance and analog control. See Table 7for detailed functional information.

Table 7 Functions of Anyport Interface

| Interface type | Pin position | Signal level | Functional description | | |
|----------------|--------------|---------------------|---|--|--|
| | Pin10 | 米着雨 | WER SKIETIONPOL | | |
| | Pin11 | | Six pins correspond to six input interfaces, each of which can be configured with external | | |
| Digital input | Pin19 | 3V~27V | given enabling, triggering, interlocking, start-stop, reset, emergency stop and external | | |
| Digital input | Pin20 | 30~270 | synchronous input functions. The schematic diagram of digital input interface is shown in | | |
| | Pin21 | | Figure 44. | | |
| 2 | Pin22 | | Figure 44. | | |
| | Pin1 | | | | |
| Digital output | Pin2 | iffi | Six pins correspond to six output interfaces, each of which can be configured with interlocking, trigger, general I/O, voltage indication, current indication and external | | |
| | Pin3 | 3V~27V | synchronous output functions, and each of which can be configured to monitor the running | | |
| | Pin4 ACTION | | state, CV state and protection state of the product. The default interface is OC (open collector), and the current limit shall be 3~10mA when using. See Figure 45 for the | | |
| | Pin14 | | schematic diagram of digital output interface. | | |
| | Pin15 | | | | |
| Pin9 | | | This pin can be configured with the tracking amplitude, tracking valid value or real-time tracking function of Φ 1, and the measuring range can be configured in the "Anyport-Analog" interface. See Section 8 14.2 for details. | | |
| Analog input | Pin8 | -5V~5V/ -10V~10V | This pin can be configured with the tracking amplitude, tracking valid value or real-time tracking function of Φ 2, and the measuring range can be configured in the "Anyport-Analog" interface. See Section 8.14.2 for details. | | |
| | Pin7 | 一個 | This pin can be configured with the tracking amplitude, tracking valid value or real-time tracking function of Φ 3, and the measuring range can be configured in the | | |
| | 1.7 | STIDNPOWER | ACTIONICE 72 | | |

*ETIDNPOWER



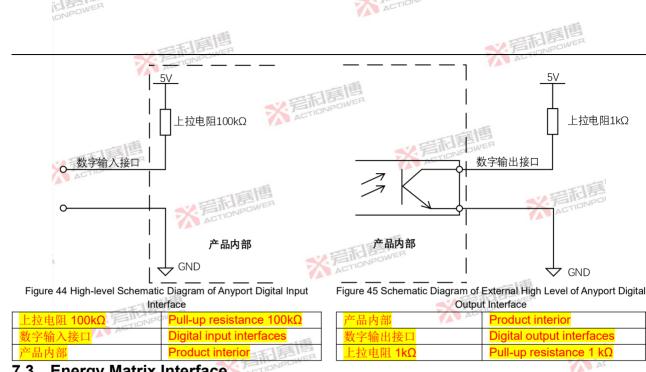
72





| | | 三和夏博 | ※ 着和厚個 |
|------------------------------|--|------------------|---|
| nterface type | Pin position | Signal level | Functional description |
| | | 1 | "Anyport-Analog" interface. See Section 8.14.2 for details. |
| | Pin6 |] | This pin can be configured to track the output frequency. See Section 8.14.2 for details. |
| | Pin24 | 5V | This pin is a 5V voltage reference output. Users can divide the voltage of this pin appropriately, and connect it by themselves according to the requirements, and set the setting value of this product. |
| Analog output Pin25 Pin26 | Pin25 Pin26 | -5V~5V | Both pins can indicate the voltage valid value, current valid value, active power, apparen power and reactive power of each phase, as well as total active power, total apparen power and total reactive power. Configure the measuring range in the "Anyport- Analog" interface. See Section 8.14.2 for details. The parameter value of analog output is proportional to the parameter value of actual output. |
| Ground erminal | Pin5 Pin12 Pin13 Pin16 Pin17 Pin18 Pin23 | ※ 着 c Tion | The seven pins are the negative terminals of the digital input, digital output, analog input and analog output interface pins, and are grounded together. |





7.3 Energy Matrix Interface

Energy Matrix is an energy matrix interface, which is a unique parallel function of this product, and can realize the parallel expansion of 10 products to 200kVA capacity. The general parallel system will have uneven flow after parallel expansion, and the maximum output capacity of the system will be less than the product of the single machine capacity and the number of parallel connections. With the increase of the number of parallel systems, this situation will become ACTIONPOWE

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more and more obvious. The Energy Matrix interface of this product can provide an uneven fluidity of less than 0.02%. with almost no loss of capacity.

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7.4 USB interface

The USB interface is used for remote control. It is a Type-B interface, which supports two types of USB2.0 and USB1.1, and includes two protocols, namely USBTMC and USB488. The transmission rate can reach 480Mbps. In order to ensure the communication reliability, the length of the connecting line is not allowed to exceed 2m, and both SCPI and Modbus-RTU protocol instruction sets are supported. See PRE20 series bidirectional AC programmable power supply programming guide for details.

Note: USB and LAN interfaces can receive inquiry instructions at the same time, but only one control instruction can be selected

7.5 LAN interface

Remote control is accomplished through the LAN interface. Standard RJ45 interface, port number is 502. Support SCPI or Modbus-TCP two protocol instruction sets. See PRE20 series bidirectional AC programmable power supply programming guide for details.

Note: USB and LAN interfaces can receive inquiry instructions at the same time, but only one control instruction can be selected. ACTIONPOWER

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7.6 Log storage interface

The log storage interface can be connected with an external USB storage device to import/export the contents of the log interface. See Section 8.11.2 for specific operations.

7.7 Output measurement interface

PRE20XXS series products are designed with a standard 4mm banana socket, which can be adapted to various ACTIONPOWER types of measuring instruments to quickly measure the output end voltage.

7.8 Output connector

The output connector is the output end of PRE20XXS series products. In all cases, when the AC input is connected 后前:時間 ACTIONPOWER ACTION

to the product, the operator must disconnect the input of the product before connecting or disconnecting the wiring of the output connector.

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7.9 **Optional interface**

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2 音和嘉 Optional interface can expand the functions of PRE20XXS series products, which can be used in different industries. Users can refer to the Magic-Box/Magic-Bus manual to select the required expansion components. The optional interface has two card slots, both of which can automatically identify Magic-Box/Magic-Bus functional components, but only one Magic-Box and one Magic-Bus can be installed, and two Magic-Boxes or Magic-Buses with different functions cannot be identified.

7.10 Remote compensation interface

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The remote compensation interface of PRE20XXS series products has the function of remote compensation voltage, which can directly compensate the voltage drop on the line from the output end to the external load. The value displayed on the display screen is calculated by sampling from the compensation interface, so the remote compensation cable must always be connected to the output end or the user load end.

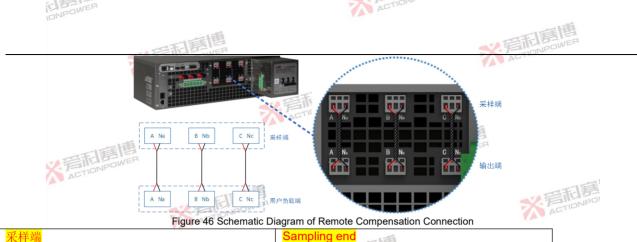
With the increase of AC output frequency or output power, the terminal voltage of load may decrease. If you want to obtain more accurate voltage at the load port, please use the remote compensation cable, and the user can connect it by himself as required. See Figure 46 for the connection mode.

One end of the compensation cable is connected to the "sampling end" and the other end is connected to the "user load end" according to the corresponding phase sequence, and the remote compensation function is automatically enabling.

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| <mark>采样端</mark> | Sampling end |
|------------------|---------------|
| 用户负载端 | User load end |
| 采样端 | Sampling end |
| <mark>输出端</mark> | Output end |

The requirements for remote compensation cables connected by users themselves are as follows:

For the line compensation cable with a length of less than 5m, the cross-sectional area is suggested to be 0.5mm²; The compensation line shall be twisted;

In parallel mode, the compensation line only needs to be connected to the host product;

The dielectric strength of the compensation line must at least meet the rated DC voltage of 636 V;

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7.11 Input connector

The input connector is the AC input end of PRE20XXS series products, which can be directly connected to the power grid. Before connection, be sure to turn the input circuit breaker to the OFF position.







PE connector is the ground terminal of PRE20XXS series products. In order to ensure personal and product safety, PE connector must always be connected to the ground.

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7.13 AC end circuit breaker

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The AC-side circuit breaker is an important switch connecting the PRE20XXS series products with the network side, which has the functions of overload and short circuit protection. When the circuit breaker at the AC end is turned ON, it will be powered on, and when it is turned OFF, it will be powered off. When not using this product, be sure to turn the circuit breaker to the OFF position.

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8 Display screen function and operation

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All parameter settings and functional applications of PRE20XXS series products can be realized by operating the front panel display screen, and the functional interface of the display screen is divided into 16 parts, as shown in Figure 47. You can swipe left and right or up and down in each function interface to view related content.



Main Interface 8.1

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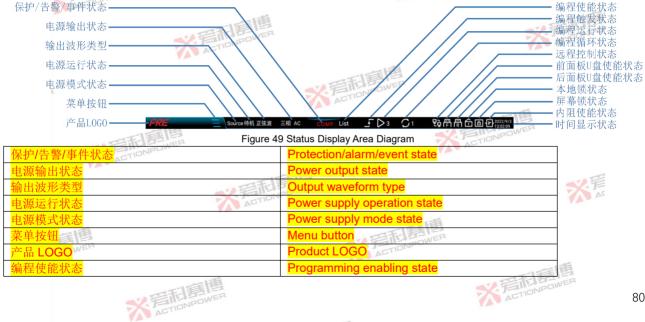
The main interface, as shown in Figure 48, is divided into the following five areas: menu operation area, status display area, output display area, drop-down shortcut area and output setting area. Different areas can achieve different functions, and users can quickly obtain the required information in these interfaces.



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|----------|----------|-------------------------|---------------|
| | 平和軍團 | | 秋 焉而唐唐 |
| 菜单按钮 | ACTIONPU | Menu button | AL |
| 输出显示区 | | Output display area | |
| 下拉快捷区 | | Drop-down shortcut area | |
| 输出设置区 | | Output setting area | |

8.1.1 State display area

The status display area at the top of the display screen is shown in Figure 49, which indicates the working status and working mode of PRE20XXS series products. See Table 8 for details.







| | 三和夏唐 | ~ 第前書 | 王国 DOWER |
|-------------------------------|--------------|---|-------------|
| 编程触发状态 | ACTIONPOWE | Programming triggering state | |
| 编程运行状态 | | Programming running state | |
| 编程循环状态 | | Programming cycle state | |
| 远程控制状态 | | Remote control state | |
| 前面板 U 盘使能状态 | | U disk enabling status of front panel | |
| 后面板 U 盘使能状态 | | Enabling status of rear panel USB flash drive | |
| 本地锁状态言志了品wer | 2 | Local lock state | |
| 屏幕锁状态ACTION | | Screen lock state | |
| 内阻使能状态 | 画種 | Internal resistance enabling state | 目和 |
| 时间显示状态 | SK FILMPOWER | Time display status | ACTIONPO |
| Table 8 Menu of Status Displa | | | |

Table 8 Menu of Status Display Area 🍊 🐣

| State area | Display content | Interpretation and application |
|---|--------------------|---|
| Product LOGO | PRE | PRE20XXS series product LOGO. |
| Menu button | Ξ | Click the menu button and a menu bar will appear on the right side of the interface. |
| Power supply mode | Source | Users can set this product to work in Source mode when they need bidirectional power flow. See Section 8.15 for the operation mode. |
| state | Load | When users need to absorb external power, they can set this product to work in Load mode. See Section 8.15 for the operation mode. |
| | Standby | The output end of this product is disconnected. When the output end is not used, the product can work in standby state. See Section 6.3 for the operation mode. |
| | Operation | The output end of this product is connected. When the output end is needed, the product can be operated. See Section 6.3 for the operation mode. |
| Power supply operation state Protection | | This product enters the protection state, at this time, the output end is disconnected and reset operation is required to restore the standby state. See Section 6.2.2 for the operation mode. When users need to protect products and user equipment from working in a safe range, they can do so by setting protection parameters, as shown in Section 8.8. |
| | Reset | Product reset can be restored to standby state. In case of protection/alarm/event, if the user needs to return to the standby state, he can click the power/reset button or use the external input reset signal of |
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| 10 | 1 | 112 | OWEP |
| | | 10NF | |

| State area | Display content | Interpretation and application |
|----------------------|--------------------|---|
| | | Anyport for reset operation. See Section 8.14.1 for the operation mode. |
| | Emergency stop | The emergency stop of this product disconnects the output. When the user needs to disconnect the output urgently, he can click the output button or use the emergency stop signal input from Anyport for emergency stop operation. See Section 8.14.1 for the operation mode. |
| Output waveform type | Sine wave | In "Waveform Selection", you can select the waveform type. See Figure 59 for details. |
| Power output state | Three-phase AC | Displays the current output phase number and coupling mode. |
| | LVP | Load undervoltage protection. The output port voltage in load mode is lower than the set value in Section 9.6 "Protection" interface. |
| | OVP 🗧 | Overvoltage protection. It indicates that the output voltage is higher than the set value in Section 8.8 "Protection" interface. |
| | OCP | Overcurrent protection. It indicates that the output current is higher than the set value in Section 8.8 "Protection" interface. |
| | OPP | Overpower protection. It indicates that the output power is higher than the set value in Section 8.8 "Protection" interface. |
| | LFP | Low frequency protection. It indicates that the output frequency is lower than the set value in Section 8.8 "Protection" interface. |
| Protection status | OFP | Overfrequency protection. It indicates that the output frequency is higher than the set value in Section 8.8 "Protection" interface. |
| | CHAENPORT | Chain protection. Receive external interlocking signal through "Anyport", see Section 8.14 for details. |
| | SLAF | Slave protection. When the machine is connected in parallel, any slave machine will be protected, which will be displayed in the interface of the host machine. |
| | INSF | Internal protection. It indicates internal module protection. |
| | POWF | Power supply protection. It indicates that external power supply is abnormal. |
| | PARF | Parallel communication protection. It indicates that the optical fiber line connection is abnormal. |
| | COMF | Communication timeout protection. It indicates abnormal communication within the product. |
| | OPT | Over-temperature protection of air outlet. |
| | SENF | Telemetry protection. It indicates that the feedback cable is abnormal. |
| Alarm status | EMST | Emergency stop alarm. Receive external emergency stop signal through "Anyport". See Section 8.14 for |
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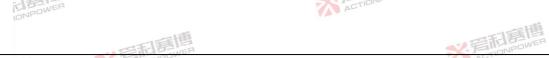
| | | 日夏唐 |
|--|--------------------|---|
| State area | Display content | Interpretation and application |
| | IPAF | IP conflict alarm. It indicates that the IP address of the product conflicts. |
| | SPDL | Alarm of data range overrun of AC source programming. It indicates that during programming operation when the set data is higher than the set value in Section 8.7 "Limits", it will run according to the limit and give an alarm at the same time. |
| | LVL | Cut-off voltage alarm Load mode gives an alarm when the external input voltage is lower than the AC cut-off voltage during operation. |
| | WAIT | Parallel WAIT alarm. It indicates that the parallel machine conditions are not available. |
| | PARA | Parallel redundant alarm. It indicates that the parallel system is running in parallel redundancy state. |
| | TMCE | USBTMC queue empty alarm. USBTMC query queue is empty. |
| Event state | Event X | It displays triggered user events, for example, Event 1. |
| | List | This status is displayed after the List mode in the programming interface is loaded. |
| Programming | Wave | This status is displayed after the Wave mode in the programming interface is loaded. |
| enabling state | Step | This status is displayed after the Step mode in the programming interface is loaded. |
| chabiling state | Pulse | This status is displayed after the Pulse mode in the programming interface is loaded. |
| | Advanced | This status is displayed after the Advanced mode in the programming interface is loaded. |
| Programming triggering state | F | When the programming mode is triggered, this icon will light up. |
| Programming running state | D_3 | It displays the serial number that the current programming is executing. |
| Programming cycle state | SANPOWE | It displays the number of cycles that the current programming is executing. |
| Remote control state | 된 | This icon will light up when the remote control is turned on. |
| U disk trigger status of front panel | | This icon will light up when the product recognizes the USB storage device on the front panel. |
| U disk trigger status of rear panel | | This icon will light up when the product recognizes the USB storage device on the rear panel. |
| Local lock state | | This icon will light up when the local lock is opened. |
| Screen lock state | æ | This icon will light up when the screen lock is opened. |
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※ 言和 言情 Action power





| IONPOWER | | | ACTION | | |
|------------------------------------|----------------------------|----------------------------------|---------------------------------------|-----------------------------|----|
| | | 日夏唐 | | 秋 岩和唐唐 | |
| State area | Display content | Interpretation and application | | | |
| Internal resistance enabling state | F | When the internal resistance is | s enabling, this icon will light u | p. | |
| Time state | 2022/9/3 13:02:09 | It displays the current time (ye | | | |
| X SETION | 言 MPDWER | | ※ 着在TIOT | | |
| | | ※ 言和意情 | | ※ 言相言 ACTIONIO | |
| 2 | | * | 若而意愿 | - | |
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| | | ※ 着西 ACTION | FILE | | |



8.1.2 Menu operation area

Press the menu button in the main interface, and a menu interface will appear on the right side of the main interface, as shown in Figure). You can view all menu items by sliding up and down in the menu interface. Click in any interface to enter the main interface.

| | FRE | | 俞 | Source待机 正 | 弦波 | 三相 AC | | | | 동5 t | F R C C 2022/9/3 12:47:23 | |
|---------|-----|----------|----|------------|----|---------|-----|-----------|----------------------|-------------------------|------------------------------|--------|
| | Φ1 | CV | Φ2 | CV | ФЗ | CV | ALL | | | Ø | 模式 | |
| THE | C | .00 Vrms | | 0.00 Vrms | | | | 0.00 kW | 0.00 V ₁₂ | | 参数 | |
| ACTIONE | 0 | .00 Arms | | 0.00 Arms | | | | 0.00 kVA | 0.00 V ₂₃ | | | |
| AL | C | .00 kW | | 0.00 kW | | | | 0.00 kvar | 0.00 V ₃₁ | | 编程 ~ | |
| | C | .00 kVA | | 0.00 kVA | | | | 0.00 PF | | | 谐波 | 雪村 |
| | | .00 PF | | 0.00 PF | | | | | | M | 间谐波 | ACTION |
| | | | | 0.0011 | | 0.00 11 | | | | $\overline{\mathbf{N}}$ | 限值 | |

Figure 50 Menu Interface Diagram

8.1.3 Output display area

The output display area is the display area of product output parameters, which is divided into four pages, namely, output basic parameters display page, output detail parameter display page, voltage/current distortion rate digital display page of voltage/current distortion rate column display page. Swipe left and right in this area to see the corresponding content.

8.1.3.1 Output basic parameters display page

The display page of output basic parameters is shown in Figure 51. See Table 9 for the definition of each parameter.

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|-------------------|---|---------------------|---------------------|-------------------|------------------------|----------|
| | 一一一一 | 唐 | | | X 着起幕情 | B |
| | Φ1 CV | •2 CV • | 42 OV | ALL | ACTIO | |
| | | | | | 0.00.1/ | |
| | 0.00 Vrms | 0.00 Vrms | 0.00 Vrms | 0.00 kW | 0.00 V ₁₂ | |
| | 0.00 Arms | 0.00 Arms | | 0.00 kVA | 0.00 V ₂₃ | |
| | 0.00 kW | 0.00 kW | | 0.00 kvar | 0.00 V ₃₁ | |
| | 0.00 kVA | 0.00 kVA | | 0.00 PF | | |
| | | | | | | |
| ACTI | ONF 0.00 PF | 0.00 PF | 0.00 PF | | | |
| | Fig | gure 51 Output Basi | c Parameters Displa | ay Page Diagram | | 語 |
| able 9 Output Bas | ic Parameter Interpretatio | | | | XE | IONPO |
| arameter term | Interpretation | CTIONICO | | | AL. | |
| /rms | Valid value of output vo | | | | | |
| rms | Valid value of output cu | rrent | -15 | 图 | | |
| W | Active power | | | WER | | |
| VA | Apparent power | | ACTION | | | |
| ۶F | Power factor | | | | -126 | |
| var | Reactive power | | | | 王月夏日 | |
| 12、V23、V31 | Line voltage | | | 54.7 | TIONPOWER | |
| | ut detail paramete 52 for the output deta | | Nav nadel See T | able 10 for the c | lefinition of each par | ameter. |
| | | ACTIONPO | | | | AL |
| IEE IEE | | | × F | 記意 TIONPOWER | | |
| | ※着起意 ACTIONPOV | B JER | Y and T | | ※着和意情 ACTIONPOWER | 86 |
| | | 米戸 | 利意博 | | | |

| IONPOWE | | | | | AC | | | | 100 |
|--|---|--------------------|----------------------|------------|-------------|---------------|-----|--|-------------------|
| | 三百百 | 計 国 WEP | | | | | | 2.言形 | NPOWER |
| | Ø1 | CV | Ф2 | | CV | ሰ3 | | AU. | |
| | | 000 kW | 0.00 Vrms | s 0.00 | 00 kW | 0.00 Vr | | 000 kW | |
| | 0.00 Arms 0.0 | 000 PF | 0.00 Arms | s 0.00 | 00 PF | | | | |
| | 0.00 %Uthd 0.00 %Ithd | 0.0 * | 0.00 %Uthd | 0.00 %lthd | 0.0 * | | | | |
| | 0.00 Vac 0.00 Aac | 0.00 CF | 0.00 Vac | 0.00 Aac | 0.00 CF | | | | |
| | 0.00 Vdc 0.00 Adc | 0.000 kVA | 0.00 Vdc | 0.00 Adc | 0.000 kVA | | | | |
| TET | 0.00 Vpk 0.00 Apk | 0.000 kvar | 0.00 Vpk | 0.00 Apk | 0.000 kvar | | | | |
| | 0.00 V12 0.00 Arush | 0.000 Hz | 0.00 V ₂₃ | 0.00 Arush | 0.000 Hz | | | | |
| ACTI | Fig | | ut Page Diag | ram of D | etail Para | ameter Displa | ay. | | 晋利嘉 |
| Table 10 Output De | | | ut Page Diag | | etail Para | ameter Displa | ay. | Ž | SETIONPOL |
| Table 10 Output De Parameter term | Fig etail Parameter Interpretat | tion Table | ut Page Diag | | etail Para | ameter Displa | ay. | Ž | 与 石 CTIONPO |
| Table 10 Output De Parameter term %Uthd | Fig etail Parameter Int <mark>erpre</mark> tat | tion Table | ut Page Diag | | Detail Para | ameter Displa | ay. | Ž | 方に ACTIONPO |
| Table 10 Output De Parameter term %Uthd Vac | Fig etail Parameter Interpretat Interpretation Total voltage distortion | tion Table | ut Page Diag | | Detail Para | ameter Displa | ay. | Ž | ACTIONPOL |
| Table 10 Output De Parameter term %Uthd Vac Vdc | Fig etail Parameter Interpretat Interpretation Total voltage distortion AC voltage | tion Table | ut Page Diag | | Detail Para | ameter Displa | ay. | Ž | ACTIONPOL |
| Table 10 Output De Parameter term %Uthd Vac Vdc Vpk | Fig etail Parameter Interpretation Interpretation Total voltage distortion AC voltage DC voltage | tion Table rate | ut Page Diag | | Detail Para | ameter Displa | ay. | 2 | ACTIONPOL |
| Table 10 Output De Parameter term %Uthd Vac Vdc Vpk %Ithd | Fig etail Parameter Interpretat Interpretation Total voltage distortion AC voltage DC voltage Crest voltage | tion Table rate | ut Page Diag | | Detail Para | ameter Displa | ay. | | ACTIONIPOL |
| Table 10 Output De Parameter term %Uthd Vac Vdc Vpk %Ithd Aac | Fig etail Parameter Interpretat Interpretation Total voltage distortion AC voltage DC voltage Crest voltage Total current distortion | tion Table rate | ut Page Diag | | Detail Para | ameter Displa | | 22 | |
| Table 10 Output De Parameter term %Uthd Vac Vdc Vdc Vpk %Ithd Aac Adc | Fig etail Parameter Interpretat Interpretation Total voltage distortion AC voltage DC voltage Crest voltage Total current distortion AC current | tion Table rate | ut Page Diag | | Detail Para | ameter Displa | ay. | NPOWER | |
| Table 10 Output De Parameter term %Uthd Vac Vdc Vpk %Ithd Aac Adc Apk | Fig etail Parameter Interpretat Interpretation Total voltage distortion AC voltage DC voltage Crest voltage Total current distortion AC current DC current | tion Table rate | ut Page Diag | | Detail Para | ameter Displa | | The second secon | |
| | Fig etail Parameter Interpretat Interpretation Total voltage distortion AC voltage DC voltage Crest voltage Total current distortion AC current DC current Peak current | tion Table rate | ut Page Diag | | Detail Para | ameter Displa | | Powen. | |

8.1.3.3 Digital display page of voltage/current distortion rate

The digital display page of voltage/current distortion rate is shown in Figure 53. This page shows the odd and even ※ 言語 言語 action power harmonic content in the output voltage/current. NPOWER

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|----------|---|---|--|----------------------------|
| | | | | X 爱和意博 |
| | ¢1 | hd Φ2 | Thd 0 3 | The |
| | U 100.0% 1 100.0% 2 0.15% 2 0.0 | | | U 0.07% 1 0.00% |
| | U 32.87% J 0.00% U 0.08% J 0.0 | $\begin{array}{cccccccccccccccccccccccccccccccccccc$ | 13% ¹ / ₄ 0.00% ^U / ₃ 33.25% ¹ / ₃ 0.00% | U 0.16% 1 0.00% |
| | U 20.04% J 0.00% U 0.02% J 0.0 | 0% ${}^{U}_{5}$ 19.93% ${}^{I}_{5}$ 0.00% ${}^{U}_{6}$ 0. | 28% 6 0.00% 5 20.17% 5 0.00% | U 0.15% ^I 0.00% |
| | U 14.20% J 0.00% U 0.18% J 0.0 | $\begin{array}{cccccccccccccccccccccccccccccccccccc$ | 12% ^I 0.00% ^U 14.07% ^I 0.00% | U 0.08% ^I 0.00% |
| | U 10.66% J 0.00% U 0.02% I 0.0 | 0% ^U ₉ 10.86% ^I ₉ 0.00% ^U ₁₀ 0. | 12% 10 0.00% 9 11.33% 9 0.00% | U 0.23% I 0.00% |
| | $\begin{array}{c} U\\ 11 \end{array}$ 8.96% $\begin{array}{c} I\\ 11 \end{array}$ 0.00% $\begin{array}{c} U\\ 12 \end{array}$ 0.02% $\begin{array}{c} I\\ 12 \end{array}$ 0.0 | $\begin{array}{cccccccccccccccccccccccccccccccccccc$ | 05% 12 0.00% U 8.86% 1 0.00% | U 0.19% 12 0.00% |
| | U 7.59% I 0.00% U 0.01% I 0.0 | $\begin{array}{cccccccccccccccccccccccccccccccccccc$ | 10% 14 0.00% U 7.60% 1 0.00% | U 0.23% I 0.00% |
| ACTION | | | | 10 J |

Figure 53 Digital Display Page Diagram of Voltage/Current Distortion Rate

8.1.3.4 Voltage/current distortion rate column display page

The column display page of voltage/current distortion rate is shown in Figure 54. This page displays the histogram of 2-50 harmonic content of output voltage/current.

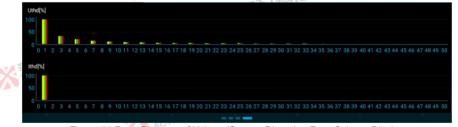


Figure 54 Page Diagram of Voltage/Current Distortion Rate Column Display

8.1.4 Drop-down shortcut area

The drop-down shortcut area provides some basic operations, which can improve the user's operation efficiency, and the same function can still be operated in the corresponding menu items. The function options in the drop-down shortcut area are temporarily not supported for adjustment or modification.

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Users can click the middle button at the top of the screen to open the drop-down shortcut area, and click the button imes at the top right to close the drop-down shortcut area. See Figure 55 and Table 11 for the established functions.



Figure 55 Drop-down Shortcut Area Map

| | riguie 55 Diop-down onoredt Area map |
|--------------------------|---|
| Table 11 Functions o | f Shortcut Area |
| Button | Interpretation and operation |
| Alarm tone | Click this button when the protection/alarm/event signal sound prompt is needed, and the alarm sound prompt will sound when the product screen displays the status. |
| Local control/LAN/USB | Click this button to quickly switch communication ports. |
| Screen lock | Click this button when you need to prevent misoperation or lock the screen. Click this button again and the screen lock function will be released. |
| Local lock | When it is necessary to prevent the remote command from modifying the control right, click this button, and the product can only allocate the control right through the display screen. |
| Clear event | Clear the events and status that have occurred. |
| List | Quickly jump to the programming interface or the corresponding functional interface. |
| | |

8.1.5 Output setting area

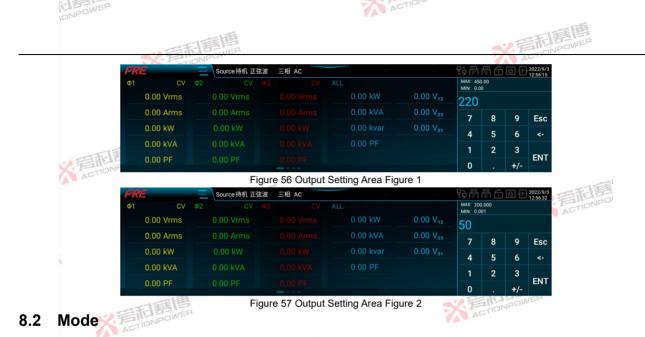
NPOWER

The output setting area can set the output voltage and frequency. Click the numerical value and enter the desired parameters in the right numeric keypad, as shown in Figure 56 and Figure 57. You can also use the left/right shuttle to set the parameters. See Section 6.1.6 for details. ACTIONPOWER

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Click Mode in the menu bar to enter the mode setting interface. In the mode setting interface, you can select the output phase number, coupling mode, output waveform and the percentage of waveform of PRE20XXS series products. See Figure 58 for the setting interface.





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| | | | ※言和意思 |
| | PRE 模式 Source待机 正弦波 三相 AC | | ₽ 骨 冊 ि ⑥ ₽ 2022/9/3 12:47:27 |
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| 2 | 百分比 | | |
| | | | ── 限值 |

Figure 58 Mode Setting Interface Diagram

Click the arrow to the right of "Select Waveform" to enter the waveform selection interface, as shown in Figure 59, which provides not only common sine wave, pulse wave, triangle wave, clipping wave and pulse wave, but also 30 kinds of harmonics, and opens 100 kinds of user-defined waveforms. Users can get the required waveforms by setting the percentages of pulse wave, triangle wave, clipping wave, leading half wave and trailing edge half-wave. See Table 12 for the percentage interpretation.

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| | | 正弦波 | | ▲ 三角波 | こ | ~_ 正半波 | | Q | 模式 | | |
| | | | 前沿半波 | く 后沿半波 | DST01 | DST02 | | -~ | | | |
| | | 657 | 20.77 D/ 010 | - 101 | 10180 | 05102 | | 2 | | - | |
| | | DST03 | DST04 | DST05 | DST06 | DST07 | 返回 | M | 间谐波 | | |
| | 一形 | DST08 | DST09 | DST10 | DST11 | DST12 | 预览 | $\overline{\mathbf{v}}$ | 限值 | | |
| Figure 59 Waveform Selection Interface Diagram Table 12 Percent Interpretation Table of Different Waveforms | | | | | | | | | | | |
| | cent Interpre | tation Table of | Different | Waveforn | ns | | | | | | |
| Waveform name | Unit | Percent interpretation | | | | | Mod | del | Resolution | Initial value | Setting range |
| Pulse wave | 1 | Duty cycle D | | | | | ALL | | 0.01 | 50 | 0~100 |
| Triangular wave | 1 | Symmetry S | | | | | ALL | - | 0.01 | 50 | 0~100 |
| Clipping wave | 1 | Percentage C | | | | | ALL | | 0.01 | 0 | 0~50 |
| Leading half wave | / | Percentage of conduction angle L | | | | | ALL | | 0.01 | O | 0~100 |
| Trailing edge half-wave | | Turn-off angle percentage T | | | | | ALL | | 0.01 | 50 | 0~100 |

8.3 Parameters

Click Parameters in the menu bar to enter the parameter setting interface. The parameter setting interface includes the parameter setting and function configuration related to product output.

The relevant parameter settings of product output include AC/DC output voltage, phase and frequency; Functional configuration includes AC limit, DC limit and internal resistance; You can also set the slope, response speed, slew rate, angle, impact current and external synchronization delay.

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| 1 | PRE 参数 | Source待机 | | | | 門骨合合子 2022/9/3 12:47:10 | |
| | 交流电压 | Φ1[V] 220.00 | Φ2[V] 220.00 | Ф3[V] 220.00 | | 模式 | |
| | | Φ1[V] | Φ2[V] | Φ3[V] | | 参数 | |
| | 直流电压 | 0.00 | 0.00 | 0.00 | | ⊻ 编程 ~ | |
| | 1 | Φ1[*] | Φ2[*] | Φ3[*] | | | |
| 一酒 | 相位 | | | | | ↓ 间谐波 ~ ✓ 限值 | |
| 三利男 | PRE 参数 | Source 待机 | 正弦波 三相 AC | | | ▶ 冊 冊 合 圖 [] 2022/9/3 12:47:52 | |
| ACTIONPOWER | | | | | | 模式 | |
| A | 频率 | 蔡率[Hz] 50.000 | | | | 参数 | -1 |
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| | 交流限值 | | | <u> </u> | | □ ····· · · · · · · · · · · · · · · · · | ACTION |
| | 直流限值 | | |) × | | ▶ 间谐波 ~ | |
| | 内阻 | 2020 to 100 1 | あたわ こわい…1 | 关 | | △ 限值 | |
| | PRE 参数 | Source待机 | 正弦波 三相 AC | | | 戸骨骨 合 圖 子 2022/9/3 12:48:00 | |
| ι | 斜率 | 交流电压[V/ms] | 直流电压[V/ms] | 频率[Hz/ms] | | 模式 | |
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| | 响应速度 | て 快速 | *** 中速 | ₹ 慢速 | | ⊻ 编程 ~ | WER |
| | | 电压[V/us] | 平迷 关机[V/us] | 20,20 | | na na | Un |
| ACTION | 摆率 | | | | | ▶ 间谐波 | |
| AL | PRE 参数 | 公 Source 待机 | 正弦波 三相 AC | | | へ 限値 日 局 合 圖 단 2022/9/3 12:48:11 | |
| | | 开机[*] | 关机[*] | | | 模式 | |
| | the set of | | | | | | |
| | 角度 | 0.0 | 0.0 | | | | |
| | 角度 暂态角度 | | | ● <u>×</u> | | 参数 | |
| | 暂态角度 | 0.0 起始时间[s] | 0.0 测量时问[s] |) ¥ | | 参数 ▶_编程~ | |
| 這個 | | 0.0 起始时问(s) 0.000 | | ž | - | ご参数 ☆ 编程 ~ ↓ 谐波 ~ | |
| 唐唐 NPOWER | 暂态角度 | 0.0 起始时间[s] | 0.0 测量时问[s] | | | 参数 ▶_编程~ | |
| NPOWER | 暂态角度 冲击电流 | 0.0 起始时间[s] 0.000 时间[s] 0.000 | 0.0 潮量时间[s] 0.000 | | | ☆数 ☆ 编程 ↓ 请波 ↓ 问谐波 ✔ (限值 | |
| Eigure 61 for the | 暂态角度 冲击电流 外同步延时 | 0.0 起始时间(s) 0.000 时间(s) 0.000 Figure (c) | 0.0 ^{測量时间(s)} 0.000 60 Parameter | | | ☆数 ☆ 编程 ↓ 请波 ↓ 问谐波 ✔ (限值 | 和意應 |
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See Figure 61 for the interface of AC limit enabling.



| NPOWER | | | | | | | N | ACTION | | | | |
|--------------|--|--|--|---|---------------------------------|---|-------------------------------|-------------|---|---|----------------------------|--------|
| | | 利赛 | 1 B | | | | | | | ×7 | TIONPOW | ER NER |
| 1 | FRE 参数 | s 👔 | ource待机ī | E弦波 三相 | AC | | | | · £Ç | ┇╔╫╔ | 022/9/26 0:54:31 | |
| 3 | を流限値 | | | | | | म – | | Ģ | 2 模式 | | |
| | 电流 | Φ1[A] | 35.00 | Φ2[Α] | 35.00 | ФЗ[А] | 35.00 | | | 参数 | | |
| | | | | | | | | | Ľ | ∑ 编程 | ~ | |
| | 视在功率 | Φ1[kVA] | 0.000 | Φ2[kVA] | 0.000 | Φ3[kVA] | 0.000 | | ~ | ₩ 谐波 | ~ | |
| | | | | | | | | | N | № 间谐波 | ~ | |
| | 直流限值 | | | | | | × 🔍 | | | ▲ 限值 | | |
| | 1.00 | | | | | | | | () () () () () () () () () () | TKIA | | |
| AGTIONPL | | | Figure | e 61 Inte | rface D |)iagram (| of AC L | _imit Enabl | ing | | | |
| nterface for | r enabling [| DC limi | | | |)iagram (e 62. | of AC L | _imit Enabl | ing | | | - |
| nterface for | r enabling [<i>「RE</i> 参数 | | | own in | Figur | | of AC L | ₋imit Enabl | - | ₽₽₽ ₽₽₽ ₽₽₽ | 22/9/26 | 雨 |
| nterface for | r enabling [| | it is sh | own in | Figur | | | ₋imit Enabl | Ę | | 022/9/26 0:54:44 | TION |
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| nterface for | r enabling [<i>PRE 参</i> 数 | ि ि | it is sh | own in E弦波 三相 | Figur | e 62. | | ∟imit Enabl | | ● 模式 ● 参数 | 022/9/28 0:54:44 | TION |
| nterface for | r enabling [PRE 参数 直流限值 正向电流 | ک 🖒 S Ф1[A] | it is sh ^{ource} 待机 ī | own in E弦波 三相 Ф2[A] | Figur AC | e 62. Ф3[A] | π – | ∟imit Enabl | | ● 模式 ● 参数 ▲ 编程 |)22/9/28 2:54:44 ACT | TION |
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| nterface for | r enabling [PRE 参数 直流限值 正向电流 负向电流 正向有功功率 | 61[A] 01[A] 01[A] 01[kW] | it is sh ource待机 ī 35.00 -35.00 | OWN in E弦波 三相 Ф2[A] Ф2[A] Ф2[kW] | Figur Ac 35.00 -35.00 | e 62. ФЗ[А] ФЗ[А] | 开 35.00 -35.00 | imit Enabl | | ● 模式 ● 参数 ◆ 编程 ● 谐波 ● 間 間 급 圖 ⊡ 篇 ● 間 間 급 圖 ⊡ 篇 | ~ | TION |
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Φ3[kW]

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Figure 62 Interface Diagram of DC Limit Enabling The internal resistance enabling interface is shown in Figure 63.

Φ2[kW]

Φ1[kW]



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| 10 | | 和夏博 | | | *2言起言 | |
| | PRE 参数 | Source 待机 j | E弦波 三相 AC | | 및 FR R C @ P2022/9/26 10:55:05 | |
| | 内阻 | | | <i>म</i> – | ④ 模式 | |
| | R | Φ1[Ohm] 0.000 | Φ2[Ohm] 0.000 | Ф3[Ohm] 0.000 | 参数 | |
| | | 0.000 | 0.000 | 0.000 | ▲ 编程 ● ● ● ● ● ● ● ● ● ● ● ● ● ● ● ● ● ● | |
| | L * * * | Φ1[mH] 0.000 | Φ2[mH] 0.000 | Φ3[mH] 0.000 | ∿ 谐波 ~ | |
| | | 交流电压[V/ms] | 直流电压[V/ms] | 频率[Hz/ms] | ▲ 间谐波 | |
| TATE | 斜率 | 交流电压[v/ms] 500.00 | 互加中的主[v/ms] 500.00 | 频率[nz/ms] 100.0000 | ── 限值 | |
| ACTION | 501 | Figure 63 | Internal Resist | ance Enabling Interfa | ace Diagram | |
| See Figure 64 | for transien | t angle enabli | ing interface. | | | 王寶 |
| | FRE 参数 | 公 Source 待机 i | E弦波 三相 AC | | दुही 🛱 🛱 🔂 🕼 🕑 1324/28 | ACTIONPOL |
| | 暂态角度 | | | # | @ 模式 | AL |
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Figure 64 Transient Angle Enabling Interface Diagram

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Figure 64 Transient Angle See Table 13 for detailed functions of each parameter. Table 13 Parameter Detailed Menu

| Parameter term | Unit | Interpretation and application | Model | Resolu tion | Initial value | Setting range |
|-------------------|------|---|-------|----------------|---------------|---------------|
| AC voltage | V | AC voltage setting of product output. | ALL | 0.01 | 220 | 0~450 |
| DC voltage | V | DC voltage setting of product output. | ALL | 0.01 | 0 | -636~636 |
| Phase | o | Phase angle setting of product output three-phase AC voltage. | ALL | 0.1 | 0 | 0~359.9 |
| Frequency | Hz | Frequency setting of product output AC voltage. | ALL | 0.001 | 50 | 0.001~200 |
| AC limit enabling | \ | The enabling button is only effective when | ALL | 1 | I STATE | ALER IER |
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| Parameter term Ur | Jnit 🏹 | Interpretation and application | Model | Resolu tion | Initial value | Setting range |
| switch | | the coupling mode is AC. When enabled, the maximum AC current and apparent power output by the product are limited to the settings. | ER | | | |
| Current X | | When the number of output phases is three-phase or split-phase, it indicates the maximum output AC current of each phase. | PRE2006S | ACTIONP 0.01 | Three-phase/sp lit-phase: 30 Single-phase: 90 | Three-phase/split- hase: 0~30 Single-phase: 0~9 |
| Current A | | When the number of output phases is single-phase, it indicates the maximum total output AC current. | PRE2009S PRE2012S PRE2015S PRE2020S | 0.01 | Three-phase/sp lit-phase: 35 Single-phase: 105 | Three-phase/split- hase: 0~35 Single-phase: 0~105 |
| 2 | | | PRE2006S | - | Three-phase/sp lit-phase: 2 Single-phase: 6 Three-phase/sp lit-phase: 2.5 | Three-phase/split- hase: 0~2 Single-phase: 0~6 Three-phase/split- hase: 0~2.5 |
| 大手 | AGTION | When the number of output phases is three-phase or split-phase, it indicates the | PRE2007S PRE2009S | X | Single-phase: 7.5 Three-phase/sp lit-phase: 3 | Single-phase: 0~7.5 Three-phase/split- hase: 0~3 |
| Apparent power 🚧 kV | VA | maximum apparent power of each phase. When the number of output phases is single phase, it indicates the maximum total apparent power. | PRE2012S | 0.001 | Single-phase: 9 Three-phase/sp lit-phase: 4 Single-phase: 12 | Single-phase: 0~9 Three-phase/split- hase: 0~4 Single-phase: 0~1 |
| INPOWER | | | PRE2015S | OWER | Three-phase/sp lit-phase: 5 Single-phase: 15 | Three-phase/split- hase: 0~5 Single-phase: 0~1 |
| | | -168 | PRE2020S | | Three-phase/sp lit-phase: 6.667 | Three-phase/split- hase: 0~6.667 |
| | | ACTIONPOWER | | | ACTIONP | 9 |





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| | | | | | ~ 着起 | 美国 Dower |
| Parameter term | Unit 🏹 | Interpretation and application | Model | Resolu tion | Initial value | Setting range |
| | | 三王章 | E CONTRACTOR | | Single-phase: 20 | Single-phase: 0~2 |
| DC limit enabling switch | 唐 明 WPDWER | The enabling button is only effective when the coupling mode is DC. After it is enabled, the maximum positive/negative DC current and the maximum positive and negative active power output by the product are limited to the settings. | ALL | ACTIONR | NUER | ١ |
| ACT | | | PRE2006S | | Three-phase/sp | Three-phase/split- |
| | | When the number of output phases is three-phase or split-phase, it indicates the maximum direct current output of each | PRE2007S | 0.01 | lit-phase: 30 Single-phase: 90 | hase: 0~30 Single-phase: 0~9 |
| Positive current | A | phase. When the number of output phases | PRE2009S | 0.01 | Three-phase/sp | Three-phase/split- |
| | | is single-phase, it indicates the maximum | PRE2012S | | lit-phase: 35 | hase: 0~35 |
| | | total positive output DC current. | PRE2015S | 4 | Single-phase: | Single-phase: |
| 2 | | | PRE2020S | | 105 | 0~105 |
| | | When the number of output phases is three-phase or split-phase, it indicates the minimum value of negative output DC | PRE2006S PRE2007S | | Three-phase separation: -30 Single phase: -90 | Three-phase/split- hase: -30~0 Single phase -90~0 |
| Negative current | A | current of each phase. When the number of output phases is single phase, it indicates | PRE2009S | 0.01 | Three-phase | Three/phase |
| | AL | the minimum value of total negative output | PRE2012S | | separation: -35 | separation: -35~0 |
| | | DC current. | PRE2015S | | Single phase: | Single phas |
| | | Be canona | PRE2020S | | -105 | -105~0 |
| | | When the number of output phases is three-phase or split-phase, it indicates the | PRE2006S | - I E | Three-phase/sp lit-phase: 2 Single-phase: 6 | Three-phase/split- hase: 0~2 Single-phase: 0~6 |
| Positive active | 12147 | maximum positive active power of each | | | Three-phase/sp | Three-phase/split- |
| power NPDWER | kW | phase. When the number of output phases | PRE2007S | 0.01 | lit-phase: 2.5 | hase: 0~2.5 |
| INFL | | is single-phase, it indicates the maximum | LACTOR S | | Single-phase: | Single-phase: |
| | | total positive active power. | | | 7.5 | 0~7.5 |
| | | ACTION POWER | PRE2009S | | Three-phase/sp | Three-phase/split- |
| | | STATISTICS NER | | | ACTIONIC | g |

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|--------------------------|-------------|--|----------|--------------------|--|---|
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| Parameter term | Unit 🏹 | Interpretation and application | Model | Resolu tion | Initial value | Setting range |
| | | 三利募 | | | lit-phase: 3 Single-phase: 9 | hase: 0~3 Single-phase: 0~9 |
| | | жастю прож | PRE2012S | 一一日日 | Three-phase/sp lit-phase: 4 Single-phase: 12 | Three-phase/split- hase: 0~4 Single-phase: 0~12 |
| X TEN | NPOWER | 一一道 | PRE2015S | ACTIONP | Three-phase/sp lit-phase: 5 Single-phase: 15 | Three-phase/split-p hase: 0~5 Single-phase: 0~1 |
| | | ※ ACTIONPOWER | PRE2020S | | Three-phase/sp lit-phase: 6.667 Single-phase: 20 | Three-phase/split-phase: 0~6.667 Single-phase: 0~20 |
| i. X | | ※ 着 | PRE2006S | | Three-phase/sp lit-phase: -2 Single-phase: -6 | Three-phase/split-p hase: -2~0 Single-phase: -6~0 |
| * | 一 ACTION | When the number of output phases is three-phase or split-phase, it indicates the | PRE2007S | X | Three-phase/sp lit-phase: -2.5 Single-phase: -7.5 | Three-phase/split- hase: -2.5~0 Single-phase: -7.5~0 |
| Negative active power | kW | minimum value of negative active power of each phase. When the number of output phases is single phase, it indicates the minimum value of total negative active | PRE2009S | 0.01 | Three-phase/sp lit-phase: -3 Single-phase: -9 | Three-phase/split-p hase: -3~0 Single-phase: -9~0 |
| NPOWER | | power. | PRE2012S | EIB OWER | Three-phase/sp lit-phase: -4 Single-phase: -12 | Three-phase/split-p hase: -4~0 Single-phase: -12~0 |
| | | 178 | PRE2015S | | Three-phase/sp lit-phase: -5 | Three-phase/split-p hase: -5~0 |
| | | ACTIONPOWER | | | ACTIONP | 98 |







| IDNPU | | | | | | |
|--|--------|--|----------|----------------|--|---|
| | | | | | * 言語 | FOWER |
| Parameter term | Unit 🏹 | Interpretation and application | Model | Resolu tion | Initial value | Setting range |
| | | 東部属 | | | Single-phase: -15 | Single-phase: -15~0 |
| | 寢圃 | ※着Hast | PRE2020S | 着利用 | Three-phase/sp lit-phase: -6.667 Single-phase: -20 | Three-phase/split-phase: -6.667~0 Single-phase: -20~0 |
| Internal resistance enabling switch | NPOWE | When enabled, a set impedance will be added to the output end of the product, which will reduce the output voltage. | ALL | ١ | ١ | |
| R | Ω | Built-in resistor. | ALL | 0.001 | 0 🐋 | 0~10 NPO |
| L | mH | Built-in inductance. Calculate the inductive reactance by $X=2\pi fL$. | ALL | 0.001 | 0 | 0~2 |
| Voltage slope | V/ms | A parameter that describes the output voltage in steady state, that is, the ratio of the increment of the valid value of the output voltage to time. | ALLOWER | 0.01 | 500 | 0.01~3000 |
| Frequency slope | Hz/ms | A parameter that describes the output frequency in steady state, that is, the ratio of output frequency increment to time. | ALL | 0.0001 | 2000 | 0.0001~2000 |
| Response rate | ACTIO | The response bandwidth of the system, users can choose different loudness speeds to adapt to the tested equipment. | ALL | 1 | Medium | 1 |
| Voltage slew rate | V/µs | The larger the parameter describing the output voltage transient, the shorter the response time to the set voltage. | ALL | 1 | 1 | 0.02~10 |
| Shutdown slew rate | V/µs | After disconnecting the output, the voltage at the output end drops by an instantaneous value every µs, and the voltage drop time can be controlled by setting the shutdown slew rate. | ALCTIONE | 0.001 | 2 | 0.002~10 |
| Starting angle | 0 | The output starts at the set angle. | ALL | 0.1 | 0 | 0~359.9 |
| | × | ACTIONPOWER | | | ACTIONP | 99 |
| | | | | | | |

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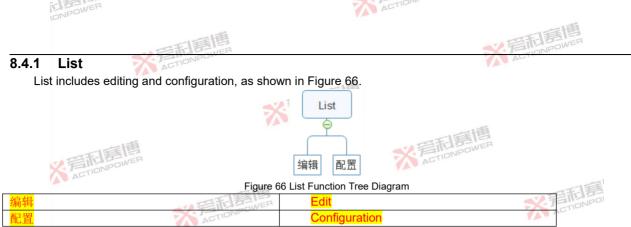
| | | 四和意思 | | | ~ 言形 | E |
|---|--------|---|-------|----------------|---------------|---------------|
| Parameter term | Unit 🏹 | Interpretation and application | Model | Resolu tion | Initial value | Setting range |
| Shutdown angle | • | The output ends at the set angle. | ALL | 0.1 | 0 | 0~359.9 |
| Transient angle enabling switch | 1 | When enabled, when the voltage or frequency is changed, the output will change synchronously according to the set transient angle. | ALL | ١ | | ١ |
| angle | ° | Transient angle. | ALL | 0.1 | OER | 0~359.9 |
| Impact current starting time | SOWER | Time from product output to measurement of impact current. | ALL 🏹 | 0.001 | 0 | 0~999.999 |
| Impact // current measuring time | s | Measuring time of impact current. | ALL | 0.001 | 0 | 0~999.999 |
| External synchronization delay time | S | Delay time of external synchronous phase input. It can realize multi-phase synchronous output of multiple products. | ALL | 0.001 | 0 | 0~999.999 |

Note: When paralleling, the relevant parameter settings of current and power need to be multiplied by the number of paralleling. 岩市は 局間 ACTIONPOWER

Programming 8.4

PRE20XXS series products are designed with five programming modes. Through flexible configuration parameters, the required waveform can be edited. See Figure 65 for programming functions. All programming modes must be used ACTION when the product has been exported.





Click Programming -List- Edit in the menu bar to enter the List programming interface, and you can set the list programming parameters yourself, as shown in Figure 67. See Table 14 for the definition of each parameter.

| | PI | RE | 纠 | 辑 | | 窗 | Sou | rce运 | 行 正弦波 | 三相 AC | TIDIS | | | 면류╓ ^{2022/9/2} 9:52:55 |
|----|--------------|-----|----|--------|----|--------|------|-------|----------|----------|-------|----|-------|------------------------------------|
| | \checkmark | No. | Φ1 | Uac[V] | Φ2 | Uac[V] | Φ3 U | ac[V] | Freq[Hz] | Dwell[s] | -3 | 导入 | 导出 | - 参数 |
| | > | | | 220.00 | | 220.00 | | | 50.000 | 1.0000 | | | | ···· → 编程 ^··· |
| 12 | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | ma na | List ^ |
| | | | | | | | | | | | | 加载 | 退出 | 1 编辑 |
| | | | | | | | | | | | | | | 1 配置 |
| | | | | | | | | | <i>.</i> | | | 肥 | 发 | 👫 Wave 🗸 |

Figure 67 List Programming Interface Diagram

Table 14 List Programming Interface Parameter Interpretation Table

| Parameter term | Unit | Interpretation | ACTIONPOWER | Model | Resolution | Setting range |
|-------------------|------|--|-------------|-------|------------|------------------|
| No. | 1 | Serial number. | | ALL | 1 | 1~300 |
| Uac[V] | V | Valid value of AC voltage of each phase. | | ALL | 0.01 | 0~450 |
| | | 公 言相意傳 | | XAC | TIONPOWE | 101 |





| DOWEN | 5- | | 21.0 | - | ~ |
|-------|----|----|------|----|----|
| 10000 | | 1- | -10 | | P4 |
| | 1. | | | 1. | |



| | | · 一下下下下下下下下下下下下下下下下下下下下下下下下下下下下下下下下下下下下 | *2.7 | 記寫傳 | 2 |
|-------------------|---------|--|-------|------------|------------------|
| Parameter term | Unit | Interpretation | Model | Resolution | Setting range |
| Freq[Hz] | Hz | Frequency of the output voltage. | ALL | 0.001 | 0.001~200 |
| Dwell[s] | S | The holding time of the current sequence. | ALL | 0.0001 | 0~999.9999 |
| <i>*</i> 3 | 1 | Clear all the current programming data and return to the initial programming state in Figure 67. | ALL | 1 | / |
| "+" | 1 | The current sequence inserts a set of new sequences backward, and the parameter values are the same as the current sequence. | ALL | 1 | / |
| "_" | =F | Delete the current sequence. | ALL | 1 | / |
| Export 🔀 | FIONPOL | Store the programmed waveform data into the interior product. | ALL | 1 | / |
| Import 🤼 | 1 | Import the stored waveform data into the current programming interface. | ALL | 1 | 1 |
| Loading | / | Lock the programming data and enter the state to be triggered. | ALL | | F |
| Exit | 1 | At any time when the programming mode is running, you can click "Exit" to end the current programming mode. | ALL | ACTIC | NPU |
| Triggering | / | From the stable output state to the programming waveform output state. | ALL | / | 1 |

Note: The expected output waveform is still limited by the value parameters, and improper limit setting may distort the expected output ACTIONPOWER waveform.

List programming example:

1) Press the output button on the front panel to let the product output a steady-state voltage. ACTIONPOWER

2) List programming data are shown in table 15.

Table 15 List Programming Data Sample Table

NPOWER

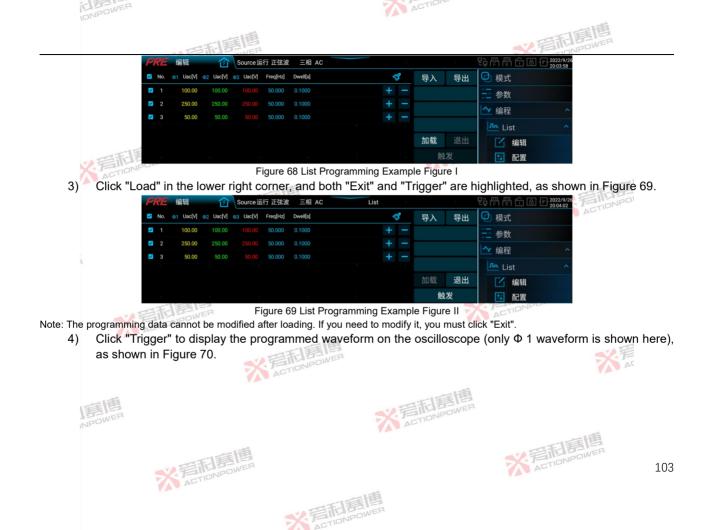
| Serial number Parameter term | No.1 | No.2 | No.3 |
|------------------------------|------------|------|------|
| Uac[V] | 100 | 250 | 50 |
| Freq[Hz] | 50 FIDNPOW | 50 | 50 |
| Dwell[s] | 0.1 | 0.1 | 0.1 |

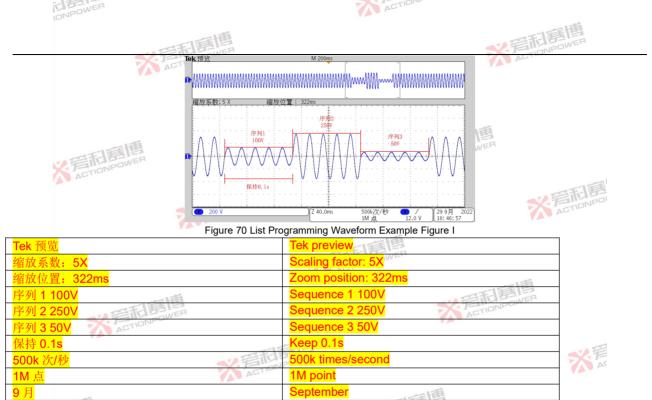
※言**訂意傳**

See Figure 68 for an example of List programming.

※ 着 前 意 個 ACTIONPOWER







Note:At any time when the programming mode is running, you can click "Exit" to end the current programming mode.

Click Programming -List- Configuration in the menu bar to enter the list mode configuration interface, as shown in Figure 71.

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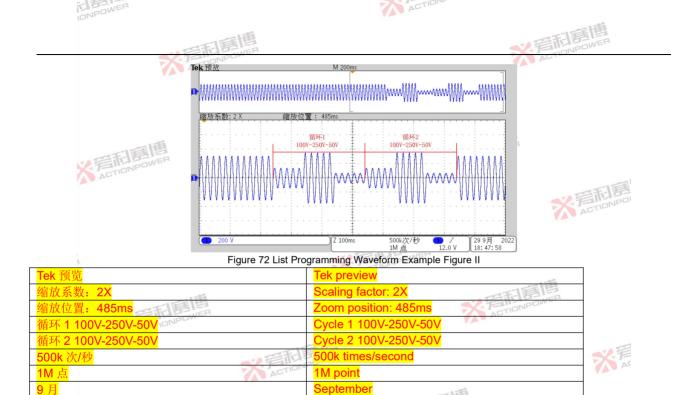
Figure 71 List Configuration Interface Diagram

The configuration interface can change the number of cycles of the programming waveform. If the number of cycles of the List programming waveform is set to 2, the programming waveform is shown in Figure 72.

※言記意傳







See Table 16 for parameter definitions in the configuration interface.

Table 16 List Configuration Interface Parameter Interpretation Table

| Parameter term | Unit | Interpretation and application | I | Model | Resolution | Setting range | |
|-------------------|------|--------------------------------|---|-------|------------|------------------|----|
| | | · 音和寫傳 | | X ACT | IONPOWER | 10 |)6 |









| IONE | | | | 175 | |
|---------------------|------|--|-------|-------------|------------------|
| | | 三和唐博 | N.F | 派語 傳 | |
| Parameter term | Unit | Interpretation and application | Model | Resolution | Setting range |
| Number of cycles | 1 | Setting the number of cycle outputs of the List programming waveform. The number of cycles of 0 indicates an infinite cycle. | ALL | 1 | 0~9999999 |
| Ending state | | Steady state: After programming, the output waveform returns to steady state. Hold: After programming, the output waveform is held in the last programming sequence. Standby: After programming, the output is disconnected and the output button turns green. | ALL | / | 1 |
| Continuous | 1 | After it is enabled, when the same programming data is triggered again, you don't need to click "Load", just click "Trigger". | ALL | 1 | 喜 |
| Trigger mode | / | Automatic: it is executed in sequence according to the programming order. Single shot: Only one sequence is executed at a time. | ALL | ACTIO | NPOI |
| Trigger input | 1 | Internal: Click "Trigger" manually on the display screen or send a trigger instruction through the communication interface to realize internal trigger. External: send a trigger signal to it through Anyport digital input interface to realize external trigger. See Section 8.14.1 for details. | ALL | 1 | 1 |
| Trigger delay | s | Press "Trigger" and wait for the set trigger delay before executing the programming sequence. | ALL | | 0~999.999 |
| Trigger output | | After the trigger function is set in the Anyport digital output interface, the product will send out a pulse indication signal at the Anyport digital output port when outputting the programming waveform. This operation needs to enable the trigger function in the Anyport digital output configuration interface. See Section 8.14.1 for details. See Figure 73 for the schematic diagram of pulse output waveform. One-time: Only when the programming starts to be executed, the pulse indication signal is output. Single step: when each sequence is executed, a pulse indication signal is issued. Single cycle: send out pulse indication signal at the beginning of each | ALL | , 🐔 | AC AC |
| Valid value | 1 | cycle. Automatic: When the programming waveforms of all sequences in the | ALL | | |
| | , ' | | | TONPOWER | 10 |

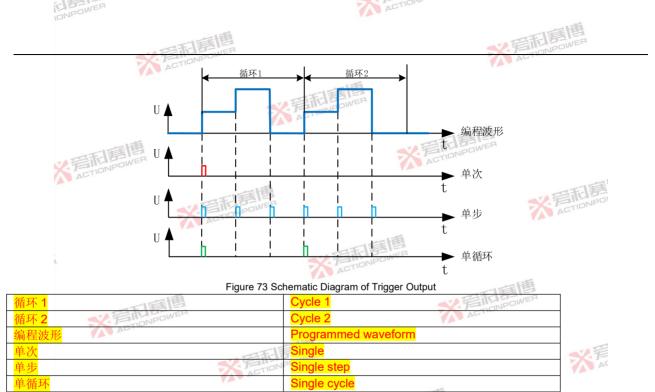








| IONF | | | | | | |
|----------------|------|---|----------|------------|------------------|--|
| | | | | 新記 第個 | L | |
| arameter rm | Unit | Interpretation and application | Model | Resolution | Setting range | |
| ode | 音利言 | programming data are sine waves, clipping wave and built-in harmonics, the valid value mode is automatically enabled, and the output voltage value is closed-loop, and the output voltage value is automatically adjusted to be consistent with the set value. Otherwise, the valid value mode is automatically disabled, and the output voltage value is open-loop. Enabled: Forced closed loop. Forbidden: Forced open loop. | 書 | | | |
| | AC. | ※ 言和 ETIONPOWER | | X ACTIO | 15 NPD | |
| 2 | | ※言形 唐博 ACTIONPOWER | | | | |
| | ※言 | 記憶 CTIONPOWER STIONPOWER | STIONPOV | VER | | |
| | | ※ 着市 IEIEIEIEI ACTIONPOWER | | Ž | 子 AC | |
| IR. | WER | ※ STIDNPOWER | | | | |
| | | ※完TIONPOWER | 彩音 | 利嘉博 | 10 | |
| | | 来 一 石 TIONPOWER | | | | |



The configured List programming waveform data can be stored in the product interior or in an external USB storage device, which is convenient for direct calling next time, so as to reduce the repeated configuration operation of users. See Section 8.11.5 for details.

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List programming waveform data is stored in internal storage as follows:





| IDNPOWER | | | ACTION | | | | | | | |
|----------|-------|------|----------|-----------|----------|--------|----|------|-------|--|
| | | | :1算 | 唐 | | | | | | * 言相言傳 |
| | PRE # | | | Source 待相 | ᄳᆴᆇᆁ | * =# | 40 | | | こ こ こ の で し の の で の の の の の の の の の の の の の |
| | List | 8744 | <u>ن</u> | Source | /11134/0 | K —118 | AC | | | M 间谐波 |
| | Q | w | E R | ۲ (| - | Y | U | 1 | 0 Р | |
| | Α | s | D | F | G | Н | J | к | | |
| -15 | ¢ | Z | x | С | v | В | N | м | | |
| ACTION | ? | 123 | | | | | | Back | Enter | |

- Figure 74 Waveform Export Interface Diagram
- 2) Enter the name of the saved file in the keyboard area, and click "Enter" to finish saving.
- 電利息 3) Return to the List programming interface, click "Import", select the saved file (suffix:. List) in Figure 75, and click "OK" to import the saved waveform data into the list programming interface.

| PRE | 编辑 | 畲 | Source待机 正弦 | 波 三相 AC | | | 2022 | 2/9/26 6:10 |
|------|-------|---|-------------|----------------|--------|----|------------|----------------|
| Name | | | | Time | | | ೂ 间谐波 | ~ |
| List | .list | | | 2022-09-26 11: | :05:57 | | 🔽 限值 | |
| | | | | | | | 🛈 保护 | |
| | | | | | | | \Lambda 事件 | |
| ×. | | | | | | 确认 | 通讯 | |
| | | | | | | 返回 | 💾 存储 | ~ |

Figure 75 Waveform File Selection Interface ACTIONPON

* STIDNPOWER

8.4.2 Wave

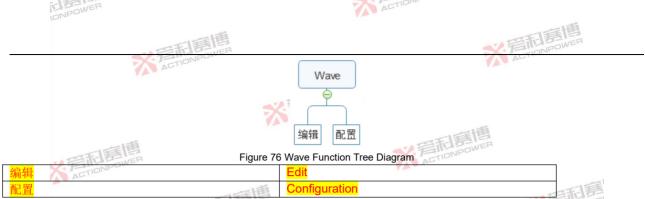
NPOWE

7

Wave includes editing and configuration, as shown in Figure 76. ACTIONPOWER







Click Programming -Wave- Edit in the menu bar to enter the Wave programming interface, where you can set the wave programming parameters yourself, as shown in Figure 77. See Table 17 for the definition of each parameter.

| FRE # | 扁辑 | 俞 | Source运 | 行 正弦波 | 三相 AC | | | | ₽;₩₩₩ ₽;₩₩ 2022/ 20:05 |
|----------|---------------------|--------|----------|----------|---------|-----|----|----|---------------------------------|
| 🗹 No. φ1 | Uac[V] 0 2 U | Jac[V] | 3 Uac[V] | Freq[Hz] | Ramp[s] | | 导入 | 导出 | 参数 |
| ☑ 1 | 220.00 2 | 20.00 | 220.00 | 50.000 | 1.0000 | + - | | | 编程 |
| | | | | | | | | | List |
| | | | | | | | | | 🚾 Wave |
| 111 | | | | | | | 加载 | 退出 | ☑ 编辑 |
| | | | | | | | | 蚀发 | 1 配置 |

Figure 77 Wave Programming Interface Diagram Table 17 Interpretation Table of Wave Programming Interface Parameters



| Llnit | | Model | Resolution | Setting |
|-------|--|--|--|---|
| Onic | | Woder | Resolution | range |
| L | Serial number. | ALL | 1 | 1~300 |
| V | Valid value of AC voltage of each phase. | ALL | 0.01 | 0~450 |
| Hz | Frequency of the output voltage. | ALL | 0.001 | 0.001~200 |
| s | Variation time of voltage values between adjacent sequences. | ALL | 0.0001 | 0~999.9999 |
| / | Clear all the current programming data and return to the initial programming | ALL | 1 BUNER | 1 |
| | TETE BUER | 20 401 | TIONPE | 112 |
| | | / Serial number. V Valid value of AC voltage of each phase. Hz Frequency of the output voltage. s Variation time of voltage values between adjacent sequences. | / Serial number. ALL V Valid value of AC voltage of each phase. ALL Hz Frequency of the output voltage. ALL s Variation time of voltage values between adjacent sequences. ALL | / Serial number. ALL / V Valid value of AC voltage of each phase. ALL 0.01 Hz Frequency of the output voltage. ALL 0.001 s Variation time of voltage values between adjacent sequences. ALL 0.001 |

* STONPOWE









| | | · 平和意思 | ~?? | < ≫ 言記 島間 B NPOWER B NPOWER | | | | |
|-------------------|--------|--|-------|--|------------------|--|--|--|
| Parameter term | Unit | Interpretation | Model | Resolution | Setting range | | | |
| | | state in Figure 77. | | | | | | |
| "+" | 1 | The current sequence inserts a set of new sequences backward, and the parameter values are the same as the current sequence. | ALL | / | 1 | | | |
| "_" | 1 | Delete the current sequence. | ALL | 1 | 1 | | | |
| Export | 1 | Store the programmed waveform data into the interior product. | ALL | 1 | 1 | | | |
| Import | 1-1-1 | Import the stored waveform data into the current programming interface. | ALL | 1 | 1 | | | |
| Loading | | Lock the programming data and enter the state to be triggered. | ALL | 1 | 1 | | | |
| Exit | AGTION | At any time when the programming mode is running, you can click "Exit" to end the current programming mode. | ALL | 1 | | | | |
| Triggering | 1 | From the stable output state to the programming waveform output state. | ALL | | 50 | | | |

Note: The expected output waveform is still limited by the value parameters, and improper limit setting may distort the expected output waveform.

Wave programming example:

- Press the output button on the front panel to let the product output a steady-state voltage. 1) ACTIO
- 2) See Table 18 for Wave programming data.

Table 18 Sample Table of Wave Programming Data

| Serial number Parameter term | No.1 | No.2 | No.3/EP |
|---------------------------------|----------------------------|------|---------|
| Uac[V] | 100 | 250 | 50 |
| Freq[Hz] | 50 | 50 | 50 |
| Ramp[s] | 0.1 | 0.1 | 0.1 |
| See Figure 78 for an exa | ample of Wave programming. | | AC |

※言相意傳

See Figure 78 for an example of Wave programming. A ACT

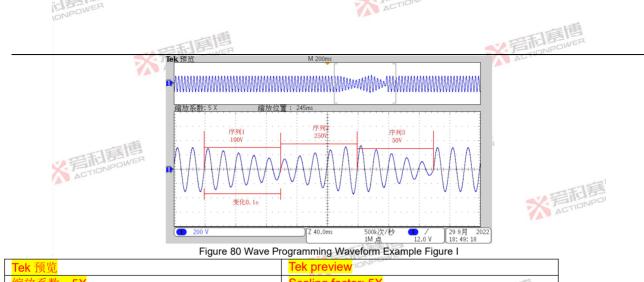








| IDNPOWER | | | | | | | 7 | A | CTION | 5 × | | | |
|----------------------------|-------------|--------|-----------|----------|----------|------------|----------------|-----|---------|-----------|--|---------------|--------|
| IDIa. | | 彩 | 朝 | | | | | | | | 秋 着雨 | 語個 | |
| PRE | 编辑 | | Source运 | 行 正弦波 | 三相 AC | | | | | | ₽₽ 骨 骨 合 圖 단 2022/9/26 20:06:40 | | |
| Mo. | ⊕1 Uac[V] d | Uac[V] | ⊕3 Uac[V] | Freq[Hz] | Ramp[s] | | 1 | 3 | 导入 | 导出 | <u>-</u> 参数 | | |
| Z 1 | 100.00 | 100.00 | | 50.000 | 0.1000 | | | | | | └☆ 编程 へ | | |
| ☑ 2 | 250.00 | 250.00 | | 50.000 | | | | | | | 📠 List 👻 | | |
| Z 3 | 50.00 | 50.00 | | 50.000 | 0.1000 | | + | | | | 🚾 Wave 🔷 🔨 | | |
| | | | | | | | | | 加载 | 退出 | □ 编辑 | | |
| -1- | | | | | | | | | 触 | | 1 配置 | | |
| X FILE | 4 | | Fic | illire 7 | 8 Wave P | rogrammin | a Ex | amr | | A 5 - 1 - | | | |
| 3) Click "Load" in | n the Ic | wer ri | | | | | | | | | ighlighted, as sho | wn in Figure | 79 |
| | | | igni o | | , and be | | una | | 9901 | uror | ngringritoù, uo orio | 175 1 2 2 2 3 | 10. |
| PRE | 编辑 | | Source运 | 行 正弦波 | 三相 AC | Way | ve | | | | という 日間での 2022/9/26 2022/9/26 2020/9/26 | ACTIONPO | |
| No. | ↓1 Uac[V] | Uac[V] | 03 Uac[V] | Freq[Hz] | Ramp[s] | | ~ | 3 | 导入 | 导出 | <u>-</u> 参数 | - A- | |
| ☑ 1 | 100.00 | 100.00 | | 50.000 | 0.1000 | | | | | | └── 编程 ^ | | |
| 2 | 250.00 | 250.00 | | 50.000 | 0.1000 | | | | | | 📠 List 🗸 🗸 | | |
| 2 3 | 50.00 | 50.00 | | 50.000 | | | | | | | Wave ^ | | |
| | | | | | | | | | | NB (I) | | | |
| | | | | | | | | | 加载 | 退出 | 1 配置 | | |
| | 121- | | | | | | _ | | 触 | | | | |
| ~ 言語 | NPOWE | R | | | | rogramming | | | | | ACTION | | |
| Note: The programming data | | | | | | | | | | | | | |
| , | | | ne pro | ograr | nmed w | aveform | on t | ne | OSCIIIC | scope | e (only Φ 1 wavefo | orm is snown | nere), |
| as shown in F | igure 8 | 30. | ~ | 言 | ICI DOW | ER | | | | | | A | |
| | | | 1 | AC | FE SON | | | | | | | VA - | |
| | | | | | | | | | | -16 | | | |
| 属 | | | | | | | - | | 利害 | E B | | | |
| NPOWER | | | | | | 1 | × | F | TIONP | CIV. | | | |
| More. | | | | | | | | | | | | -15 | |
| | | | 135 | | | | | | | | ※ 言語 ACTION | 書 | |
| | 爱新 | 語 | | | | | | | | | STION! | | 114 |
| S | 一一 | ONPO | VV L | | | | | | | | | | 114 |
| | AC | | | | | | | | | | | | |
| | | | | | 5.00 | E E | AR | | | | | | |
| | | | | 4 | 义百 | TONPOWE | 5 ¹ | | | | | | |
| | | | | | AL | | | | | | | | |



| Tek 预览 | Tek preview CONPE | |
|------------------------|--------------------------|----|
| 缩放系数:5X | Scaling factor: 5X | |
| 缩放位置: 245ms | Zoom position: 245ms | |
| 序列 1 100V 序列 2 250V | Sequence 1 100V | |
| 序列 2 250V | Sequence 2 250V | |
| 序列 3 50V | Sequence 3 50V | |
| 保持 0.1s | P <mark>Keep 0.1s</mark> | AC |
| 500k 次/秒 | 500k times/second | |
| <mark>1M 点</mark> | 1M point | |
| 9月 15日 16日 | September 2 FILD POWER | |

Note:At any time when the programming mode is running, you can click "Exit" to end the current programming mode.

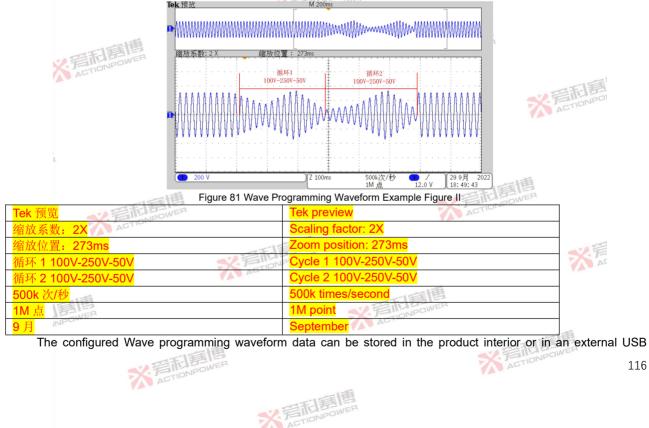
ACTIONPOWER Click Programming -Wave- Configuration in the menu bar to enter the Wave mode configuration interface. The







parameters and functions of the Wave configuration interface are the same as those of the List mode configuration interface, as shown in Figure 71. Set the cycle number of Wave programming waveform to 2 in the configuration interface, and the programming waveform is shown in Figure 81.





storage device, which is convenient for direct calling next time, so as to reduce the repeated configuration operation of users. See Section 8.11.5 for details.

The specific method of storing Wave programming waveform data into the product interior can refer to the storage method of List programming.

8.4.3 Step

 Step includes editing and configuration, as shown in Figure 82.

 Step

 Step

 编辑<</td>

 Figure 82 Step Function Tree Diagram

 編輯

 Edit

 Configuration

Click Programming -Step- Edit in the menu bar to enter the Step programming interface, and you can set the Step programming parameters yourself, as shown in Figure 83. See Table 19 for the definition of each parameter.



| DIPOWER | 5-1 | 11 | 21 | - | 2 |
|---------|-----|----|-----|---|----|
| DNPL | 12 | - | 714 | | ÷. |
| | .08 | | 0- | | |

| V J | TION | |
|-----|------|--|
| | AL | |
| V | | |



| Table 19 Interpretation | Table of Step Pro | ogramming Interfac | e Parameters |
|-------------------------|-------------------|--------------------|--------------|
| | | | |

| Parameter term | Unit | Interpretation | Model | Resolution | Setting range |
|----------------|-------|--|---------|------------|------------------|
| Waveform | / | Waveform. | ALL | / | 1 |
| Phase[°] | 0 | Phase. | ALL | 0.1 | 0~359.9 |
| Percent[%] | / | Percentage of waveform. | ALL | 0.01 | 0~100 |
| Uac[V]Start | V | Valid value of initial voltage. | ALL | 0.01 | 0~450 |
| Uac[V]End | V | Valid value of ending voltage. | MAEL | 0.01 | 0~450 |
| Uac[V]A | VOWER | Voltage variation. | ALL | 0.01 | 0~450 |
| Freq[Hz]Start | Hz | Starting voltage frequency. | ALL | 0.001 | 0.001~200 |
| Freq[Hz]End | Hz | Ending voltage frequency. | ALL | 0.001 | 0.001~200 |
| Freq[Hz]∆ | Hz | Frequency variation. | ALL | 0.001 | 0.001~200 |
| Degree[°] | 0 | Trigger angle. | ALL | 0.1 ACTIO | 0~359.9 |
| Time[s] | S | The holding time of each step. | ALL | 0.0001 | 0~999.9999 |
| Export | / | Store the programmed waveform data into the interior product. | ALL | / | / |
| Import | 1 | Import the stored waveform data into the current programming interface. | ALL | / | / |
| Loading | / | Lock the programming data and enter the state to be triggered. | ALL | / | / |
| Exit | 1 | At any time when the programming mode is running, you can click "Exit" to end the current programming mode. | ALL | | 1 |
| Triggering | 目形 | From the stable output state to the programmed waveform output state. | ALLIPOW | 1 | 1 |

Note: The expected output waveform is still limited by the value parameters, and improper limit setting may distort the expected output waveform.

Step programming example:



- Press the output button on the front panel to let the product output a steady-state voltage. 1)
- See Table 20 for Step programming data. 2)

Table 20 Example Table of Step Programming Data

| Parameter term | Settings | Parameter term | Settings | |
|----------------|------------|----------------|--------------|-----|
| Uac[V]Start | 100 | Freq[Hz]End | 50 | |
| Uac[V]End | 300 | Freq[Hz]∆ | 0 | |
| Uac[V]∆ | 100 | Degree[°] | 0 TILL DOWER | |
| | V STABOWER | | ACTION | 118 |

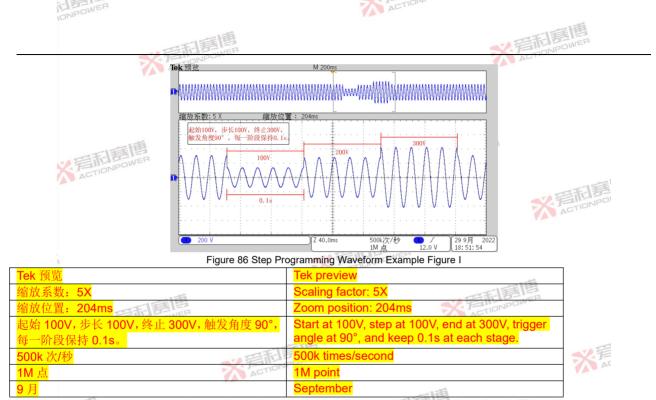
TELE









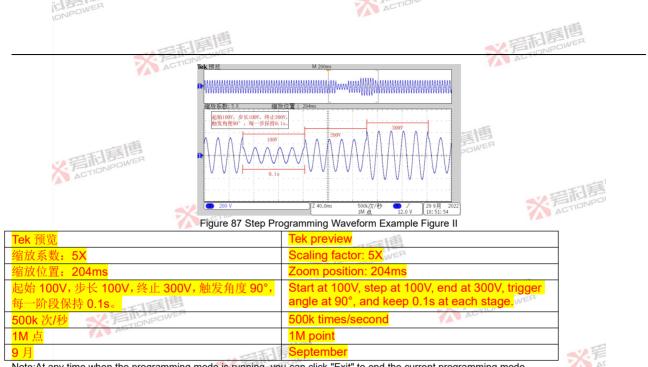


Keep other parameters unchanged, set the trigger angle Degree to 90°, click "Load" and "Trigger", and display the waveform with trigger angle of 90° on the oscilloscope (only Φ 1 waveform is shown here), as shown in Figure 87.

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Note:At any time when the programming mode is running, you can click "Exit" to end the current programming mode.

Click Programming -Step- Configuration in the menu bar to enter the Step mode configuration interface. The parameters and functions of the Step configuration interface are the same as those of the List mode configuration interface, as shown in Figure 71. Set the cycle number of Step programming waveform to 2 in the configuration interface, and the programming waveform is shown in Figure 88.

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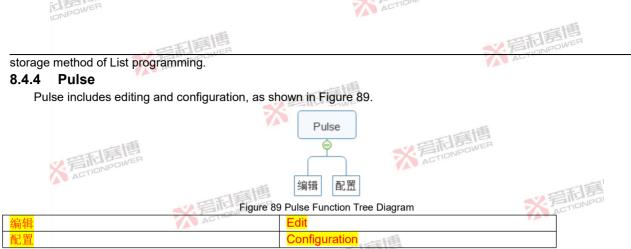




The configured Step programming waveform data can be stored in the product interior or in an external USB storage device, which is convenient for direct calling next time, so as to reduce the repeated configuration operation of users. See Section 8.11.5 for details.

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For the specific method of storing the waveform data of Step programming in the product interior, please refer to the ACTIONPOWER ACTION



Click Programming -Pulse- Edit in the menu bar to enter the Pulse programming interface, where you can set the Pulse programming parameters yourself, as shown in Figure 90. See Table 21 for the definition of each parameter.

| 01 | | | | | | Y | | | | |
|----------------------|----------|----------|------------|--------|----------|-----------|----|----|---------|---------|
| PRE | 编辑 | 一台 | Source运行 | 〒 正弦波 | 三相 AC | | | | | 2022/9/ |
| | Waveform | Phase[*] | Percent[%] | Uac[V] | Freq[Hz] | | 导入 | 导出 | | |
| φ1 | 正弦波 | 0.0 | 50.00 | 220.00 | 50.000 | Width[s] | | | Wave | |
| 基 @2 | | | | | | | | | 🚅 Step | |
| Φ3 | | | | | | Period[s] | | | M Pulse | |
| Φ1 | 正弦波 | 0.0 | | 10.00 | | | | | 1 编辑 | |
| 脉 冲 ⁰² | | | | | | Degree[*] | 加载 | | 1 配置 | |
| Φ3 | 正弦波 | 120.0 | 50.00 | 10.00 | 10 | 0.0 | 触 | 发 | | |

Figure 90 Pulse Programming Interface Diagram

Table 21 Interpretation Table of Pulse Programming Interface Parameters

| Parameter POW term | Unit | Interpretation | N | /lodel | Resolution | Setting range |
|-----------------------|------|---|---|--------|------------|---------------|
| Fundamental | / | Steady-state waveform programmed by the user. | A | ALL | 1 | EB |
| | | N STATISTICS | | 7 | ACTIONPO | 124 |









| | | | | 2 言形 | 其 四 POWER |
|-------------------|--------|--|--------|------------|---|
| Parameter term | Unit | Interpretation | Model | Resolution | Setting range |
| wave | | 一個 | | | |
| Pulse | / | Replace a section of waveform in the fundamental wave. | ALL | 1 | 1 |
| Waveform | / | Waveform. | ALL | 1 | 1 |
| Phase[°] | 0 | Phase. | ALL | 0.1 | 0~359.9 |
| Percent[%] | / | Percentage of waveform. | ALL | 0.01 | 0~100 |
| Uac[V] | V | Valid value of AC voltage of each phase. | ALLWEI | a / | 0~450 |
| Freq[Hz] | HZNPOW | Frequency of the output voltage. | ALL | 0.001 | Fundamental wave: 0.001~200 Pulse: 0.001~2000 |
| Width[s] | S | Pulse width. | ALL | 0.0001 | 0~999.9999 |
| Period[s] | S | Fundamental period. | ALL | 0.0001 | 0~999.9999 |
| Degree[°] | 0 | Trigger angle. Action | ALL | 0.1 | 0~359.9 |
| Export | / | Store the programmed waveform data into the interior product. | ALL | 1 | 1 |
| Import | 1 | Import the stored waveform data into the current programming interface. | ALL | / | 1 |
| Loading | / | Lock the programming data and enter the state to be triggered. | ALL | 1 | 1 |
| Exit | 1 | At any time when the programming mode is running, you can click "Exit" to end the current programming mode. | ALL | 自由 | 1 |
| Triggering | 1 | From the stable output state to the programming waveform output state. | ALL | POWER | 1 |

Note: The expected output waveform is still limited by the value parameters, and improper limit setting may distort the expected output waveform.

Pulse programming example:

- Press the output button on the front panel to let the product output a steady-state voltage. 1)

2) See Table 22 for Pulse programming data.

Table 22 Sample Table of Pulse Programming Data

| Category Parameter term | Fundamental wave | Pulse ACTIONPOWER | Others | |
|----------------------------|------------------|-------------------|-----------|-----|
| Uac[V] | 220 | 20 | / | |
| Freq[Hz] | 50 | 1000 | I STATER | |
| * | STATE OWER | 7 | ACTIONPOR | 125 |

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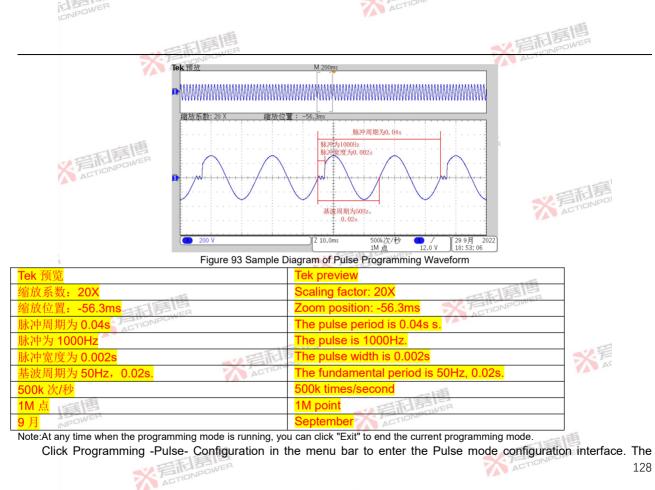
工道



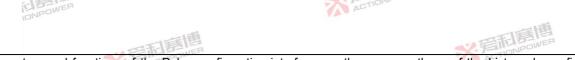




| IONPOWER | | | | | ACTION | | |
|------------------------------|------------------------|---|--------------|-----------|-----------------------|---------------------|--|
| | 四形唐 | | | | | | E DE |
| 5 | - TETIONPI | June: | | | | ACTIO | |
| PRE | 编辑 🕜 | Source运行 正弦波 | 三相 AC | | | 段骨骨合圈 仔2022/10/21 | |
| | Waveform Phase[*] | Percent[%] Uac[V] | Freq[Hz] | | 导入 导出 | List Y | |
| Ø1 | 正弦波 0.0 | 50.00 220.00 | | Width[s] | | 💆 Wave 💙 | |
| 基 波 ^{中2} | 正弦波 240.0 | 50.00 220.00 | | | | 🖃 Step | |
| Φ3 | 正弦波 120.0 | 50.00 220.00 | | Period[s] | | Pulse ^ | |
| Ф1 В¥ | 正弦波 0.0 | 50.00 20.00 | | 0.0400 | 加载 退出 | | |
| ₩ ⁰² | 正弦波 240.0 正弦波 120.0 | | | Degree[*] | 触发 | 日間 | |
| ACTIONE | 120.0 | Eiguro 01 | Pulse Progra | | | | |
| 2) Click "Lood" in | the lower ri | | | | | ighlighted as sho | up in Figure 02 |
| 3) Click "Load" in | | The second se | -0 | | ngger are n | ighlighted, as show | ACTION FIGURE 92. |
| PRE | | Source运行 正弦波 | 三相 AC | Pulse | | 日常常合合で2022/9/26 | ACT |
| | | Percent[%] Uac[V] | Freq[Hz] | | 导入 导出 | Wave Y | |
| ф1 # | 正弦波 0.0 | 50.00 220.00 | | Width[s] | | 🛃 Step 👻 | |
| 基 波 ⁴ 2 | 正弦波 240.0 | 50.00 220.00 | | | | M Pulse ^ | |
| Φ3 Φ1 | 正弦波 120.0 正弦波 0.0 | 50.00 220.00 50.00 20.00 | 1000.000 | Period[s] | | └ 编辑 | |
| () 脉 | 正弦波 240.0 | 50.00 20.00 | | | 加载 退出 | 1 配置 | |
| 并 | 正弦波 240.0 | | | Degree[*] | 触发 | Advanced Y | |
| | VPOWER | Eiguro 02 | Pulso Progra | | ole Figure II 🕖 | | |
| Note: The programming data c | annot be mod | | | | | | |
| | | | | | | | rm is shown here), |
| , | | le program | imed waver | | oscilloscope | | |
| as shown in Fig | gure 93. | X AGT | ONPOWER | | | | AC |
| | | | | | | | |
| 156 | | | | | 記 意 也 NPOWER | | |
| 唐唱 | | | | VE | THER | | |
| NPOWER | | | | A | STIDIC | | |
| | | | | | | | 王恒 |
| | | 画 | | | | ※ 着 TIONE | DWER |
| | 雪利昂 | NER | | | | ACTION | 127 |
| | STIDNPOL | | | | | | |
| | | | | 利用 | | | |
| | | | X 号利语 | BIER | | | |
| | | | ACTIONE | | | | |



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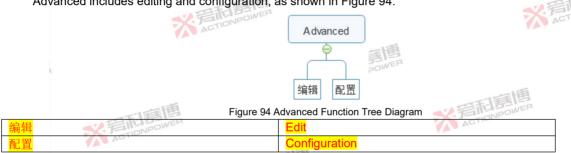
parameters and functions of the Pulse configuration interface are the same as those of the List mode configuration interface, as shown in Figure 71.

The configured Pulse programming waveform data can be stored in the product interior or in an external USB storage device, which is convenient for direct calling next time, so as to reduce the repeated configuration operation of users See Section 8 11 5 for details

The specific method of storing Pulse programming waveform data into the product interior can refer to the storage AGTIO method of List programming.

8.4.5 Advanced

Advanced includes editing and configuration, as shown in Figure 94.



Click Programming -Advanced- Editing in the menu bar to enter the Advanced programming interface, where you can set advanced programming parameters by yourself. Slide left and right in the interface to see the complete programming parameters, as shown in Figure 95 and Figure 96. See Table 23 for the definition of each parameter.





| Table 23 Interpretation Table of Advanced Programming Interface Parameters | 3 |
|--|---|
|--|---|

| Parameter term | Unit Act | Interpretation | Model | Resolution | Setting range |
|-------------------|----------|---|-------|------------|------------------|
| No. | / | Serial number. | ALL | 1 | 1~300 |
| Waveform | / | Waveform. | ALL | 1 🔊 | |
| Phase[°] | 0 | Phase. | ALL | 0.1 🏹 | 0~359.9 |
| Percent[%] | / | Percentage of waveform. | ALL | 0.01 | 0~100 |
| Uac[V] | V | Valid value of AC voltage of each phase. | ALL | 0.01 | 0~450 |
| Freq[Hz] | Hz | Frequency of the output voltage. | ALL | 0.001 | 0.001~200 |
| Ramp[s] | S | Change time between adjacent sequences. | ALL | 0.0001 | 0~999.9999 |
| Dwell[s] | S | The holding time of the current sequence. | ALL | 0.0001 | 0~999.9999 |
| Link | / | After the current sequence is executed, jump to the specified sequence, | ALL | 力重要 | 0~300 |
| | | ※ 言 和 意 個 | XA | TIONPOWER | 130 |

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| | | | 公 司 | 新 記 DNPOWER | a |
|-------------------|----------|--|------------|-------------------|------------------|
| Parameter term | Unit | Interpretation | Model | Resolution | Setting range |
| | | and the rule is "current serial number -Link value = jump to serial number". If the Link of sequence 3 is set to 2 (at this time, the Count must be set to a value ≥1, otherwise the function of Link will be invalid), then after executing sequence 3, jump to sequence 1. | 目间 | | |
| Count | STIDNPOW | Used in conjunction with Link, it indicates the number of cycles to jump from the current sequence to the specified sequence. If the Link of sequence 3 is set to 1 and the Count is set to 2, after executing sequence 3, jump to sequence 2, execute sequence 3 in sequence, and then jump to sequence 2 to complete two cycles. | ALL | /0 | 0~9999999 |
| Degree[°] | 0 | Starting angle, and enabling is effective. | ALL | 0.1 | 0~359.9 |
| Trig In | 1 | When prohibited, it shall be executed in sequence according to the serial number. When enabled, the trigger mode in the "Configuration" interface must be set to automatic, and the enabling sequence shall be executed by using internal trigger or external trigger. | ALL | I | 1 |
| Trig Out | 1 | When enabled, the trigger output in the "Configuration" interface must be set to single step, and a single-step pulse indication signal can be sent out in the Anyport digital output interface. This operation needs to enable the Anyport digital output interface and select the trigger function. See Section 8,14.1 for details. | ALL | EA IER | 1 |
| <i>3</i> | TX ACT | Clear all the current programming data, and return to the initial programming state of Figure 95 and Figure 96. | ALL | / | 1 |
| '+" | 1 | The current sequence inserts a set of new sequences backward, and the parameter values are the same as the current sequence. | ALL | 1 | F |
| '_" | / | Delete the current sequence | ALL | 1 | V AC |
| Export | 1 | Store the programmed waveform data into the interior product. | ALL | 1 | 1 |
| mport | 1 | Import the stored waveform data into the current programming interface. | ALL | 1 | 1 |
| Loading | 11 | Lock the programming data and enter the state to be triggered. | ALL | 1 | 1 |
| Exit | NEP | At any time when the programming mode is running, you can click "Exit" to end the current programming mode. | ALL | 1 | / |
| Triggering | / | From the stable output state to the programming waveform output state. | ALL | 1 | / |

Note: The expected output waveform is still limited by the value parameters, and improper limit setting may distort the expected output

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waveform

Advanved programming example:

- Press the output button on the front panel to let the product output a steady-state voltage. 1) ACTIONPOWE
- See Table 24 for Pulse programming data. 2)

Table 24 Example Table of Advanced Programming Data

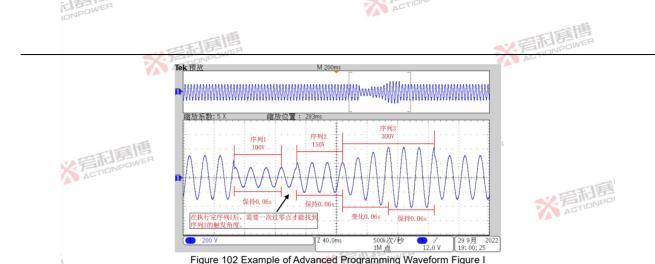
| Serial number Parameter term | No.1 | No.2 | No.3 |
|---------------------------------|-------------|--------------|------------|
| Uac[V] | 50 | 150 ACTIONIC | 300 |
| Freq[Hz] | 50 | 50 | 50 |
| Ramp[s] | 0 | 0 | 0.06 |
| Dwell[s] | 0.06 | 0.06 | 0.06 |
| Link | 0 DIPOWER | 0 | 1 ACTION |
| Count | 0 ACTIO | 0 | 1 |
| Degree[°] | Enabled, 60 | Enabled, 90 | Prohibited |
| Trig In | Prohibited | Prohibited | Prohibited |
| Trig Out | Enabling | Enabling | Enabling |

See Figure 97 to Figure 100 for an example of Advanced programming.













| INPOWER | | ACTION | |
|-----------------------|-------------|-------------------|---------|
| | 一百萬博 | | w 雪雨夏博 |
| <mark>2 的触发角度。</mark> | ACTIONPOWER | | AUTIONI |
| <mark>500k 次/秒</mark> | | 500k times/second | |
| <mark>1M 点</mark> | | 1M point | |
| <mark>9月</mark> | | September | |

Note:At any time when the programming mode is running, you can click "Exit" to end the current programming mode.

Keep other parameters unchanged, set all Link and Count of Sequence 3 to 1, click "Load" and click "Trigger", and the waveform displayed on the oscilloscope (only Φ 1 waveform is shown here) is shown in Figure 103.









| IDNPD | WER | ACTION | |
|-------------------|----------|-----------|-------------|
| | | | 一口調團 |
| | 三市語 | | N BILD OWER |
| <mark>1M 点</mark> | ACTIONPO | 1M point | AL |
| <mark>9月</mark> | | September | |

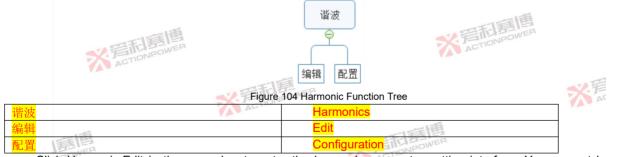
Click Programming-Advanced-Configuration in the menu bar to enter the Advanced mode configuration interface. The parameters and functions of the Advanced configuration interface are the same as those of the List mode configuration interface, as shown in Figure 71.

The configured Advanced programming waveform data can be stored inside the product or to an external USB storage device to facilitate direct call next time to reduce the repeated configuration operation of the user. See Section 8.11.5 for details

For the specific method of storing waveform data of Advanced Programming into the product, please refer to the ACTIONP ACTIONPOWER storage method of List Programming.

8.5 Harmonics

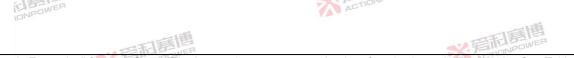
Harmonic includes editing and configuration, as shown in Figure 104.



Click Harmonic-Edit in the menu bar to enter the harmonic parameter setting interface. You can set harmonic parameters and output them yourself, or output 30 kinds of harmonics built in the product. See "Appendix-Built-in ACTIONPOWE







Harmonic Examples" for waveforms. The harmonic parameter setting interface is shown in Figure 105. See Table 25 for the explanation of each parameter. -

| PRE | 编辑 | 企 | Source运行 | 〒 正弦波 | 三相 AC | | | | | 란ሞ | R 🔂 🙆 (| F 2022/9/26 20:32:55 |
|--------|----------|-------------|----------|------------|------------|----------|-----------|----------|---------|------------|----------|-------------------------|
| No. | Value[%] | Phase[*] @2 | Value[%] | Phase[°] 🚓 | 3 Value[%] | Phase[*] | | 导入 | 导出 | 1 | Step | |
| 2 | 0.00 | 0.0 | 0.00 | 0.0 | | | | D | ST | M | Pulse | |
| 3 | 0.00 | 0.0 | 0.00 | | | | | 预 | 迈 | ~ V | Advanced | |
| 4 | 0.00 | 0.0 | | | | | | | 波形 | る。 | 法 | |
| 5 6 | 0.00 | 0.0 | 0.00 | | | | | _ | | | | |
| 6 | 0.00 | 0.0 | | | | | | 加载 | 退出 | | 编辑 | |
| 7 | 0.00 | 0.0 | | | | | | 触发 | 更新 | - | 配置 | |
| | | | Figure | 105 In | terface | of Ha | rmonic Pa | irametei | Setting | 1 | | Ň |
| of Ha | rmonic | Interfac | e Param | neters | | | | | | | | |

Table 25 Interpretation of Harmonic Interface Parameters

X

| Parameter term | Unit | Interpretation | Model | Resolution | Setting range |
|--------------------|------|--|-------|------------|-----------------------------|
| No. | 1 | Number of harmonics. Up to 100 harmonics can be edited, see Section 4.9. | ALL | 1 | 1 |
| Value[%] | 1 | Harmonic content. | ALL | 0.01 | See Section 4.9 for details |
| Phase[°] | 0 | Harmonic phase. | ALL | 0.1 | 0~359.9 |
| -3 | 大言! | Clear all current data and return to the initial programming state of Figure 105. | ALL | 1 | 1 |
| Export | 1 | Store harmonic parameters into the product. | ALL | / | 1 |
| Import | 1 | Import the stored harmonic parameters to the Harmonic Settings screen. | ALL | 1 | 17月 |
| DST | 1 | It contains 30 kinds of built-in harmonics, which can be imported to a certain phase or three phases in the DST interface, as shown in Figure 106. | ALL | 1 | 1 |
| Preview | | Preview the output waveform under the currently set harmonic parameter. | ALL | 1 | 1 |
| Export waveform | 1 | Store the set harmonic waveform inside the product and import it to a custom waveform in 8.11.4, which can be output as a steady-state | ALL | | 1 |
| | | ※ 是TIENPOWER | X | CTIONPOWER | 139 |

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| | | ×. | 音形 第 同 NPOWE | | |
|-------------------|----------------------|---|-----------------------|------------|---------------|
| Parameter term | Unit | Interpretation | Model | Resolution | Setting range |
| | | waveform. | | | |
| Loading | 1 | Lock the harmonic data and enter the to-be-triggered state. | ALL | / | 1 |
| Exit | 1 | At any time during harmonic operation, you can click "Exit" to end the current mode. | ALL | 1 | 1 |
| Triggering | 1 | Transition from steady output state to harmonic output state. | ALL | / | 1 |
| Update | 活行 TIDNPOW | After the user modifies the harmonic parameters, simply click "Update" and the product will output the waveform according to the harmonic parameters currently set. | ALL | 1 | 1 |

Note: The expected output waveform is still limited by the value parameters, and improper limit setting may distort the expected output waveform.

| FRE 编辑 | Source待机正弦波 三相 AC | | | 日常常合 ● 1 ^{2022/9/2} 20:43:06 |
|------------|------------------------|----------|---------|---------------------------------------|
| Name | Time | | 导入至Φ1 | Advanced |
| DST01.harm | 2022-09-13 00:00:00 | | 导入至Φ2 | した Advanced つい 谐波 へ |
| DST02.harm | 2022-09-13 00:00:00 | | 导入至Φ3 | ₩ 頃波 |
| DST03.harm | 2022-09-13 00:00:00 | | 导入至Φ123 | 1 编辑 |
| DST04.harm | 2022-09-13 00:00:00 | | | ▲ 间谐波 |
| DST05.harm | 2022-09-13 00:00:00 | | 返回 | ◎ 限值 |
| BOWER | Figure 106 DST Interfa | ace Diac | ıram 🧹 | ACTIO |

Example of harmonic setting:

- 1) Press the output button on the front panel to let the product output a steady-state voltage.
- 2) Set the 3rd harmonic content to 20% and the 5th harmonic content to 40%, see Fig.107.

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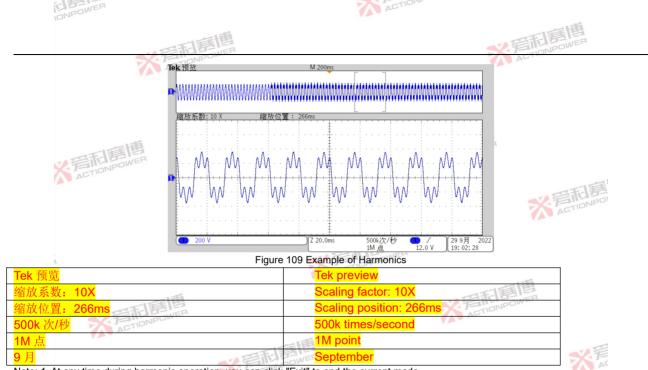








| IDNPOWER | | | | ~ | ACTION | | |
|--------------------|-------------------------|------------------------|-------------------|-----------|------------------------------|-----------------------------------|-----------------------|
| far. | 四形度 | | | | | * 着雨 | EFIG NPOWER |
| | CHE TIONPI | | | | | 다 | |
| PRE | 编辑 🕜 | | E相 AC | ~ | | 호 F F F C & 산 20:32:55 | |
| No. • 1 | Value[%] Phase[*] #2 | Value[%] Phase[*] \$\$ | Value[%] Phase[*] | | 导入 导出 | Pulse | |
| 3 | 20.00 0.0 | 20.00 0.0 | | | DST | | |
| 4 | 0.00 0.0 | | | | 预览 | Advanced Y | |
| 5 | 40.00 0.0 | 40.00 0.0 | | | 导出波形 | ∾ 谐波 ^ | |
| ETE 6 | 0.00 0.0 | | | | 加载 退出 | | |
| TIONE 7 | 0.00 0.0 | 0.00 0.0 | 0.00 0.0 | | 触发 更新 | 1 配置 | |
| AL | | | | | arameter Settin | | -1= |
| 3) Click "Load" in | the lower right | ght corner. A | t this time, | "Exit" an | d "Trigger <mark>"</mark> ar | e highlighted, as sl | nown in Figure 10 |
| PRE | 编辑 🕜 | Source运行 正弦波 | E相 AC | 谐波 | | 원류R (C) (D) 2022/9/20 20:33:44 | ACTIONPO |
| No. Φ1 | Value[%] Phase[*] | Value[%] Phase[*] | Value[%] Phase[*] | -3 | 导入 导出 | 🚅 Step 💙 | |
| 2 | 0.00 0.0 | | | | DST | M Pulse 🗸 | |
| 3 | 20.00 0.0 | 20.00 0.0 | | | 预览 | 🗠 Advanced | |
| 4 | 0.00 0.0 | 0.00 0.0 | | | 导出波形 | ∿ 谐波 ^ | |
| 5 | 40.00 0.0 0.00 0.0 | 40.00 0.0 0.00 0.0 | | | 加载 退出 | └ 编辑 | |
| 6 | 0.00 0.0 | 0.00 0.0 | | | 触发更新 | 1 配置 | |
| | | | | | arameter Settin | ACT | |
| The still | to display | the program | med wave | form on | the oscilloso | ope (only ф1 wav | eform is display |
| here), see Fig | | the program | med wave | | | | - |
| 11010), 000 Hg | | X ACTIO | NPOWER | | | | 茶 着 AT |
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Note: 1. At any time during harmonic operation, you can click "Exit" to end the current mode.

2. After modifying the harmonic parameters, "Update" is highlighted and click "Update". The product will output the waveform according to the harmonic parameters currently set.

3. How to use "Export Waveform": click "Export Waveform" \rightarrow enter the name of the saved waveform \rightarrow click "Enter" \rightarrow click $\varphi 1/\varphi 2/\varphi 3$ to export, that is, to store the currently edited waveform to the product.

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Click Harmonic - Configuration in the menu bar to enter the harmonic configuration interface, as shown in Figure ACTIONPOWER







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Figure 110 Interface of Harmonic Configuration

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| Table 26 Interp | retation of H | armonic Configuration Parameters | | | 司意 |
|-------------------|---------------|--|-------|------------|---------------|
| Parameter term | Unit | Interpretation and application | Model | Resolution | Setting range |
| Trigger input | 1 | Internal: manually click "Trigger" on the display to realize internal triggering. External: send a trigger signal to it through Anyport digital input interface to realize external trigger. See Section 8.14.1 for details. | ALL | 1 | 1 |
| Trigger delay | s | When "Trigger" is pressed, the harmonics are output after a set trigger delay. | ALL | 0.001 | 0~999.999 |
| Trigger output | X Act | Single: A pulse indication signal is sent through the digital output of Anyport at the moment of harmonic output. See Section 8.14.1 for details. Fundamental wave: After harmonic output, a pulse indication signal is sent through the digital output of Anyport at each zero-crossing point of the fundamental wave. | ALL | / | Ar |

The configured harmonic parameters can be stored inside the product or to an external USB storage device for direct call next time to reduce repeated configuration by users. See Section 8.11.5 for details.

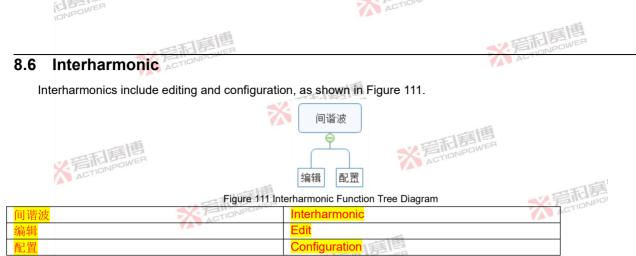
For the specific practice of storing harmonic parameters inside the product, refer to the storage method of List programming.

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Click Interharmonic-Edit in the menu bar to enter the interharmonic parameter setting interface, where you can set the interharmonic parameters by yourself. See Figure 112 for the interharmonic parameter setting interface. The parameters are explained in Table 27.



Figure 112 Interharmonic Parameter Setting Interface

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Table 27 Interharmonic Interface Parameter Interpretation









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|-------------------|-----------|---|---------------|------------|---------------|--|
| Parameter term | Unit | Interpretation | Model 🌾 | Resolution | Setting range | |
| No. | 1 | Serial number, supporting up to 300 steps. | ALL | 1 | 1 | |
| Value[%] | / | Interharmonic content. | ALL | 0.01 | 0~40 | |
| Start[Hz] | Hz | Initial frequency. | ALL | 0.001 | 0.001~2000 | |
| End[Hz] | Hz | End frequency. | ALL | 0.001 | 0.001~2000 | |
| Δ[Hz] | Hz | Frequency step. | ALL | 0.001 | 0.001~2000 | |
| Dwell[s] | S | Execution time per frequency step. | ALLOWER | 0.0001 | 0~999.9999 | |
| Pause[s] 🎾 🛫 | S | Interval time per frequency step. | ALL | 0.0001 | 0~999.9999 | |
| 3 | ACTION PU | Clear all current data and return to the initial programming state of FIGURE 112. | ALL | / | 1 | |
| "+" | 1 | The current sequence inserts a set of new sequences backward, and the parameter values are the same as the current sequence. | ALL | / ※浮 | TIONPO | |
| "_" | 1 | Delete the current sequence. | ALL | | 1 | |
| Export | / | Interharmonic parameters are stored in the product. | ALL | 1 | / | |
| Import | 1 | Import the stored interharmonic parameters to the harmonic setting interface. | ALL | 1 | 1 | |
| Loading | / | Lock the interharmonic data and enter the state to be triggered. | ALL | / | / | |
| Exit | 1 | At any time during interharmonic operation, you can click "Exit" to end the current mode. | ALL | 書画 | 1 | |
| Triggering | / | From the stable output state to the programming waveform output state. | ALLACTION | SAWEN | 1 | |

Note: The expected output waveform is still limited by the value parameters, and improper limit setting may distort the expected output waveform.

Example of setting interharmonic parameters:



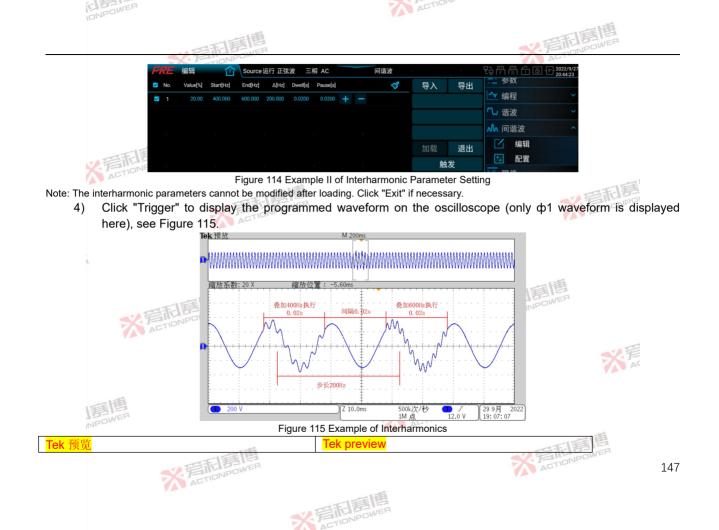
- 1) Press the output button on the front panel to let the product output a steady-state voltage.
- 2) The interharmonic parameters are shown in Table 28.

| Parameter term | Settings | Parameter term | Settings | |
|----------------|----------|----------------|----------|--|
| Value[%] | 20 | Δ[Hz] | 200 | |
| Start[Hz] | 400 | Dwell[s] | 0.02 | |
| End[Hz] | 600 | Pause[s] | 0.02 | |









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| 音放系数: 20X | Scaling factor: 20X |
|-----------------------|--|
| 诸放位置: -5.60ms | Scaling position: -5.60ms |
| 查加 400H 执行 0.02s | Superimpose 400H for 0.02s |
| <mark>]隔 0.02s</mark> | Interval 0.02s |
| 加 600H 执行 0.02s | Superimpose 600H for 0.02s |
| 长 200Hz | Step size: 200Hz |
| DOK 次/秒 音前 Shewer | 500k times/second |
| | 1M point |
| 月 | September an click "Exit" to end the current mode. |

Click Interharmonic - Configuration in the menu bar to enter the harmonic configuration interface, as shown in Figure 116.



| IONPOWER | | ACTION |
|-----------|--|---|
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| | PRE 配置 Gource待机正弦波 三相 AC | 원 문 문 문 습 G 단 2022/9/27 20.42.03 |
| | 循环次数 | ∽ 谐波 |
| | | ▲ |
| | 连续触发 | |
| | 触发模式 | |
| | 自动 | |
| | | |
| X 完計書書 | FRE 配置 Source 待机 正弦波 三相 AC | 段 骨 骨 骨 合 個 仕 2022/9/27 20.42-13 |
| ACTIONPUT | (φ) (マンクロン (マンクロン) (マンクロ) (マンD) (マ) (マ) (マ) (マ) (マ) (マ) (マ) (マ) (マ) (マ | ~ 谐波 ~ |
| | 融友物入 内部 外部 | ▲ 间谐波 |
| | 时间[s] | |
| | 触发延时 0.000 | |
| | | |
| | 触发输出 单次 单步 单街 | |
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| 4 | 的IIIISI 0.000 | ~ 谐波 ~ |
| | | □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ |
| | 触发输出 ① ① ② | I I I I I I I I I I I I I I I I I I I |
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Figure 116 Interface of Interharmonic Configuration

Refer to List and Harmonic Configuration Interface for parameter functions and interpretation in the interharmonic configuration interface.

The configured interharmonic parameters can be stored inside the product or to an external USB storage device to facilitate direct call next time to reduce repeated configuration by the user. See Section 8.11.5 for details.

For the specific practice of storing interharmonic parameters inside the product, refer to the storage method of List programming.

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Click the limit in the menu bar to enter the limit setting interface. The limit setting interface is shown in Figure 117, where the given range of voltage, frequency, current and power can be set. See Table 29 for the definition of limit parameters.

| | PRE 限值 | Source 待机 正弦波 🛛 | E相 AC | 設骨骨骨合 ④ 12/28/40 |
|------------|--------|---------------------------|--------------------------------|--|
| ACTIONPOWE | 交流电压 | 下限[M] 0.00 | 上限[V] 450.00 | ▲ 编程 へ 谐波 ~ |
| ACTIONPOWE | | | | ▲ |
| | 直流电压 | 下限[/] -636.00 | 上限[/] 636.00 | |
| | 频率 | 下限[Hz] | 上限[Hz] | ○ 限值 ○ 保护 ▲ 事件 |
| | | 0.001 | 200.000 | lout. |
| | PRE RÉ | | E相 AC 上限[A] | ちの一部である。 日本語の 12222/9/3 12248.49 12 |
| 2 | 交流电流限值 | 下限[A] 0.00 | 25.00 | ∿ 谐波 ~ |
| | | 下限[A] | 上限[A] | ▲ 间谐波 |
| | 直流电流限值 | -35.00 | 35.00 | |
| | | 下限[kW] | 上限[kw] | ♥ 保护 VEP |
| ※ ACT | 有功功率限值 | -6.667 | 6.667 | ▲ 事件 ● ● ● ● ● ● ● ● ● ● ● ● ● ● ● ● ● ● |
| ALT | PRE RÉ | | E相 AC | 日本 |
| | 直流电流限值 | 下限[A] -35.00 | 上限[A] 35.00 | |
| | | | | へ 谐波 × 小 间谐波 × |
| | 有功功率限值 | 下限[kW] -6.667 | 上限[kW] 6.667 | ── 限值 |
| 一道 | | 下限[kVA] | 上限[kVA] | ⑦ 保护 |
| NPOWER | 视在功率限值 | 0.000 | 6.667 | ▲ 事件 |
| INPL | | Figure | 117 Interface of Limit Setting | 156 |
| | | - IE | | ※ 言語 意題 AcTIONPOWER |
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| | ACTION | POW | | |
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| Table 29 Functions of | of Limits | X FINNPOWER | | ALT | ON | |
|---------------------------------|-----------|--|--|------------|------------------|------------------|
| Parameter term | Unit | Interpretation and application | Model | Resolution | Initial value | Setting range |
| AC voltage lower limit | V | The minimum value that can be set for AC voltage in the output setting area. When the user needs to avoid damage to the tested equipment due to too low output AC voltage caused by misoperation, the lower limit of AC voltage can be set in the safe range here. | ALL | 0.01 | 0 | 0.00~450 |
| AC voltage upper limit | V | The maximum value that can be set for AC voltage in the output setting area. When the user needs to avoid damage to the tested equipment due to excessive output AC voltage caused by misoperation, the upper limit of AC voltage can be set in the safe range here. | ACTIONIC | 0.01 | 450 | 0.00~450 |
| DC voltage lower limit | V | The minimum value that can be set for DC voltage in the output setting area. When the user needs to avoid damage to the tested equipment due to too low output DC voltage caused by misoperation, the lower limit of DC voltage can be set in the safe range here. | ALL | 0.01 | -636 | -636~0 |
| Upper limit of DC voltage | V | The maximum value that can be set for DC voltage in the output setting area. When the user needs to avoid damage to the tested equipment due to excessive output DC voltage caused by misoperation, the upper limit of DC voltage can be set in the safe range here. | ALL | 0.01 | 636 | 0~636 |
| Lower limit of AC current limit | A | The minimum value of the output AC current of each phase, which is valid when the coupling mode is AC. When the output phase is three-phase or split-phase, the actual value is equal to the set value. When the output phase is single phase, the actual value is 3 times the set value. When the user needs to avoid damage to the equipment under test due to low output AC current due to misoperation, the lower limit of AC current can be set in a safe range here. | PRE2006S PRE2007S PRE2009S PRE2012S PRE2012S PRE2020S | 0.01 | 0 | 0.00~30 |
| Upper limit of AC current | А | The maximum value of the output AC current of each phase, which is valid when the coupling mode is AC. | PRE2006S PRE2007S | 0.01 | 30 | 0.00~30 |
| | 7 | X 言和意情 | | ACTIC | NPUW | 15 |
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|--------------------------------------|-------|--|--|------------|--|--|
| | | 一一一月夏月 | | | 日夏博 | |
| Parameter term | Unit | Interpretation and application | Model | Resolution | Initial value | Setting range |
| - F | 語傳 | When the output phase is three-phase or split-phase, the actual value is equal to the set value. When the output phase is single phase, the actual value is 3 times the set value. When the user needs to avoid damage to the equipment under test due to excessive output AC current caused by misoperation, the upper limit of AC current can be set in the safe range here. | PRE2009S PRE2012S PRE2015S PRE2020S | IER. | 35 | 0.00~35 |
| ACTIO | NPOWE | The minimum value of the output DC current of each phase, which is valid when the coupling mode is DC. | PRE2006S PRE2007S | | -30 | -30~0 |
| Lower limit of DC current limit | A | When the output phase is three-phase or split-phase, the actual value is equal to the set value. When the output phase is single phase, the actual value is 3 times the set value. When the user needs to avoid damage to the equipment under test due to too low output DC current due to misoperation, the lower DC current limit can be set in the safe range here. | PRE2009S PRE2012S PRE2015S PRE2020S | 0.01 | -35 | -35~0 |
| | | The maximum value of the output DC current of each phase, which is valid when the coupling mode is DC. | PRE2006S PRE2007S | | 30 | 0~30 |
| Upper limit of DC current | ACT | When the output phase is three-phase or split-phase, the actual value is equal to the set value. When the output phase is single phase, the actual value is 3 times the set value. When the user needs to avoid damage to the equipment under test due to excessive output DC current caused by misoperation, the upper limit of DC current can be set in the safe range here. | PRE2009S PRE2012S PRE2015S PRE2020S | 0.01 | 35 | 0~35 |
| Lower limit of active power limit | kW | The minimum active power of each phase. When the output phase is three-phase or split-phase, the actual value is equal to the set value. When the output phase is single phase, the actual value is 3 times the set value. When the user needs to avoid damage to the equipment under test due to low source power due to misoperation, the lower limit of active power can be set in the safe range | PRE2006S PRE2007S PRE2009S PRE2012S PRE2015S PRE2020S | 0.001 | -2 -2.5 -3 -4 -5 -6.667 | -2~0 -2.5~0 -3~0 -4~0 -5~0 -6.667~0 |
| | | ACTION POWER | 1 | ACTIC | NPOWER | 1 |

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|--------------------|---------------|--|----------|------------|-----------------------|------------------|
| Parameter term | Unit | Interpretation and application | Model | Resolution | Initial value | Setting range |
| | | here. | | | | |
| | | The maximum active power of each phase. When the | PRE2006S | | 2 | 0~2 |
| | | output phase is three-phase or split-phase, the actual | PRE2007S | | 2.5 | 0~2.5 |
| | | value is equal to the set value. When the output phase is | PRE2009S | | 3 | 0~3 |
| Upper limit of | кW | single phase, the actual value is 3 times the set value. | PRE2012S | 0.001 | 4 | 0~4 |
| active power limit | e power limit | When the user needs to avoid damage to the equipment | PRE2015S | WER | 5 | 0~5 |
| ACTIONPOL | NPOWE | under test due to excessive source power due to misoperation, the upper limit of active power limit can be set in a safe range. | PRE2020S | | 6.667 | 0~6.667 |
| | | The minimum apparent power of each phase. When the | PRE2006S | | 0 | 0~2 |
| | | output phase is three-phase or split-phase, the actual | PRE2007S | 1 | 0 | 0~2.5 |
| | kVA | value is equal to the set value. When the output phase is | PRE2009S | 0.001 | 0 AL | 0~3 |
| Apparent power | | single phase, the actual value is 3 times the set value. | PRE2012S | | 0 | 0~4 |
| limit lower limit | | When the user needs to avoid damage to the equipment | PRE2015S | | 0 | 0~5 |
| 2 | | under test due to low source power due to misoperation, the lower limit of apparent power can be set in the safe range here. | PRE2020S | | 0 | 0~6.667 |
| | | The maximum apparent power of each phase. When the | PRE2006S | 一個 | 2 | 0~2 |
| | | output phase is three-phase or split-phase, the actual | PRE2007S | 新昂昂 | 2.5 | 0~2.5 |
| | THE | value is equal to the set value. When the output phase is | PRE2009S | CTIONPOW | 3 | 0~3 |
| Upper limit of | kVA | single phase, the actual value is 3 times the set value. | PRE2012S | 0.001 | 4 | 0~4 |
| apparent power 🏑 | ACT | When the user needs to avoid damage to the equipment | PRE2015S | 0.00. | 5 | 0~5 |
| | | under test due to excessive apparent power caused by misoperation, the upper limit of apparent power can be set in a safe range. | PRE2020S | | 6.667 | 0~6.667 |

Note: When paralleling, the relevant parameter settings of current and power need to be multiplied by the number of paralleling.

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8.8 Protection

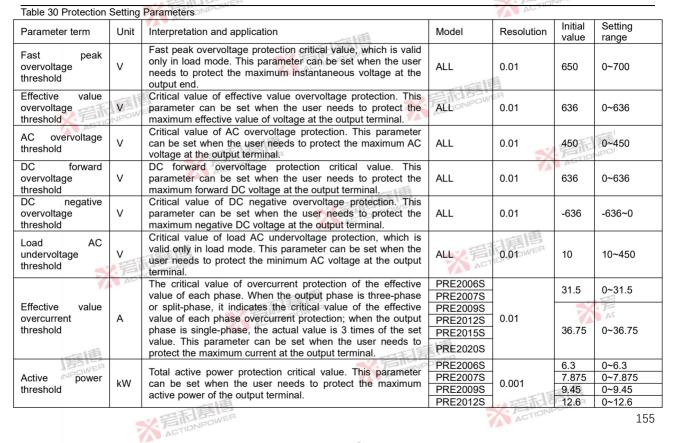
Click "Protection" in the menu bar to enter the protection setting interface. The protection setting interface is shown in Figure 118, where protection thresholds for voltage, current, power and frequency can be set. The protection ※着印書書 parameters are defined in Table 30.

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|-----------------------------|-------|---|----------------------|------------|------------------|------------------|
| Parameter term | Unit | Interpretation and application | Model | Resolution | Initial value | Setting range |
| | | 三和夏唐 | PRE2015S PRE2020S | | 15.75 21 | 0~15.75 0~21 |
| | | Total apparent power protection threshold. This parameter | PRE2006S PRE2007S | | 6.3 7.875 | 0~6.3 0~7.875 |
| Apparent power threshold | kVA | can be set when the user needs to protect the maximum apparent power of the output terminal. | PRE2009S PRE2012S | 0.001 | 9.45 12.6 | 0~9.45 0~12.6 |
| | ONPOW | | PRE2015S PRE2020S | | 15.75 21 | 0~15.75 0~21 |
| Overfrequency threshold | Hz | Critical value of overfrequency protection. This parameter can be set when the user needs to protect the maximum frequency of the output terminal AC voltage. | ALL | 0.001 | 2000 | 0.001~2000 |
| Underfrequency threshold | Hz | Critical value of underfrequency protection. This parameter can be set when the user needs to protect the minimum frequency of the AC voltage at the output terminal. | ALL | 0.001 | 0.001 | 0.001~2000 |
| Protection time | s | During the set protection time, if the output value of each parameter item continues to exceed the protection threshold, the protection will be triggered. | ALL | 0.001 | 0.1 | 0.001~3 |

Note: When paralleling, the relevant parameter settings of current and power need to be multiplied by the number of paralleling. ACTIONPOWER

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8.9 Event

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The PRE20XXS series products are designed with event logging function, which can monitor specific situations that occur during operation and facilitate users to observe and understand the working condition of the product. Click event in the menu bar to enter the event setting interface. The event setting interface is shown in Figure 119. AC



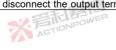






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|---------------------|-------------|--|--|--------------------------------------|---------------|---------------------------------|------------------------|------------------|
| | | · 三和意情 | | | | *2.7 | 記 意 個 ENPOWER | |
| | | FRE 事件 介 Source待 | i机 正弦波 三相 AC | | | b 田 田 日 日 日 日 | 2022/10/25 | |
| | | 事件1 | | л 🗕 | | ₩ 谐波 | ~ | |
| | | | | | | ุ ▲ 间谐波 | ~ | |
| | | 触发源 | 触发阈值[%] 无 100.00 | 触发时间[s] 0.000 | | ── 限值 | | |
| | | | | 0.000 | | 🛈 保护 | | |
| | -15 | 动作方式 | 阈值方向 | | | ⚠ 事件 | | |
| ~ | 晋市唐 | 警 | 告向上 | | 清事件 | 通讯 | | |
| | ACTION | Fiç | gure 120 Interface | of Event Paramete | r Setting | | | |
| Table 31 Eve | ent Setting | Functions | 言图 | | - | | TARE | 括 |
| Parameter erm | Unit | Interpretation and applica | tion | | Model | Resolution | Initial value | Setting range |
| Event iumber | ١ | | | 一直 | ALL | ۸ | ۸ | ١ |
| Trigger source | ١ | The voltage, current, frequency, power and temperature are displayed for each phase. When the user needs to monitor the status of voltage, current, power and temperature, the corresponding trigger source can be selected to trigger the event. | | | | | ф1 Urms | ١ |
| ⊺rigger hreshold | % | The percentage of the rat each model are given in 65°C The user can set the the trigger threshold. | ting of the trigger s Table 32, and the | for is | 0.01 | 100 | 0~100 | |
| rigger ime | s | event is triggered. The us speed of event triggering. | Time from when the trigger threshold is exceeded to when the event is triggered. The user can set this parameter to control the speed of event triggering. | | | 0.001 | 0 | 0~9999 |
| Action node | E DIVER | Recording: When an eve event in the log, and t recording. The product of and it is necessary to clic to start recording. | he action mode an operate norm | can be selected ally during recordir | as ng, ALL | ١ | Record | ١ |
| | | Alarm: when an event or disconnect the output ter | | | | | EB | |
| | | * STIDNPOWER | | | | ACT | LIDIAL | 15 |

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|------------------------|---------|--|-------|--------------------|---------------|---------------|
| Parameter term | Unit | Interpretation and application | Model | Resolution | Initial value | Setting range |
| | | as alarm. After the alarm, the product will disconnect the output end, and the word "Event X" will flash in the status display area. | | | | |
| | | Warning: When an event occurs and the user needs a warning prompt, the action mode can be selected as warning. After the warning, the product can operate normally, and the word "Event X" will flash in the status display area. | ALL | ま 博 R WER | | |
| Threshold direction | ACTIONE | An event is triggered when the voltage/current/power/temperature exceeds the trigger threshold upward. When the user needs to exceed the trigger threshold upward to trigger the event, the threshold direction needs to be set to upward. An event is triggered when the voltage/current/power/temperature exceeds the trigger threshold downward. When the user needs to exceed the trigger threshold downward to trigger the event, the threshold direction needs to be set to downward. | ALL | 2010.2 | Upward | |
| Clear event | ١ | Clear the status of all triggered events, and the power/reset key also has the function of clearing events. If the user needs to clear the event and clear the event status in the status display area, click this button. | ALL | FILENPOW | ER | ١ |

Table 32 Correspondence of Parameter Values with 100% Trigger Threshold

| Parameter term | Unit | Interpretation | | Model | Corresponding parameter value at 100% of trigger threshold |
|----------------|------|--------------------------------|--------|----------|---|
| ф1 Urms | V | Effective value of ch1 voltage | | ALL | 450 |
| ¢1 Irms | | Effective value of Φ1 current | | PRE2006S | 30 |
| | | | | PRE2007S | |
| | | | N Filt | PRE2009S | |
| | A | | | PRE2012S | 35 |
| | | | ACT | PRE2015S | 35 |
| | | | | PRE2020S | 一個 |
| ф1 P | kW | Φ1 active power | | PRE2006S | 2 TELEP |
| | | ACTIONPOWER | | | ACTIONPOWE 159 |
| | | ACTIO | 175 | | |





| _ | | St.F | TIONPOWER | | Corresponding parameter value |
|--------|-----------|----------------------|--------------------|-------------|-------------------------------|
| Parame | eter term | Unit 🔨 🗚 | Interpretation | Model | at 100% of trigger threshold |
| | | | 一個 | PRE2007S | 2.5 |
| | | | 三利司 | PRE2009S | 3 |
| | | | * TIONPOWER | PRE2012S | 4 |
| | | | ALT | PRE2015S | 5 |
| | | | | PRE2020S | 6.667 |
| | | 一個 | 4 | PRE2006S | 2 |
| | T | DNPOWER | | PRE2007S | 2.5 |
| | X | DNPOW | A 4 | PRE2009S | 3 |
| ф1 S | AU | kW | Φ1 apparent power | PRE2012S | 4 |
| | | | 一直想 | PRE2015S | 5 |
| | | | TA FEILE DOWER | PRE2020S | 6.667 |
| | | | ACTIONIC | PRE2006S | 2 |
| | | | PRE2007S | 2.5 | |
| | | kW | Ф1 reactive power | PRE2009S | 3 |
| ф1 Q | | | | PRE2012S | 4 |
| | 2 | | | PRE2015S | 5 |
| | | | | PRE2020S | 6.667 |
| | | KW ACTIONPOW | Total active power | PRE2006S | 6 |
| | | | | PRE2007S | 7.5 |
| 50 | | | | PRE2009S | 9 |
| ΣΡ | 7 | | | PRE2012S | 12 |
| | | | | PRE2015S | 15 |
| | | 一日月月日日 | PRE2020S | 20 | |
| | | | ACTIONPOWER | PRE2006S | 6 |
| | | | | PRE2007S | 7.5 |
| ΣS | | | | PRE2009S | 9 |
| | kW | Total apparent power | PRE2012S | 12 | |
| | | | PRE2015S | 15 | |
| | | | PRE2020S | 20 | |
| ΣQ | kW | Total reactive power | PRE2006S | 6 | |
| | | | PRE2007S | 7.5 1. SWER | |









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|----------------|-----------|--------------------|---------------|--|--|
| Parameter term | Unit Via | Interpretation | Model | Corresponding parameter value at 100% of trigger threshold | |
| | | 一個 | PRE2009S | 9 | |
| | | 三百月月 | PRE2012S | 12 | |
| | | * ACTIONPOWER | PRE2015S | 15 | |
| | | AL | PRE2020S | 20 | |
| ф1 Uac | V | Φ1 AC voltage | ALL | 450 | |
| ф1 Udc | V | Φ1 DC voltage | ALE | 636 | |
| | ONPOWER | Φ1 AC current | PRE2006S | 20 | |
| ACT | DNPUI | | PRE2007S | 30 | |
| ф1 lac | A | | PRE2009S | | |
| | | | PRE2012S | | |
| | | | PRE2015S | 35 ACTIONPOL | |
| | | | PRE2020S | | |
| | | | PRE2006S | 30 | |
| | | | PRE2007S | | |
| ф1 ldc | A | Φ1 DC current | PRE2009S | | |
| 1 | | 萬 | PRE2012S | 35 | |
| | | | PRE2015S | | |
| | | | PRE2020S | POWER | |
| ф1 Upk | V | ⊳Φ1 Voltage peak | ALL ACTIO | 636 | |
| ф1 lpk 📃 🔻 🔻 | AACTIONIC | Φ1 Peak current | ALL | 90 | |
| ф1 U12 🛛 🗸 | V | Line voltage UAB | ALL | 779 | |
| ф1 Irush | A | Φ1 impulse current | ALL | 90 | |
| Temp | °C | Outlet temperature | ALL | 65 | |
| Freq | Hz | Frequency ACTIVE | ALL | 200 | |

Note: 1. When ¢1 is single-phase, the corresponding parameters of current and power shall be multiplied by 3.

2. ϕ 2 and ϕ 3 are invalid in single phase, and refer to ϕ 1 for other corresponding parameters.

3. During parallel operation, the corresponding parameters of current and power shall be multiplied by the number of parallel operations.

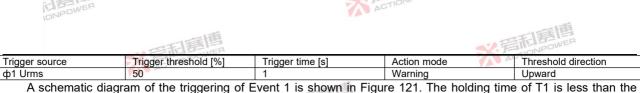
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Example: The parameter settings of Event 1 are shown in Table 33.

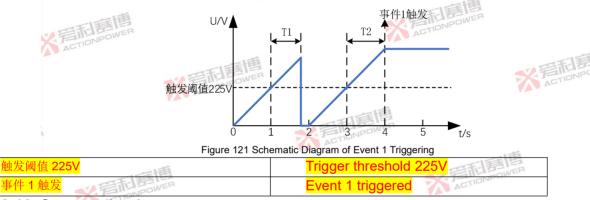
Table 33 Parameter Settings of Event 1







A schematic diagram of the triggering of Event 1 is shown in Figure 121. The holding time of 11 is less than the triggering time, so event 1 is not triggered; The holding time of T2 is equal to the trigger time, so event 1 is triggered at 4s.



8.10 Communication

The PRE20XXS series products can be switched between local and remote communication modes, and the remote supports LAN and USB communication with user equipment. Click Communication in the menu bar to enter the communication setting interface. In the communication setting interface, you can choose to transfer the control of this product to different ports for local/remote control. The communication interface is shown in Figure 122. See Table 34 for the explanation of parameters.

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|------|------|-----|------|--|
| | A | C | | |
| | | | | |
| | | | | |



| Table 34 Interpretation of Communication Interface Parameters | | | | | | |
|---|----------|---|--------|-------------------------|------------------|---------------|
| Parameter term | Unit | Interpretation | Model | Resolution | Initial value | Setting range |
| Local lock | 1 | Locking local control permissions prevents other ports from gaining control. Local lock can only be enabled in local control mode, and remote communication cannot be set after enabling. | ALL | / | / | 1 |
| Equipment No. | 1 | Used to set the product address. | ALL | TWER | 1 | 1~127 |
| Communication | TION POW | Select the control method of this product. With the local lock turned off, the remote communication port can obtain product control rights by command. SCREEN: Display local control. LAN: Ethernet remote control. USB: USB remote control. | ACTION | 1 | | |
| Communication protocol | 1 | The LAN port of this product supports SCPI and Modbus-TCP communication protocols. | ALL | 1 | 1 | 1 |
| IP Assignment | 1 | Automatic and manual. | ALL | / | 1 | 1 |
| IP address | 1 | The IP address type is IPv4. | ALL | 1 | 1 | 1 |
| Port No. | 1 | The port number is 502. | ALL | 1 | 1 | 1 |
| USB | / | The USB port supports SCPI and Modbus-RTU communication protocols. When selecting USB port control, the corresponding communication protocol also needs to be configured. | ALL | 第記書 ACTIONPOW | | 1 |

8.10.1 LAN Interface IP Assignment

8.10.1.1 Automatic mode

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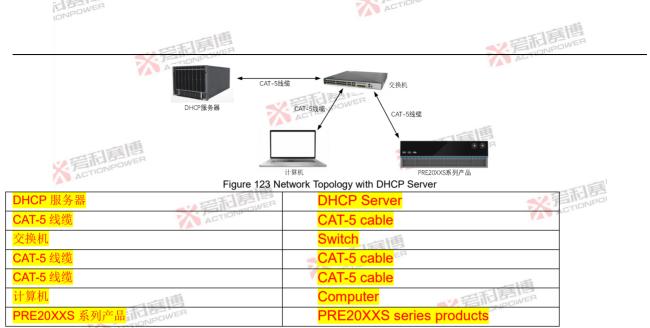
In automatic mode, in a LAN with a DHCP server, the PRE20XXS series products will request network parameters from the server through the DHCP protocol, and the request timeout is 30s. The network topology is shown in Figure 方前1時間 ACTIONPOWER

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123.







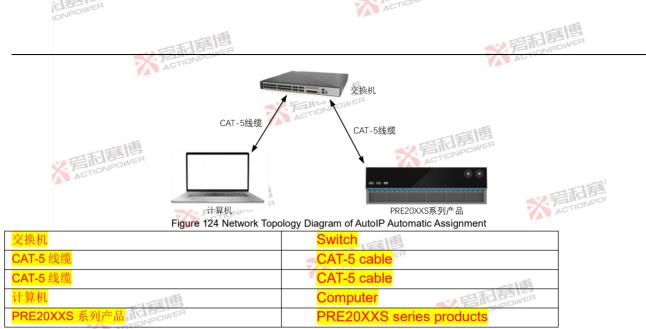
In a LAN without a DHCP server or after a DHCP request times out, the PRE20XXS series products will automatically allocate network parameters via the AutoIP protocol. The network parameters automatically allocated by AutoIP are shown in Table 35. The network topology is shown in Figure 124. AC

Table 35 Network Parameters Automatically Assigned by AutoIP

| Parameter term | Parameter range | 一個 | |
|------------------|-----------------------------|-------------|---------------|
| IP address | 169.254.1.0~169.254.254.255 | A SET DOWER | |
| Subnet mask were | 255.255.0.0 | ACTIONPUT | |
| Gateway Address | 0.0.0.0 | | 100 |
| | ★写和意情 | X | TIONPOWER 165 |

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The network parameters obtained in automatic mode are not saved, and the network parameters will be retrieved every time the network cable is inserted or switched to automatic mode.

8.10.1.2 Manual mode

The network parameters in manual mode are set by the user on the LAN configuration page. When used in the LAN, if the IP address set is the same as that of other network devices, the setting cannot take effect. After the IP conflict, the PRE20XS series products will automatically assign a new IP address through the AutoIP protocol. Manual mode is applicable to various network topologies.

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8.10.1.3 LAN Status Description

The description of LAN status display is shown in Table 36.

Table 36 Interpretation of LAN Status Display

| Status | Status Interpretation | |
|---------------------|--|--|
| Fault | No network cable inserted or IP conflict | |
| Device Identity | In network configuration | |
| Normal Operation | Configuration successful | |
| 8.10.2 USB interfac | ce configuration | |

8.10.2 USB interface configuration

8.10.2.1 Interface Description

The description of the USB interface is shown in Table 37.

Table 37 Description of LISB Interface

| | Billionado | |
|------------------|-------------------------------|--|
| Category | Support | |
| Connector type | USB Type B | |
| Hardware support | USB 2.0, USB 1.1 | |
| Protocol Type | Class USBTMC, Subclass USB488 | |
| Driver | NI-VISA Driver | |

8.10.2.2 Use

After the computer has successfully installed the NI-VISA driver, connect the computer and the PRE20XXS series products through a USB cable, and identify the device information in Figure 125 in the computer's device manager, and the software and hardware work normally.

> **USB** Test and Measurement Devices Ü V

> > * 岩形!



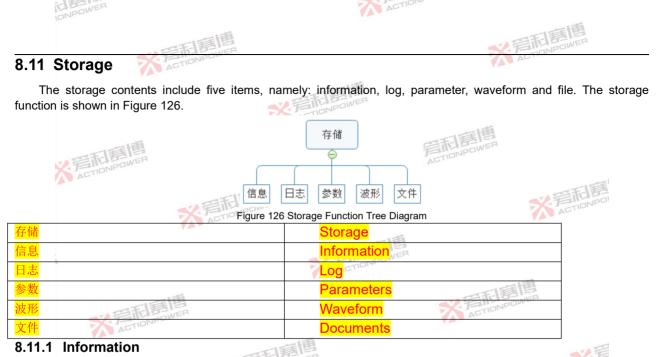
USB Test and Measurement Device (IVI)

Figure 125 USB Information Diagram in Device Manager

After successful identification, SCPI commands can be sent to the PRE20XXS series products through NI-MAX software. When the query command is sent, the interval between the DEV DEP MSG OUT message (Write) and the REQUEST DEV DEP MSG IN message (Read) must be more than 10 ms.







Click Storage-Information in the menu bar to enter the information interface. The information interface is to record the operation status of the PRE20XXS series products, including operation, protection, alarms and events, as shown in ※言和意情 Figure 127.

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| IDNPOWER | | | | | ACTION | |
|-------------|------|----|-------|--------------------|-------------------------|--------------------------------------|
| | | | 新麗 | EP. | | * 爰利意情 |
| | PRE | 信息 | So So | urce待机 正弦波 三相 AC | | 段骨骨合 ⑥ ① 2022/9/3 12:50:38 |
| | No. | 模式 | 内容 | 日期 | | 「 存储 ^ |
| | 1 | | 操作:断开 | 2022-9-3 12:46:51 | | └ 信息 |
| | 2 | | 操作:接通 | 2022-9-3 12:46:42 | | |
| | 3 | | 操作:断开 | | | |
| | 4 - | | 操作:接通 | | | 🛃 参数 🔪 |
| | 5 | | 操作:断开 | | | □ 波形 |
| -513 | 6 | | 操作:接通 | | | |
| | 7.00 | 35 | 操作·断开 | 2022-9-3 10:43:31 | | |
| ACTION | | | | Figure 127 Inform | ation Interface Diagram | |
| 9 11 2 1 00 | | | | | | |

8.11.2 Log

Click Storage-Log in the menu bar to enter the log setting interface. The log setting interface is shown in Figure 128, where you can set the sampling rate, number of records and recording method. The parameters are explained in Table 38.



| IDNPOWER | ACTION | | | | | | | |
|----------|---------|-------------------|-----------------|--|----------------------|--|--|--|
| | 三日夏日 | | | | 《 写和評書 | | | |
| | PRE Ba | Source待机正弦波 三相 AC | | | 2222/10/21 143132 | | | |
| | 采样率 SPS | | | □ 信息 □ 日志 | | | | |
| | 记录条数 | 1000 | | … 参数 ▲ 波形 | ~ | | | |
| | 记录方式事件 | | 开始 结束 | È 文件 \$\$ 并联 | | | | |

Figure 128 Interface Diagram of Log Setting

Table 38 Parameter Interpretation of Log Setting Interface

| Parameter term | Unit | Interpretation | Model | Resolution | Initial value | Setting range |
|-------------------|------|---|-------|------------|------------------|------------------|
| Sampling rate | sps | Sampling and recording rate, sps indicates the number of logs recorded per second. | ALL | 1 | | 1,2,5,10 |
| Number of records | 1 | Number of logs that can be logged. | ALL | 1 | 0 | 0~999999 |
| Recording mode | | Logging mode, including event trigger and immediate trigger. Event trigger: After pressing the "Start" button, this product will trigger log record when an event is triggered. For event triggering, trigger conditions shall be set in the event interface, as detailed in Section 8.9. Immediate trigger: After pressing the "Start" button, this product will immediately trigger log record. | ALL | / 音話語 | Event trigger | 1 |
| Start button | 1 | After clicking the Start button, the product automatically logs the event to a USB memory device externally connected to the rear panel. | ALL | 1 | 1 | 1 T |
| End button | 1 | When you click the End button, the product will stop the recording function. | ALL | 1 | 1 | |

Note: 1. The external USB storage device on the rear panel supports the formats FAT32 and exFAT.

2. The log file only supports CSV format, and the contents are separated by ",".

3. File naming rules: file name prefix + file serial number + group serial number, such as "LOG" + "001" + "001".

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4. File splitting rules: the number of logs recorded in the file shall be split according to 5000.

5. The parameters in the log file are explained in Table 39.







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|---|--------|---|
| 1 | ANPOWE | P |
| | AC | |

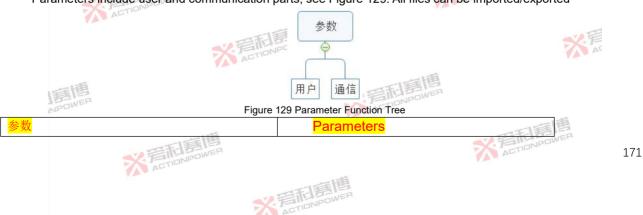
| 三部憲権 | |
|---|----------|
| Table 39 Interpretation of Logging Information Parameters | Table 39 |

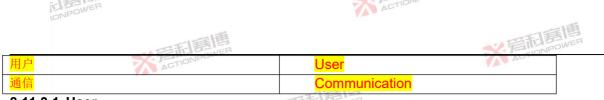
| Parameter term | Interpretation | Parameter term | Interpretation |
|----------------|---------------------------------------|------------------|-----------------------|
| PRE2020S | PRE20XXS series product model | lpk(A) | Peak current |
| E1022G0017 | PRE20XXS series product serial number | CFIONPOWER | Current peak factor |
| Urms(V) | Effective value of voltage | S(kVA) | Apparent power |
| Uthd(V) | Total voltage distortion rate | P(kW) | Active power |
| Uac(V) | AC voltage value | Q(kvar) | Reactive power |
| Udc(V) | DC voltage value | sigmaS(kVA) | Total apparent power |
| Upk(V) | Voltage peak | sigmaP(kW) | Total active power |
| theta(deg) | Voltage angle value | sigmaQ(kvar) | Total reactive power |
| Freq(Hz) | Frequency value | PF | Power factor |
| U12(V) | Line voltage value | Irush(A) | Impulse current value |
| Irms(A) | Effective value of current | PowerOnHours(h) | Operating time |
| lthd | Total current distortion rate | TransferTime(ms) | Conversion time |
| lac(A) | AC current value | Time | Recording time |
| ldc(A) | DC current value | ACTION | |

Note: phi1, phi2 and phi3 respectively represent dp1, dp2 and dp3.

8.11.3 Parameters

電利意 Parameters include user and communication parts, see Figure 129. All files can be imported/exported





8.11.3.1 User

Click Storage-Parameters-User in the menu bar to enter the user interface. The user interface is shown in Figure 130, which contains mode, parameter, limit, protection, event, parallel, advanced, Anyport, source load, data in the system, all of which are saved in the form of files.

| CTIONE | PRE | 用户 | So So | urce正弦 | 波 三相 ACDC | | | | 원 🛱 🛱 🔂 🗗 16:12:28 | /31 8 |
|--------|------|----------------|-------|--------|----------------|-------|-----|----------|-------------------------------|----------|
| L . | Name | | | | Time | | 导入 | 导出 | └──」 信息 | -1.5 |
| | | Parameter1.bas | se . | | 2022-08-31 19: | 26:41 | | | ■ 日志 | 雪乱 |
| | | arameterribat | | | | 20.11 | | | ── 参数 | ACTION |
| | | | | | | | | | ───────────────────────────── | |
| | | | | | | | | | 通信 | |
| | | | | | | | 重 | 2 | ▶ 波形 | |
| | | | | | | | - E | _ | | |

Figure 130 User Interface Diagram

8.11.3.2 Communication



Click Storage-Parameter-Communication in the menu bar to enter the communication interface. The communication interface is shown in Figure 131, which contains the parameters in the communication setting interface in the menu bar and is saved in file form.





8.11.4 Waveform

Click Storage - Waveform in the menu bar to enter the waveform interface. The waveform interface is shown in Figure 132. The user can export/import the waveform with USB memory device or host computer on the front panel.

| | FRE 波形 | 畲 | Source 正弦波 | 三相 ACDC | | | | £〕 骨 骨 合 値 ℓ ^{2022/8/31} 16:13:59 | |
|--------|--------|---|------------|---------|---|----|----|---|----------|
| | 波形名称 | | | | ! | 导入 | 导出 | <u></u> 参数 × | |
| TEL | Shape1 | | | | | | | └─ 波形 | |
| ACTION | Shape2 | | | | | | | 🖹 文件 | |
| AL | Shape3 | | | | | | | 88 并联 | |
| | Shape4 | | | | | | | | 三行星 |
| | Shape5 | | | | | | | | ACTIONPO |
| | Shape6 | | | | | 预算 | 笾 | Anyport 🛛 🖌 🖌 | |

Figure 132 Waveform Interface Diagram

Select the waveform file and click "Preview" in the lower right corner to see the waveform of the current file. If the waveform is imported into Shape1, click Shape1 and click "Preview". The preview interface is shown in Figure 133.

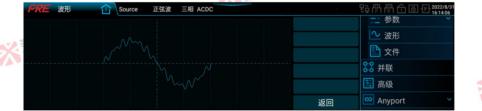


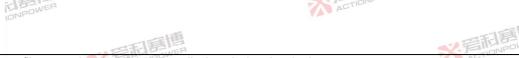
Figure 133 Waveform Preview Interface Diagram

8.11.5 Documents

Click Storage-File in the menu bar to enter the file interface. The file interface contains all internal storage files and files from external USB storage devices. All internally stored files are automatically assigned their own save paths, and ACTIONPOWER







only those files associated with them are displayed when invoked.

The interface of the internal storage file of the product is shown in Figure 134.

| FRE 文件 ① Source待机 亚 | E弦波 三相 ACDC | | 空 戸 ल 合 画 · F <u>2022/9/1</u> 16:11:37 |
|--|--|---------|--|
| Internal storage USB | | | □□ 信息 |
| UserFileRT.list list12345.list | 2022-09-1 1:30:45 | 复制 | □ 日志 □ - 二 参数 |
| ACTIONE listDG123.list | 2022-09-9 17:11:38 2022-09-9 17:27:42 | 粘贴删除 | ▲ 波形 ③ 文件 |
| | 2022-09-9 17:35:23 terface Diagram of Inter | U U | roduct |
| The interface of external USB storage fi | - | re 135. | 17 |
| FRE 文件 | E弦波 三相 ACDC | | ₽ ■ 冊 冊 合 圖 · · · 2022/9/1 16:11:33 |
| Internal storage USB | | | 信息 |
| | | | 目志 |
| | | 复制 | → 参数 |
| System Volume Information | | 粘贴 | ▶ 波形 |
| Android | | 删除 | ■ 文件 |
| 新建文件夹 | 1 - 12 - 14 - 14 - 14 - 14 - 14 - 14 - 1 | 重命名 | |

Figure 135 Interface Diagram of External USB Storage File

File interaction between internal storage and external USB storage devices can be realized through copy/paste in the file interface.

8.12 Parallel connection

When the PRE20XXS series products are connected in parallel, it is necessary to connect the parallel optical fiber cable correctly, see Section 5.10 for details, and then click Parallel in the menu bar to enter the parallel interface, and set ACTIONPOWER the master/slave in the parallel interface in Figure 136.

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| IONPOWER | | | 01 | | |
|----------|--------|----------------|--------|----|--------------------------------------|
| | | 日夏博 | | | w 若和意趣 |
| | FRE HK | Source 待机 正弦波 | 三相 AC | | 日 |
| | 并联 | 王 单机 | 主机 | 从机 | ──────────────────────────────────── |
| | | | | | 高级。自己的自己的 |
| -15 | | | | | OO Anyport Y |
| い言語 | | | | | |

Figure 136 Interface of Parallel Setting

8.12.1 Host settings

During host setting, the product needs to be set as host in the parallel interface, as shown in Figure 137. All functions of the parallel system can be realized on the host machine.



Figure 137 Interface Diagram of Host Setting

8.12.2 Slave setting

During slave setting, the product needs to be set as slave in the parallel interface, as shown in Figure 138. The slave master interface is shown in Figure 139, and the number is automatically generated according to the slave number.

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| IDNPOWER | | | | 1 | ACT | 1014 | | | |
|-------------|---|---------------------------------------|----------------|---|-------------|---------|---|-----------------------|-----------|
| | | 和夏博 | | | | | | 晋利唐 | |
| | PRE 并联 | 行ONPU | | | | | | 2022/9/26 10:58:24 | |
| | 并联 | (150) 単机 | ∎ 主机 | この して し し し し し し し し し し し し し し し し し し | | | #################################################### | 10:58:24 | |
| | 并联旁路 | | | |) X | | ■■ 示玑 | | |
| | 1. A. 1997 | | | | | | | | |
| ACTION | | a stract | 12 | 1 | | | | | |
| AL | The second second second in the second se | | e 138 Interfac | e Diagram | of Slave \$ | Setting | | 0000 (0 (0 (| -17 |
| | PRE | 三 待机 | | | | | 0-0 14 714 | 2022/9/26 10:58:29 | ACTIONPOL |
| | a transformer and the | | u +n | 01 | | | \$\$ 并联 器 系统 | ~ | ACT |
| 2 | | | 从机 | 01 | | | | | |
| | $- e^{-i k \cdot \delta}$ | | | | | | | | |
| 8.13 Senior | SELECTIONPOW | BA BA | Figure 139 M | lain Interfac | e of Slave | e | ACTION | DOWER | |

Click Advanced in the menu bar to enter the advanced setting interface. The advanced setting interface is shown in Figure 140, which provides the user with the ability to set the on/off delay time, operation and start mode, the function options of the shuttle and the calibration parameters of the product. The meaning of each parameter is shown in Table 40. This product provides calibration function, users can calibrate by themselves or contact the after-sales factory for calibration.

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| | | TID | |
|----|----|-----|--|
| 1 | AL | | |
| VA | | | |



| Table 40 Adva | inced Settin | g Parameters | | | AL | |
|----------------------|--------------|--|-------|------------------|------------|---------------|
| Parameter term | Unit | Interpretation and application | Model | Initial value | Resolution | Setting range |
| On-delay | s | When the product is not output, press the output button and start outputting after a set delay time. | ALL | 0 | 0.001 | 0~999.999 |
| Turn-off delay | s | When the product is outputting, press the output button to stop the output after the set delay time. | ALL | 0 | 0.001 | 0~999.999 |
| Operation mode | 山田東 | When Auto is selected, the output will turn on automatically when the product is turned on. | ALL T | Manual | ١ | ١ |
| Startup mode | AFTIONPO | When Auto is selected, the product will turn on automatically when power is on. | ALL | Manual | ١ | |
| Left shuttle | ١ | Change the voltage in source mode and change the current in load mode. | ALL | ١ | | STIDNPO |
| Right-hand shuttle | ١ | The frequency is changed in the source mode, and it is invalid in the load mode. | ALL | ١ | | 1 |
| Calibration | ١ | It includes four parameters: voltage slope, voltage intercept, current slope and current intercept. | ALL | ١ | ١ | ١ |
| Voltage slope | ١ | The user can set the voltage slope within the setting range. | ALL | 0 | 0.000001 | 0.95~1.05 |
| Voltage intercept | ١ | The user can set the voltage intercept within the setting range. | ALL | 0 | 0.01 | -5~5 |
| Current slope | 1.SZ | The user can set the current slope within the setting range. | ALL | 0 ACTIO | 0.000001 | 0.95~1.05 |
| Current intercept | | The user can set the current intercept within the setting range. | ALL | 0 | 0.01 | -3~3 |

The calibration consists of voltage calibration and current calibration. Before calibration, short-circuit the N-wire at the output end of the product, and then perform the calibration as follows.

1. Voltage calibration

The product does not require external loads and all protection parameters are set to their maximum values, see Section 8.8. Connect a voltmeter with precision less than 0.01% to the output measurement interface of the rear panel, adjust it to the DC gear, and set the coupling mode of the product to three-phase DC. Set the voltage values to +600V, ACTIONPOWER

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-600V and 0V respectively and output, record the voltmeter display value and product display value of each phase (i.e. one group), calculate the voltage slope and voltage intercept of each phase with three groups of data of each phase, and fill in the corresponding positions in Figure 140, that is, complete the voltage calibration.

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2. Current calibration

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Set all protection parameters to their maximum values after the product is externally loaded, see Section 8.8 Connect an ammeter with precision of 0.1% below to the output terminal, adjust it to DC gear, and set the coupling mode of the product to three-phase DC. Set the voltage value to +100V, output +30A, -30A and 0A respectively, record the ammeter display value and product display value of each phase (i.e. one group), calculate the current slope and current intercept of each phase with three groups of data of each phase, and fill in the corresponding positions in Figure 140, that is, complete the current calibration.

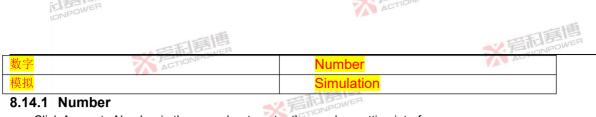
After completing the voltage calibration and current calibration, press and hold the power/reset button to turn off the machine, and the calibration parameters have been saved after turning it on again.

NOTE: If you press Reset Calibration, the above calibration parameters are cleared to zero. To save, press and hold the power/reset button again to shut down.

8.14 Anyport

Anyport consists of both digital and analog parts, see Figure 141. Each enable switch corresponds to one Anyport interface pin, and pay attention to one-to-one correspondence during use.





8.14.1 Number

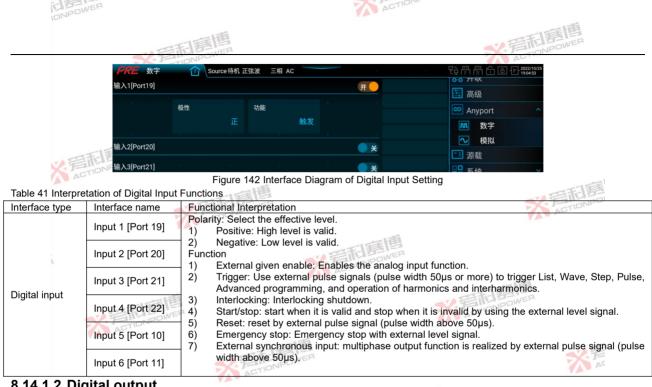
Click Anyport - Number in the menu bar to enter the number setting interface.

-

8.14.1.1 Digital input

The Anyport digital input setting interface is shown in Figure 142, which can realize the external given enable, trigger, interlock, start-stop, reset, emergency stop and external synchronization input functions under positive/negative polarity. The digital input functions are detailed in Table 41.



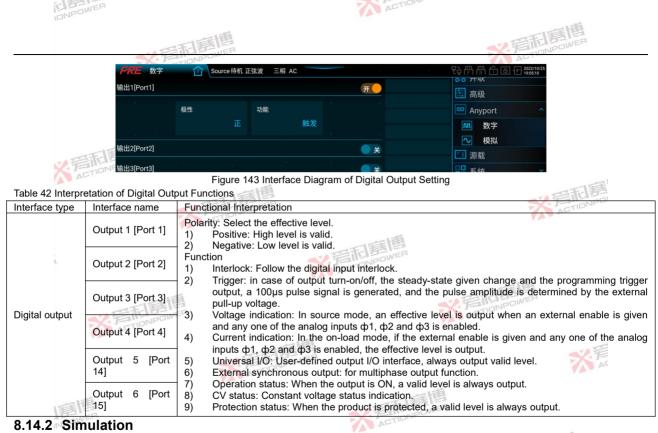


8.14.1.2 Digital output

The Anyport digital output interface is shown in Figure 143, which can realize the functions of interlocking, triggering, voltage indication, current indication, general I/O and external synchronous output under positive/negative polarity, and can also monitor the operating status, CV status and protection status of the product. The digital output functions are ACTIONPOWER detailed in Table 42.

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Click Anyport - Simulation in the menu bar to enter the simulation setting interface.

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8.14.2.1 Analog input

The Anyport analog input interface is shown in Figure 144 and Figure 145. The analog input is valid when enabled is given outside either interface of the digital input. The analog input functions are detailed in Table 43.



| 10-10 | -10 | 24 | | |
|--------|-----|-----|-----|--|
| 12-12- | | | IEP | |
| -01 | | 200 | | |
| | | | | |
| | | | | |

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|---|----|------|
| | | AL |
| | 10 | |
| | | |

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Table 43 Interpretation of Analog Input Functions

| Interface type | Interface name | Functional Interpretation |
|----------------|--------------------|--|
| | Input 1[| Tracking amplitude |
| | Input 2[cp2 Port8] | Tracking effective value |
| Analog input | Input 3[| Real-time tracking |
| | Input 4 [Freq | Tracking frequency: only the source mode is supported. |
| | Port6] | Tracking frequency. Only the source mode is supported. |

(1) Tracking amplitude:

1) When the coupling mode is AC or AC+DC, the following equation can be used:

5V range: Peak value of output sine wave = Vref(dc)/5V(dc)×450V(ac)×1.414

10V range: Peak value of output sine wave = Vref(dc)/10V(dc)×450V(ac)×1.414

Example: If a sine wave with a peak value of 300V is required to be output with a 5V range, the external

given voltage Vref is 2.357V(dc).

If a sine wave with a peak value of 300V is required to be output with a 10V range, the external given voltage Vref is 4.715V(dc).

When the external setting is less than 0, the outputs are all 0.

2) When the coupling mode is DC, the following formula can be used:

5V range: Vout=Vref(dc)/5V(dc)×636V(dc)

10V range: Vout=Vref(dc)/10V(dc)×636V(dc)

Example: When using the 5 V range, if a Vout of 300 V is required, the external given voltage Vref is 2.358 V (dc). If Vout is required to be -300 V, the external given voltage Vref is -2.358 V (dc). When using the 10 V range, if a Vout of 300 V is required, the external given voltage Vref is 4.717 V (dc). If Vout is required to be -300 V, the external given voltage Vref is -4.717 V (dc).

Tracking effective value

 When the coupling mode is AC or AC+DC, the following equation can be used: 5V range: effective value of output sine wave = Vref(dc)/5V(dc)×450V(ac) 10V range: effective value of output sine wave = Vref(dc)/10V(dc)×450V(ac)



Example: When using the 5V range, if it is desired to output a sine wave with an effective value of 300V. the external given voltage Vref is 3.333V(dc).

If a sine wave with an effective value of 300V is required to be output with a 10V range, the external given voltage Vref is 6.667V(dc).

When the external setting is less than 0, the outputs are all 0.

When the coupling mode is DC, the following formula can be used: 2) ACTIONPO 5V range: Vout=Vref(dc)/5V(dc)×636V(dc)

10V range: Vout=Vref(dc)/10V(dc)×636V(dc)

Example: When using the 5 V range, if a Vout of 300 V is required, the external given voltage Vref is 2.358 V (dc). If Vout is required to be -300 V, the external given voltage Vref is -2.358 V (dc). When using the 10 V range, if a Vout of 300 V is required, the external given voltage Vref is 4.717 V (dc). If Vout is required to be -300 V, the external given voltage Vref is -4.717 V (dc).

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Real-time tracking (3)

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It can be calculated using the following equation:

5V range: Vout=Vref(dc)/5V(dc)×636V(dc)

10V range: Vout=Vref(dc)/10V(dc)×636V(dc)

Example: When using the 5 V range, if a Vout of 300 V is required, the external given voltage Vref is 2,358 V (dc). If Vout is required to be -300 V, the external given voltage Vref is -2.358 V (dc).

When using the 10 V range, if a Vout of 300 V is required, the external given voltage Vref is 4.717 V

(dc). If Vout is required to be -300 V, the external given voltage Vref is -4.717 V (dc).

Tracking frequency (4)

When the coupling mode is AC or AC+DC, the following equation can be used: ACTIONPOWER

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5V range: Freq = Vref(dc)/5V(dc)×200Hz

10V range: Freq= Vref(dc)/10V(dc)×200Hz

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Example: When using a 5V range, if the output frequency Freq is 50Hz, the external given voltage Vref is ACTIONPON

1.25V.

When using the 10V range, if the output frequency Freq is 50Hz, the external given voltage Vref is

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2.5V.

8.14.2.2 Analog output

The Anyport analog output interface is shown in Figure 146, and the analog input/output functions are shown in Table 44.

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Figure 146 Interface Diagram of Analog Output Setting

Table 44 Interpretation of Analog Output Functions

| Interface type | Interface name | Functional Interpretation | The second se | STATER . |
|----------------|--------------------|---|--|---|
| 1 | ACTIONPOWER | reactive power of each phase, as | value, current effective value, ac s well as total active power, total a upports 5V range, and the corresp | pparent power and total reactive |
| Analog output | Output 1 [Port 25] | Φ1 Urms: Φ1 effective voltage value Φ1 lrms: φ1 effective current value | Φ2 Urms: φ2 effective voltage value Φ2 Irms: φ2 effective current value | Φ3 Urms: φ3 effective voltage value Φ3 Irms: φ3 effective current value |
| NPOWER | Output 2 [Port 26] | Φ1 Ρ: φ1 active power Φ1 S:φ1 apparent power Φ1 Q:φ1 reactive power ΣΡ: Total active power | Φ2 P: φ2 active power Φ2 S: φ2 apparent power Φ2 Q:φ2 reactive power ΣS: Total apparent power | Φ3 P: φ3 active power Φ3 S:φ3 apparent power Φ3 Q:φ3 reactive power ΣQ: Total reactive power |
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|-------------------|---------------------------------------|----------------------------|--------------------|-------------------|---|
| Table 45 Co | respondence o | f Analog Output Range Para | meters | | ACTION |
| Parameter term | Unit | Coupling mode | Range (V) | Parameter range | Model |
| ф1 Urms | V | AC or AC+DC DC | 0~5-5~5 | 0~450 -636~636 | - ALL |
| | | AC or AC+DC | 0~5 | 0~30 | PRE2006S |
| | | DC | -5~5 | -30~30 | PRE2007S |
| | i i i i i i i i i i i i i i i i i i i | | | | PRE2009S |
| ф1 Irms | AE | AC or AC+DC | 0~5 | 0~35 | PRE2012S |
| X | ACTIONPOW | 20 | | 05.05 | PRE2015S |
| \sim | AL | DC | -5~5 | -35~35 | PRE2020S |
| | | AC or AC+DC | 0~5 | 0~2 | PRE2006S |
| | | DC | -5~5 | -2~2 | - PRE20065 |
| | | AC or AC+DC | 0~5 | 0~2.5 | PDE00070 |
| | | DC | -5~5 | -2.5~2.5 | - PRE2007S |
| | | AC or AC+DC | 0~5 | 0~3 | PRE2009S |
| | kW | DC | -5~5 | w=-3~3 | PRE20095 |
| ф1 Р | KVV | AC or AC+DC | 0~5 ACTIONE | 0~4 | PRE2012S |
| | | DC | -5~5 | -4~4 | - PRE20125 |
| | | AC or AC+DC | 0~5 | | |
| | | DC | -5~5 | -5~5 5 THINPO | PRE2015S |
| | | AC or AC+DC | 0~5 | 0~6.667 | PRE2020S |
| | ACT | DC | -5~5 | -6.667~6.667 | FRE20203 |
| | | | 一個 | 0~2 | PRE2006S |
| | | | DNPOWER DNPOWER | 0~2.5 | PRE2007S |
| ф1 S | kW | AC or DC or AC+DC | 0~5 | 0~3 | PRE2009S |
| φιδ | NVV | | 0~3 | 0~4 | PRE2012S |
| | | | | 0~5 | PRE2015S |
| 1 | 相 | | | 0~6.667 | PRE2020S |
| 12 | OWER | | S.F | 0~2 | PRE2006S |
| ¢1Q | kW | AC or DC or AC+DC | 0~5 | 0~2.5 | PRE2007S |
| φια | | | | 0~3 | PRE2009S |
| | | 一個 | | 0~4 | PRE2012S |
| | | ACTIONPOWER | | A | 18 |
| | | | 128 | | |







| | | 一日日日日日日日日日日日日日日日日日日日日日日日日日日日日日日日日日日日日日 | | | 記 唐 唐 四 NPDWER |
|-------------------|------------|--|----------------|-----------------|----------------------------|
| Parameter term | Unit | Coupling mode | Range (V) | Parameter range | Model |
| | | | 一個 | 0~5 | PRE2015S |
| | | | | 0~6.667 | PRE2020S |
| | | AC or AC+DC | 0~5 | 0~6 | PRE2006S |
| | | DC | -5~5 | -6~6 | PRE20003 |
| | | AC or AC+DC | 0~5 | 0~7.5 | PRE2007S |
| | | DC | -5~5 | -7.5-7.5 DOWER | PRE20075 |
| | ETIS | AC or AC+DC | 0~5 0~9 ACTION | | PRE2009S |
| ΣΡ | KW IONPOWE | DC | -5~5 | -9~9 | FRE20093 |
| ZP | KVV | AC or AC+DC | 0~5 | 0~12 | PRE2012S |
| | | DC | -5~5 | -12~12 | FREZUIZS |
| | | AC or AC+DC | 0~5 | 0~15 | PRE2015S |
| | | DC ACTIDIC | -5~5 | -15~15 | FRE20155 |
| | | AC or AC+DC | 0~5 | | |
| | | DC | -5~5 | -20~20 | PRE2020S |
| | | | T TILBOW | EP0~6 | PRE2006S |
| | | | * ACTIONPOW | 0~7.5 | PRE2007S |
| ΣS | kW | AC or DC or AC+DC | 0~5 | 0~9 | PRE2009S |
| 23 | KVV | AC OF DC OF AC+DC | 0~5 | 0~12 | PRE2012S |
| | 13 | 目前間 | | 0~15 10NPOW | PRE2015S |
| | | NPOWER | | 0~20 | PRE2020S |
| | ACT | | | 0~6 | PRE2006S |
| | | | - IE | 0~7.5 | PRE2007S |
| ΣQ | kW | AC or DC or AC+DC | 0~5wEP | 0~9 | PRE2009S |
| 202 | | | | 0~12 | PRE2012S |
| | | ACT | | 0~15 | PRE2015S |
| | | | | 0~20 | PRE2020S |

Note: 1. When ϕ 1 is single-phase, the corresponding parameters of current and power shall be multiplied by 3.

2. ϕ 2 and ϕ 3 are invalid in single phase, and for other corresponding parameter ranges, please refer to ϕ 1.

3. During parallel operation, the corresponding parameter range of current and power shall be multiplied by the number of parallel operations.

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Click the source load in the menu bar to enter the source load setting interface, as shown in Figure 147. The operating mode of PRE20XXS series products can be switched in the source load setting interface. After switching, the power mode status display will also change.



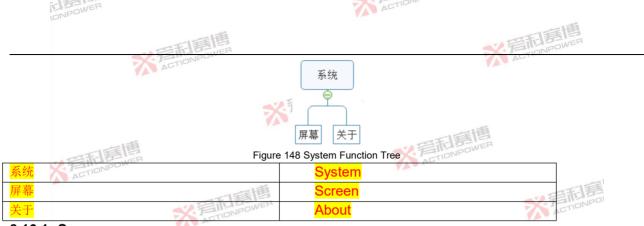
8.16 System

The system consists of the Screen section and the About section, as shown in Figure 148.

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8.16.1 Screen

Click System - Screen in the menu bar to enter the screen interface. Screen brightness, language, screen saver time, alarm tone and date time can be set in the screen interface, as shown in Figure 149.





8.16.2 About

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Click System - About in the menu bar to enter the About interface. Equipment information and software versions of the PRE20XXS series products can be seen in the About interface, see Figure 150. The equipment information includes the product model, hardware version number, serial number of the machine, number of boots and running time ACTIONPO AC (whichever is actual).

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The PRE20XXS series can also be operated in load mode. All functions and operations in load mode can be realized on the display, and each function interface can be swiped left or right or up and down to view relevant contents. This chapter mainly introduces part of the main interface, modes, parameters and limits in load mode, and the rest is 后的是 ACTIONPOWER consistent with the source mode. See Chapter 8.

Source/load switching 9.1

For source/load switching, see Section 8.15. When switching, a prompt box appears, see Figure 151.

| PRE 源载 ① Load 待机 正弦 | 波 三相 AC | 段骨骨合 ⑥ ₽2022/19/14 |
|-----------------------------------|-----------------------------------|--|
| | 提示 | 存储 |
| | 为了确保运行过程中被测设备安 | 28 并联 |
| $\leftarrow \bigcirc \rightarrow$ | 全,请设置 "快速峰值过压阈值" 为被 测设备最大耐受电压! | 高级 自己的 |
| | /则以田政八则又屯压; | Anyport Anyport |
| Source | 设置 忽略 | []] 源载 |
| | | |

Figure 151 Source/load switching prompt interface diagram

The user can set the fast peak overvoltage threshold of the PRE20XXS series products according to the maximum withstand voltage of the device under test. Click "Settings" to enter the "Protection" interface, where the fast peak overvoltage threshold is set. If you click Ignore, the prompt box disappears.

9.2 Main Interface

The load modes of the PRE20XXS series include CC, CP, RLC, and PQ, which can be selected in Section 9.3. When CC mode is selected, the main interface is shown in Figure 152.

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Time = run time. When the load timing in the Parameters screen in 9.4 is enabled, the timing time can be set, in which case Time indicates the run countdown. The output setting area can set the output current lac and the power factor PF. The status display area, menu buttons, output display area and drop-down shortcut area can refer to the main interface of source mode.

When CP mode is selected, the apparent power S and power factor PF can be set in the output setting area in the main interface

When RLC mode is selected, an RLC parameter setting page will be added to the main interface, as shown in Figure 153. Click the value to set the corresponding parameter. The basic parameters of RLC mode are shown in Table ACTIONPOWER

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Table 46 Basic Parameters of RI C Mode

| Parameter term | Unit | Interpretation | Model | Initial value | Resolution | Setting range |
|-------------------|------|---------------------------------|-------|---------------|------------|---------------|
| R | Ω | Load resistance | ALL | 1000 | 0.1 | 0.001~1000 |
| L | mH | Load inductance | ALL | 5000 | 0.1 | 1~5000 |
| R∟ | Ω | Inductance internal resistance | ALL | 0 | 0.001 | 0~1000 |
| С | μF | Load capacitance | ALL | 山山四 | 0.001 | 1~5000 |
| Rc | Ω | Capacitance internal resistance | ALL | 10 DOWER | 0.001 | 0~1000 |

When PQ mode is selected, a page of PQ parameter setting interface will be added to the main interface, as shown in Figure 154. Click the value to set the corresponding parameter. The basic parameters of PQ mode are shown in Table 47.



| Parameter term | | Unit | Interpretation | Model | Initial value | Resolution | Setting range |
|-------------------|--------|------------------|--------------------------|----------|------------------|------------|---------------|
| Р | IR NPO | kW WER | Active power | PRE2006S | 0 | 0.001 | 0~2 |
| | | | | PRE2007S | | | 0~2.5 |
| | | | | PRE2009S | | | 0~3 |
| | | | | PRE2012S | | | 0~4 |
| | | | | PRE2015S | | | 0~5 |
| | | | | PRE2020S | | | 0~6.667 |
| QL | | kVar | Inductive reactive power | PRE2006S | 0 | 0.001 | 0~2 |
| | | | 秋 晋祖唐傳 | | × | ACTIONPOWE | a 196 |



Table 47 Basic Parameters of PQ Mode







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|-------------------|-------|---|----------|-----------|------------|---------------|--|
| Parameter term | Unit | Interpretation | Model | Initial 🚺 | Resolution | Setting range | |
| | | 一個 | PRE2007S | | | 0~2.5 | |
| | | 三天日言 | PRE2009S | | | 0~3 | |
| | | ※ 着 市 あ に 内 P の WER | PRE2012S | | | 0~4 | |
| | | AL. | PRE2015S | | | 0~5 | |
| | | | PRE2020S | 画图 | | 0~6.667 | |
| | . Eti | | PRE2006S | NPOWER | | 0~2 | |
| | 三利县 | ER | PRE2007S | DNPC | | 0~2.5 | |
| | Akvar | | PRE2009S | | 0.004 | 0~3 | |
| Qc | Kvar | Capacitive reactive power | PRE2012S | 0 | 0.001 | 0~4 | |
| | | 目前 | PRE2015S | 1 | | 0~5 | |
| | | TONPOWER | PRE2020S | | | 0~6.667 | |

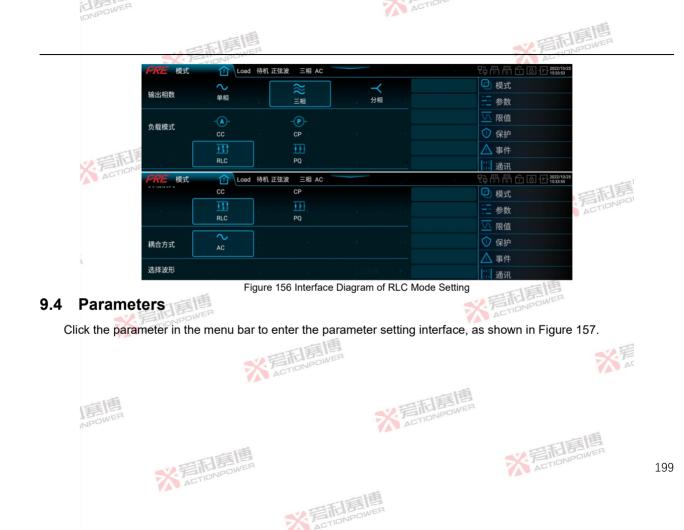
Note: During parallel operation, the above parameter settings shall be multiplied by the number of parallel operations.

9.3 Mode

Click Mode in the menu bar to enter the mode setting interface. The mode setting interface allows you to select the output phase number and load mode of the PRE20XXS series products. See Figure 155 when CC mode is selected. CP mode and CC mode are consistent.





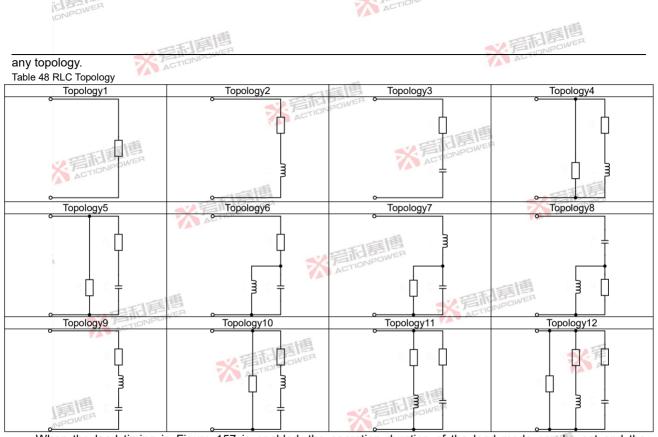


| DNPOWER | ACTION | | | | |
|------------|---------------|-----------------------------------|---------------|---------------|---|
| | | 意情 | | | |
| 7 | FID | JPDMD. | | | |
| | FRE 参数 | | 正弦波 三相 AC | | - 段骨骨合 @ 1732/10/25 |
| | 交流电流 | Φ1[A] 0.00 | Φ2[A] 0.00 | Φ3[A] 0.00 | Q (保工) 参数 参数 |
| | 视在功率 | Φ1[kVA] | Φ2[kVA] | Φ3[kVA] | |
| | 搅住功率 | | | | ◆ 保护 |
| | RLC拓扑选择 | Φ1 | Φ2 | Φ3 | ▲ 事件 |
| 一言恒 | | | | | 11. 通讯 |
| V STABLE | PRE 参数 | 企 Load 待机 | 正弦波 三相 AC | | € <u></u> = = = = = = = = = = = = = = = = = = = |
| ACTIONPOWE | 交流截止电压 | Φ1[V] | Φ2[V] | Φ3[V] | 模式 |
| | 文加截止电压 | | | | |
| | PF | Φ1[kW] | Φ2[kW] | Ф3[kW] | |
| | | | | | |
| | 斜率 | 交流电流[A/ms] | 视在功率[kVA/ms] | | ▲ 事件 |
| | 8- 1 - | 50.00 | 20.000 | | 通讯 通讯 |
| | PRE 参数 | 🕜 Load 待机 | 正弦波 三相 AC | | €〕 FI R C @ I 1534.51 |
| | | * | Ť | ŤĒ. | ④ 模式 |
| | 响应速度 | 慢速 | 中速 | 快速 | 参数 1000000000000000000000000000000000000 |
| | 频率范围 | ^∿ | **** | | ☑ 限值 |
| | | 低 | 高 | | ◆ 保护 |
| * ACTION | 摆率 | 电流[A/us] 关机[A/us] 2.000 1.0000 | ▲ 事件 | | |
| ACTI | | 375 470 (*) | 关机的 | | 通讯 通讯 |
| | FRE 参数 | Load 待机 | | | 문과 (류) (유) (유) (요) (1534-54 |
| | +00 - | 电流[A/us] | 关机[A/us] | | Q 模式 三 参数 |
| | 摆率 | | | | 三 参数 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 |
| | 角度 | 开机[*] | 关机[*] | | ── 限值 |
| | 用度 | | | | |
| B | 暂态角度 | | |) × | ▲ 事件 |
| 770 | 负载定时 | | |) × | |

Figure 157 Interface Diagram of Load Mode Parameter Setting

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There are 12 topologies in RLC topology selection, as shown in Table 48. Click the area below φ1/φ2/φ3 to select



When the load timing in Figure 157 is enabled, the operation duration of the load mode can be set and the ACTIONPOWER

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countdown timer is displayed in the main interface.

Other parameter functions and operations in the parameter setting interface are consistent with the source mode, as detailed in Section 8.3. ACTIONPOWER

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9.5 Limit

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Click the limit value in the menu bar to enter the limit setting interface, as shown in Figure 158. Definitions of limit parameters are shown in Table 49.

| ACTIONS PRE RE | Load 待机 正弦波 🛛 🗃 | 相 AC | - | |
|--------------------|-----------------|---------|--------------|---------|
| | 下限[A] | 上限[A] | ④ 模式 | -15 |
| 交流电流 | | 35.00 | → 参数 → → → → | ACTIONE |
| | 下限[kVA] | 上限[kVA] | ── 限值 | ACTIL |
| 视在功率 | | 6.667 | ◆ 保护 | |
| | | | ▲ 事件 | |
| 1. Sec. 1. Sec. 1. | | | 通讯 | |

Figure 158 Interface Diagram of Load Mode Limit Setting

Table 49 Load Mode Limit Setting Parameters Settina Initial Interpretation and application Model Parameter term Unit Resolution value range The minimum value of the output AC current of each PRE2006S 0.00~30 0 phase, which is valid when the coupling mode is AC. PRE2007S When the output phase is three-phase or split-phase, the PRE2009S actual value is equal to the set value. When the output **PRE2012S** AC current lower phase is single phase, the actual value is 3 times the set А 0.01 **PRE2015S** limit value. When the user needs to avoid damage to the 0 $0.00 \sim 35$ equipment under test due to low output AC current due to **PRE2020S** misoperation, the lower limit of AC current can be set in a safe range here. AC current upper The maximum value of the output AC current of each PRE2006S Α 0.01 30 0.00~30 limit phase, which is valid when the coupling mode is AC. PRE2007S ACTIONPON ACTIONPOWER

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|-------------------------------|------|--|--|---------------------|----------------------------------|--|
| Parameter term | Unit | Interpretation and application | Model | Resolution | Initial value | Setting range |
| | 嘉博 | When the output phase is three-phase or split-phase, the actual value is equal to the set value. When the output phase is single phase, the actual value is 3 times the set value. When the user needs to avoid damage to the equipment under test due to excessive output AC current caused by misoperation, the upper limit of AC current can be set in the safe range here. | PRE2009S PRE2012S PRE2015S PRE2020S | 10 WER | 35 | 0.00~35 |
| Apparent power ower limit | kVA | The minimum apparent power of each phase. When the output phase is three-phase or split-phase, the actual value is equal to the set value. When the output phase is single phase, the actual value is 3 times the set value. When the user needs to avoid damage to the equipment under test due to low source power due to misoperation, the lower limit of apparent power can be set in the safe range here. | PRE2006S PRE2007S PRE2009S PRE2012S PRE2015S PRE2020S | 0.001 | 0 0 0 0 0 0 0 | 0~2 0~2.5 0~3 0~4 0~5 0~6.667 |
| Apparent power upper limit | kVA | The maximum apparent power of each phase. When the output phase is three-phase or split-phase, the actual value is equal to the set value. When the output phase is single phase, the actual value is 3 times the set value. When the user needs to avoid damage to the equipment under test due to excessive apparent power caused by misoperation, the upper limit of apparent power can be set in a safe range. | PRE2006S PRE2007S PRE2009S PRE2012S PRE2015S PRE2020S | 0.001 CTIONPOWER | 2 2.5 3 4 5 6.667 | 0~2 0~2.5 0~3 0~4 0~5 0~6.667 |
| 9.6 Protect | ion | ※ 言記是傳 | 1 | 1 | × | THE AL |

9.6 Protection

Click Protection in the menu bar to enter the protection setting interface, as shown in Figure 159. The protection ※言記意題 ACTIONPOWER parameters are defined in Table 50. NPDWER

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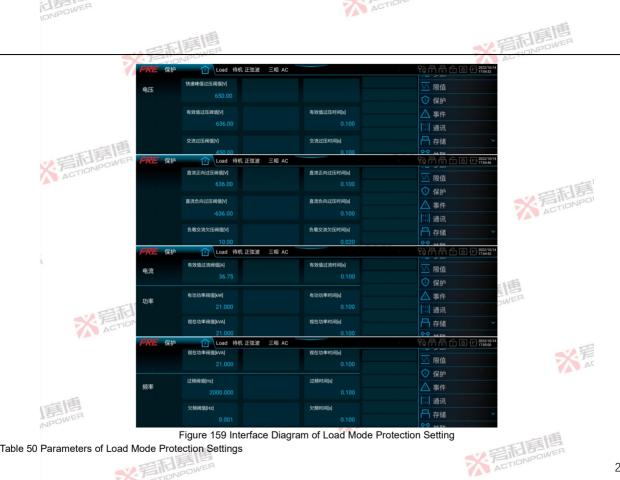


Figure 159 Interface Diagram of Load Mode Protection Setting

Table 50 Parameters of Load Mode Protection Settings ACTION POWER



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| IDNES | | | | | | |
|---|--|---|--|------------|------------------------------|--------------------------------------|
| | | 四和意思 | | ~ 着雨 | 房 MPOWER | |
| Parameter term | Unit | Interpretation and application | Model | Resolution | Initial value | Setting range |
| Fast peak overvoltage threshold | v | Fast peak overvoltage protection critical value, which is valid only in load mode. This parameter can be set when the user needs to protect the maximum instantaneous voltage at the output end. | ALL | 0.01 | 650 | 0~700 |
| Effective value overvoltage threshold | V | Critical value of effective value overvoltage protection. This parameter can be set when the user needs to protect the maximum effective value of voltage at the output terminal. | ALTIONPOW | 0.01 | 636 | 0~636 |
| AC overvoltage threshold | V | Critical value of AC overvoltage protection. This parameter can be set when the user needs to protect the maximum AC voltage at the output terminal. | ALL | 0.01 | 450 | 0~450 |
| DC forward overvoltage threshold | v | DC forward overvoltage protection critical value. This parameter can be set when the user needs to protect the maximum forward DC voltage at the output terminal. | ALL | 0.01 | 636 | 0~636 |
| DC negative overvoltage threshold | v | Critical value of DC negative overvoltage protection. This parameter can be set when the user needs to protect the maximum negative DC voltage at the output terminal. | ALL | 0.01 | -636 | -636~0 |
| Load AC undervoltage threshold | v | Critical value of load AC undervoltage protection, which is valid only in load mode. This parameter can be set when the user needs to protect the minimum AC voltage at the output terminal. | ALL | 0.01 | 10 | 10~450 |
| 7 | ACT | The critical value of overcurrent protection of the effective value of each phase. When the output phase is three-phase | PRE2006S PRE2007S | | 31.5 | 0~31.5 |
| Effective value overcurrent A threshold | or split-phase, it indicates the critical value of the effective value of each phase overcurrent protection; when the output phase is single-phase, the actual value is 3 times of the set value. This parameter can be set when the user needs to protect the maximum current at the output terminal. | PRE2009S PRE2012S PRE2015S PRE2020S | 0.01 | 36.75 | 0~36.75 | |
| Active power threshold | kW | Total active power protection critical value. This parameter can be set when the user needs to protect the maximum active power of the output terminal. | PRE2006S PRE2007S PRE2009S PRE2012S | 0.001 | 6.3 7.875 9.45 12.6 | 0~6.3 0~7.875 0~9.45 0~12.6 |

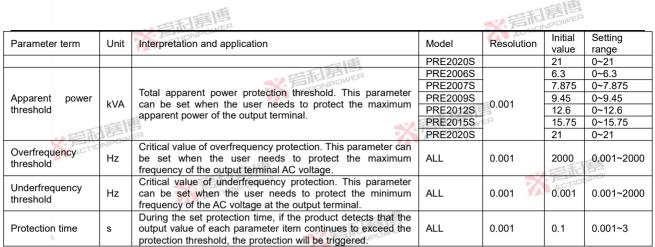
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※着記意傳 ACTIONPOWER



Note: When paralleling, the relevant parameter settings of current and power need to be multiplied by the number of paralleling.

※ 着 た TIONPOWER





※ 着 前 意 個 ACTIONPOWER



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NPOWE





10 Appendix-Examples of built-in harmonics

ACTION

